

# Extended Formulations I (Boot Camp)

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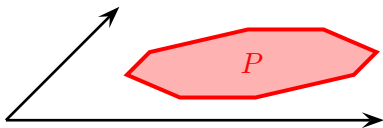
# Organization

1. Thomas Rothvoss (1.x lectures): Introduction to LP  
Extended Formulations
2. Hamza Fawzi (1.x lectures): Introduction to SDP Extended  
Formulations
3. Prasad Raghavendra (1.x lectures): Lower bounds for  
LP/SDP lifts

# Extended formulation

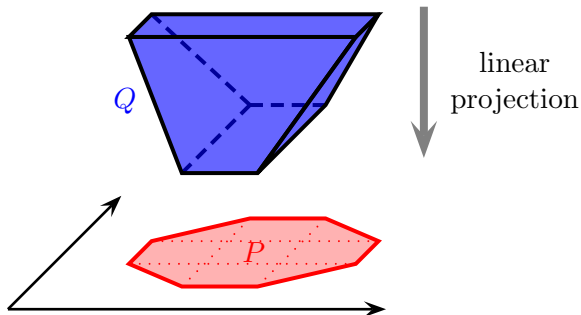
## Extended formulation

- ▶ Given polytope  $P = \{x \in \mathbb{R}^n \mid Ax \leq b\}$



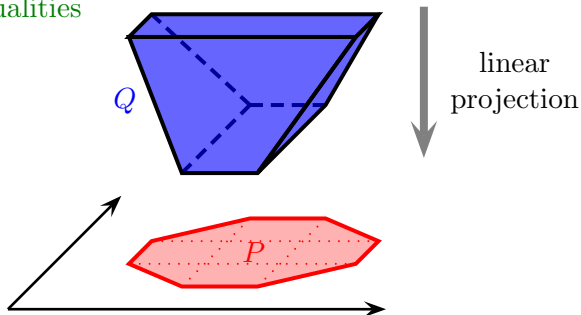
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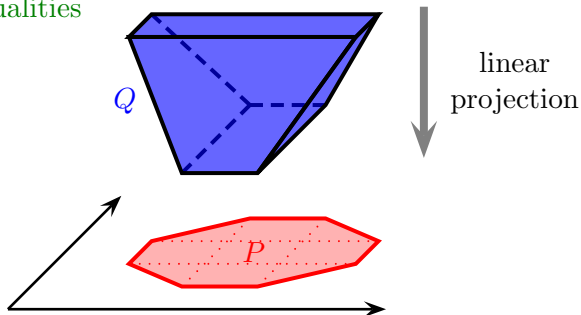
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- ▶ The **extension complexity** of  $P$  is

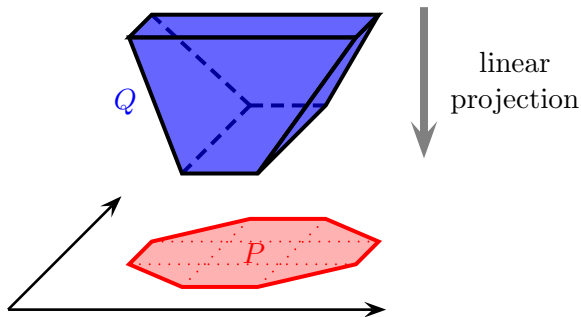
$$\text{xc}(P) := \min \left\{ \begin{array}{l} \# \text{facets of } Q \mid \\ \begin{array}{l} Q \text{ polyhedron} \\ p \text{ linear map} \\ p(Q) = P \end{array} \end{array} \right\}$$

# Motivation



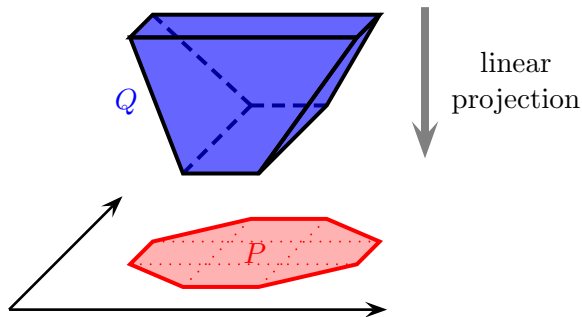
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- ▶  $\text{xc}(\text{conv}(\text{SPANNING TREES})) \leq O(n^3)$   
⇒ optimize over all Spanning trees with LP of size  $O(n^3)$



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- ▶ **In reverse:** If  $\text{xc}(P)$  is **high** for TSP / MaxCut / Correlation / Matchings, then those problems cannot be solved with a single poly-size LP!

# PART I

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## A NON TRIVIAL EXAMPLE - KNAPSACK

# Knapsack

► **Input:**

- $n$  objects with weight  $w_i \in \mathbb{Z}_+$
- profit  $p_i \in \mathbb{Q}_+$
- knapsack size  $B \in \mathbb{Q}_+$

- **Goal:** Find subset of objects, maximizing the profit and not exceeding the weight bound:

$$OPT = \max_{I \subseteq \{1, \dots, n\}} \left\{ \sum_{i \in I} p_i \mid \sum_{i \in I} w_i \leq B \right\}$$

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**Known:**

- ▶ weakly NP-hard
- ▶ Pseudo-polynomial time algorithm
- ▶ FPTAS

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**Known:**

- ▶ weakly NP-hard
- ▶ Pseudo-polynomial time algorithm
- ▶ FPTAS
- ▶  $\text{xc}(\text{conv}\{x \in \{0, 1\}^n \mid \sum_{i=1}^n w_i x_i \leq B\}) \leq O(n \cdot B)$ .

# A dynamic program for KNAPSACK

## Lemma

Knapsack can be solved in time  $O(n \cdot B)$ .

## Algorithm

(1) Compute table entries

$$\begin{aligned} T(i, W) &= \max_{I \subseteq \{1, \dots, i\}} \left\{ \sum_{j \in I} p_j \mid \sum_{j \in I} w_j = W \right\} \\ &= \text{max. profit of weight } W \text{ subsets of first } i \text{ items} \end{aligned}$$

using dynamic programming

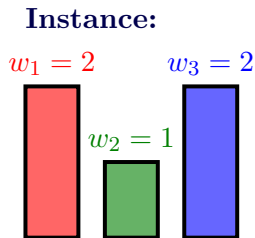
$$T(i, W) = \max \left\{ \underbrace{T(i-1, W)}_{\text{don't take } i}, \underbrace{T(i-1, W - w_i) + p_i}_{\text{take } i} \right\} \quad \forall i \quad \forall W \leq B$$

## Knapsack (3)

$T(*, 3)$	○	○	○	○
$T(*, 2)$	○	○	○	○
$T(*, 1)$	○	○	○	○
$T(*, 0)$	○	○	○	○

$T(0, *)$   $T(1, *)$   $T(2, *)$   $T(3, *)$

- ▶ Create a network with nodes  $(i, W)$  and





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$T(*, 3)$  ○ → ○ → ○ → ○

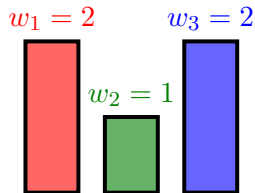
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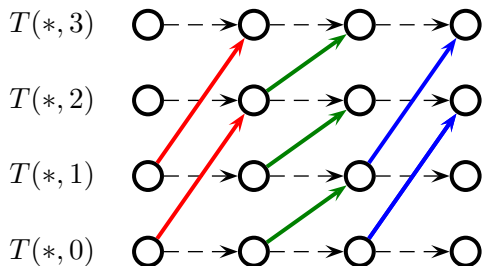
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Instance:



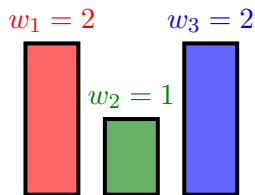
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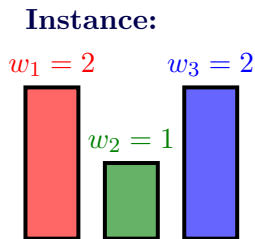
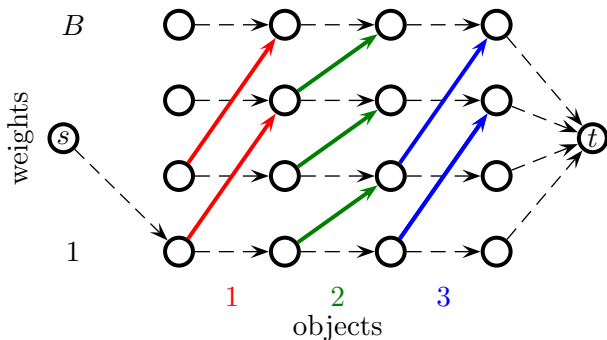
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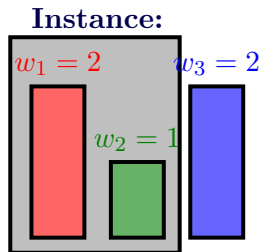
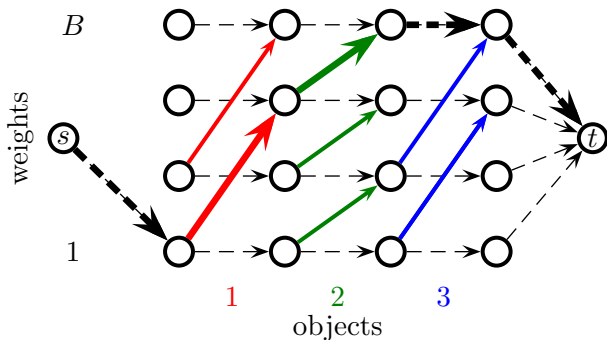
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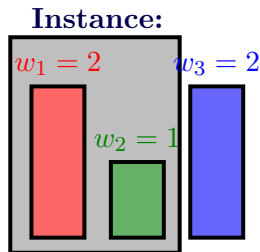
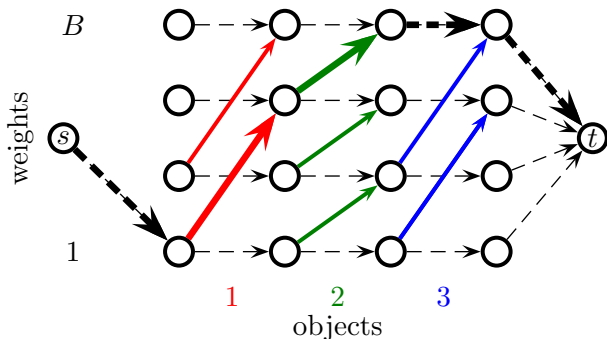


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### Observations:

- ▶  $s$ - $t$  path  $\longleftrightarrow$  Knapsack solution

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### Observations:

- ▶  $s$ - $t$  path  $\longleftrightarrow$  Knapsack solution
- ▶ max cost  $s$ - $t$  path = max profit packing

## Knapsack (4)

- ▶ Let  $G = (V, E)$  be network.
- ▶ Let  $E_i = \{\text{take item } i \text{ edges } \}$

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### Observation

The Knapsack polytope is the projection of  $Q$  with

$$\begin{aligned}x_i &= \sum_{e \in E_i} y(e) \quad \forall i \in [n] \\ y(\delta^+(v)) - y(\delta^-(v)) &= \begin{cases} 1 & v = s \\ -1 & v = t \\ 0 & \text{otherwise} \end{cases} \quad \forall v \in V \\ x, y &\geq \mathbf{0}\end{aligned}$$

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### Corollary

$\text{xc}(\text{Knapsack polytope}) \leq O(n \cdot B)$ .

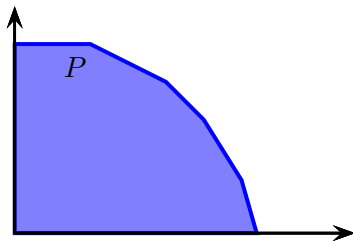


# Knapsack (5)

## Open problem

Consider a Knapsack polytope

$$P = \text{conv} \left\{ x \in \{0, 1\}^n \mid \sum_{i=1}^n w_i x_i \leq B \right\}.$$



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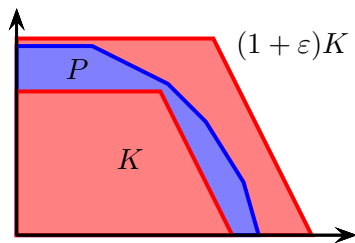
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Is there is always a polytope  $K$  with

- ▶  $K \subseteq P \subseteq (1 + \varepsilon)K$
- ▶  $xc(K) \leq \text{poly}(n, \frac{1}{\varepsilon})$ ?



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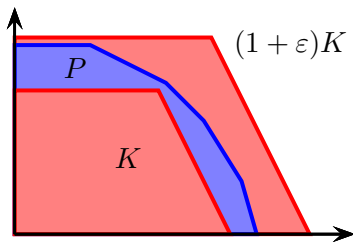
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## Known:

- ▶  $xc(K) \leq n^{O(1/\varepsilon)}$  possible  
(Bienstock)



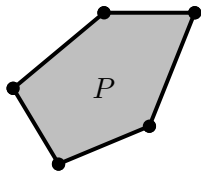
## PART II

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# SLACK-MATRICES, YANNAKAKIS' THEOREM AND COMMUNICATION COMPLEXITY

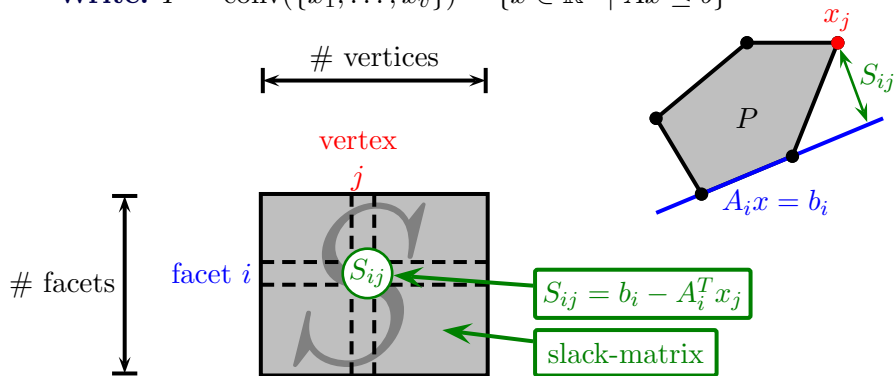
## Slack-matrix

**Write:**  $P = \text{conv}(\{x_1, \dots, x_v\}) = \{x \in \mathbb{R}^n \mid Ax \leq b\}$



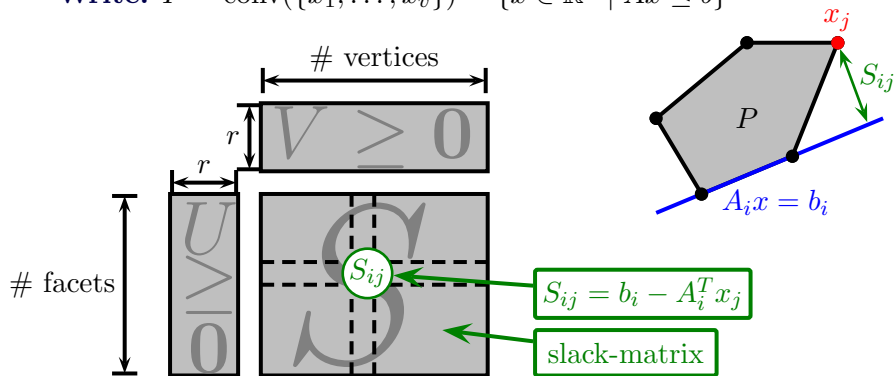
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**Non-negative rank:**

$$\text{rk}_+(S) = \min\{r \mid \exists U \in \mathbb{R}_{\geq 0}^{f \times r}, V \in \mathbb{R}_{\geq 0}^{r \times v} : S = UV\}$$

# Yannakakis' Theorem

Theorem (Yannakakis '88)

If  $S$  is the **slack-matrix** for  $P = \{x \in \mathbb{R}^n \mid Ax \leq b\}$ , then  $\text{xc}(P) = \text{rk}_+(S)$ .



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- ▶  $A_i x > b_i \implies A_i x + \underbrace{U_i y}_{\geq 0} > b_i$ .

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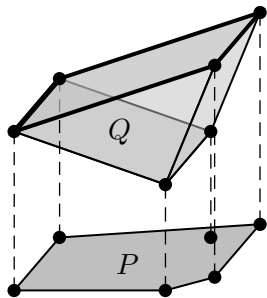
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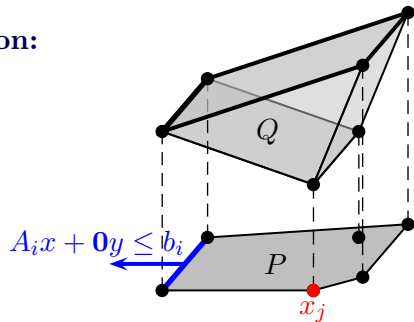
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$$\langle u(i), v(j) \rangle =$$

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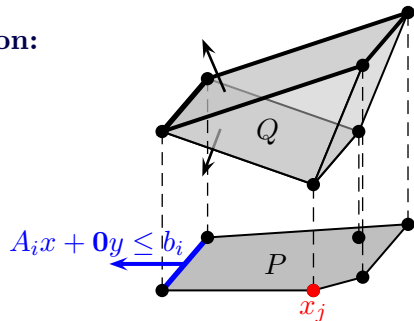
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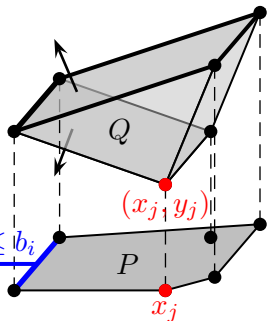
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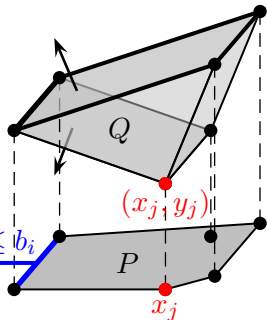
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$$\langle u(i), v(j) \rangle = \underbrace{u(i)^T d}_{=b_i} - \underbrace{u(i)B}_{=A_i} x_j - \underbrace{u(i)C}_{=0} y_j = S_{ij}$$



# Rectangle covering lower bound

Observation

$$\text{rk}_+(S) \geq \text{rectangle-covering-number}(S).$$

## Rectangle covering lower bound

$$\begin{array}{c} V \\ \begin{array}{|c|c|c|c|c|} \hline 0 & 0 & 2 & 1 & 0 \\ \hline 0 & 2 & 2 & 0 & 3 \\ \hline \end{array} \\ \\ \begin{array}{c} U \\ \begin{array}{|c|c|} \hline 3 & 2 \\ \hline 1 & 1 \\ \hline 0 & 2 \\ \hline 0 & 0 \\ \hline 2 & 0 \\ \hline \end{array} \end{array} \begin{array}{|c|c|c|c|c|} \hline 0 & 4 & 10 & 3 & 5 \\ \hline 0 & 2 & 4 & 1 & 3 \\ \hline 0 & 4 & 4 & 0 & 6 \\ \hline 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 4 & 2 & 0 \\ \hline \end{array} S \end{array}$$

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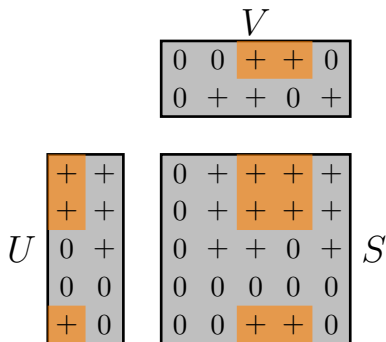
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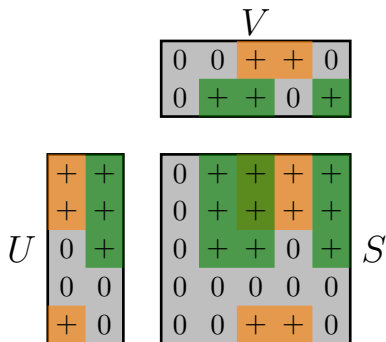
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# Communication complexity

## Setting:

- ▶ Function  $f : X \times Y \rightarrow \mathbb{R}$

**Alice**

**Bob**

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- ▶ Alice receives  $x \in X$ , Bob receives  $y \in X$

**Alice**  
 $x \in X$

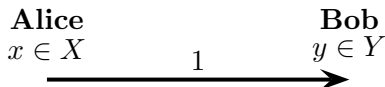
**Bob**  
 $y \in Y$



# Communication complexity

## Setting:

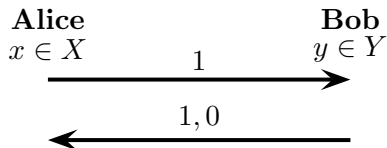
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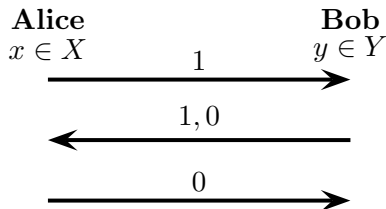
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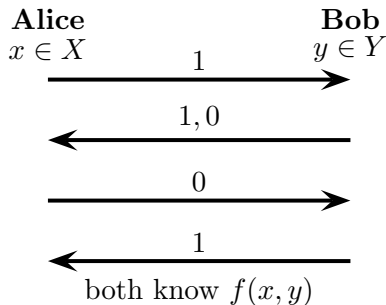
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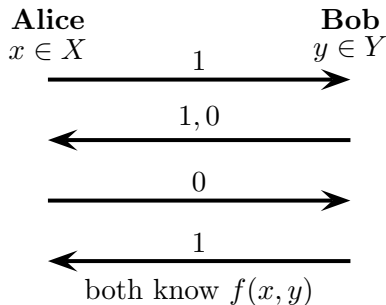
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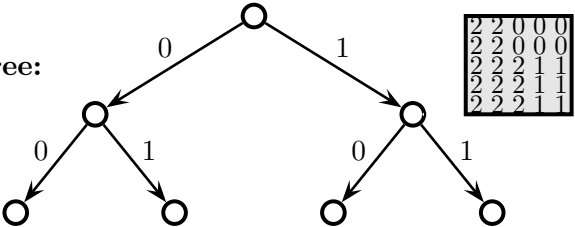
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$$CC(f) = \min_{\text{protocoll}} \max_{x \in X, y \in Y} \{\text{bits to compute } f(x, y)\}$$

# Communication complexity (3)

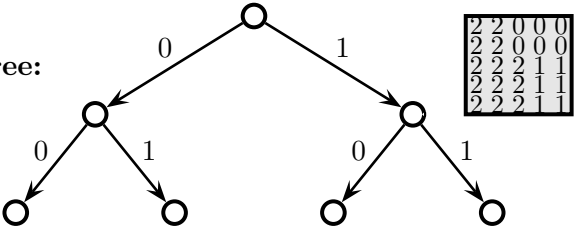
decision tree:



2	2	0	0	0
2	2	0	0	0
2	2	2	1	1
2	2	2	1	1
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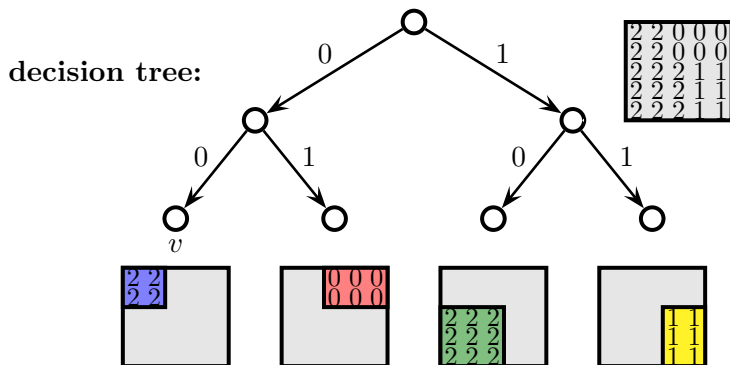
2	2			
2	2			

		0	0	0
		0	0	0

2	2	2		
2	2	2		
2	2	2		

			1	1
			1	1
			1	1

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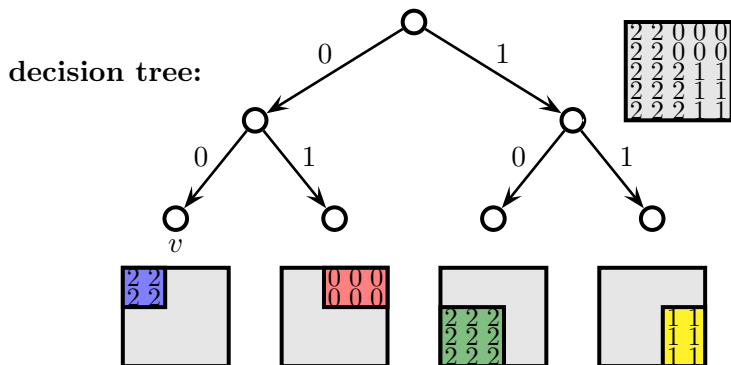


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- ▶ For a leaf  $v$  of tree,  $R_v := \{(x, y) : \text{protocoll ends in } v\}$  is a **monochromatic rectangle**



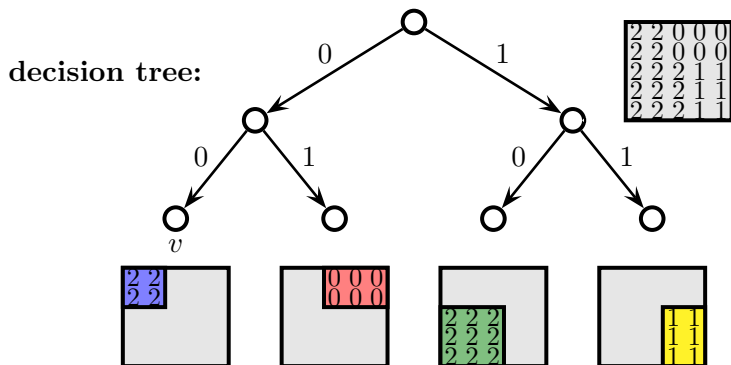
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 $\Rightarrow S$  can be partitioned into  $2^k$  monochromatic rectangles  
 $\Rightarrow S$  is sum of  $2^k$  rank-1 matrix

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- ▶  $\text{xc}(\text{polytope}) \leq 2^{CC(\text{slack matrix})}$

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We have seen:

$$2^{CC_{\text{nondet}}(\text{supp. of slack matrix})} \leq \text{xc}(\text{polytope}) \leq 2^{CC(\text{slack matrix})}$$

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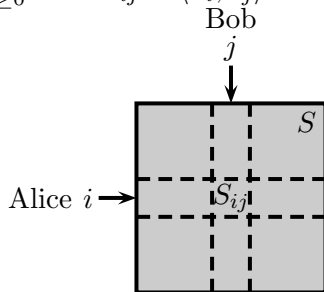
Let  $CC_{\text{RAND}}(S)$  be min. # bits. Then

$$\text{xc}(\text{polytope}) = 2^{CC_{\text{RAND}}(\text{slack matrix } S)}$$



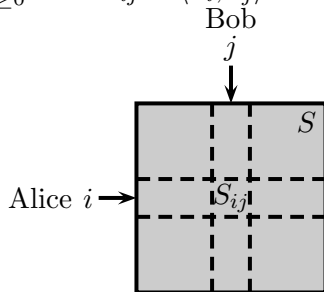
## An exact model (2)

Let  $u_i, v_j \in \mathbb{R}_{\geq 0}^r$  with  $S_{ij} = \langle u_i, v_j \rangle$ .



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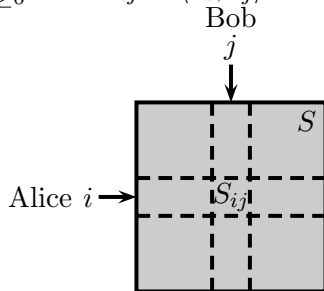
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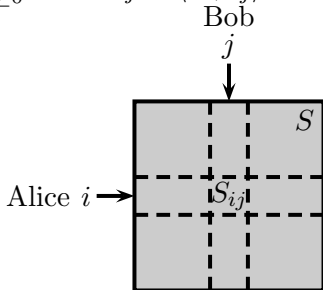


**Protocoll with  $\log_2(r)$  bits:**

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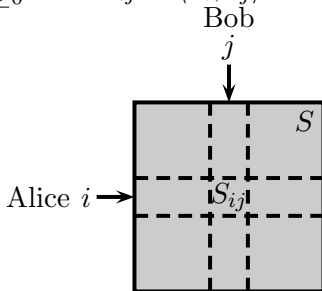


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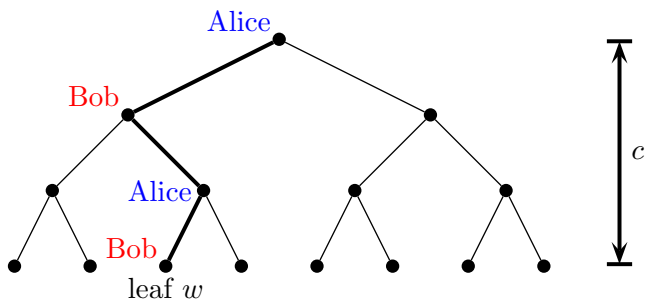
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Then

$$\mathbb{E}[\text{protocoll}(i, j)] = \sum_{k=1}^r v_i(k) \cdot u_j(k) = \langle u_i, v_j \rangle$$

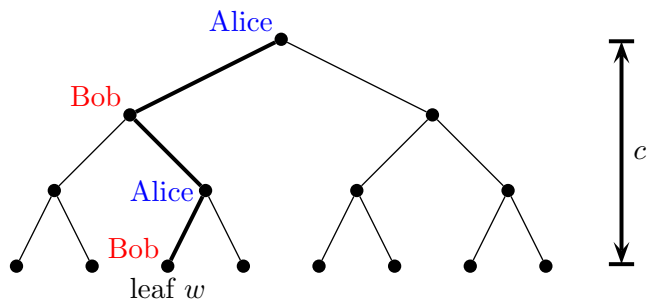
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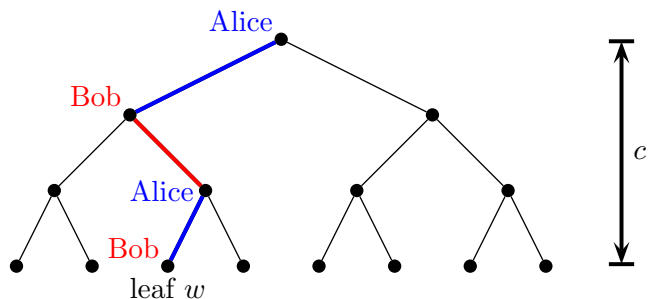
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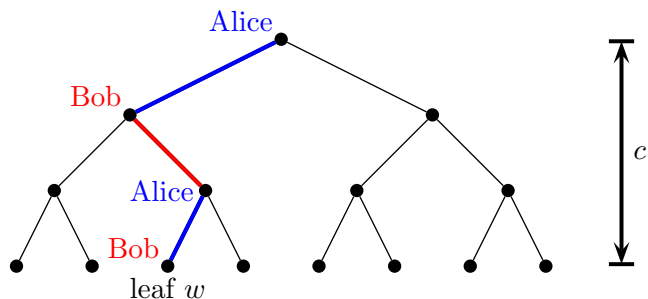
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$\Rightarrow 2^c$ -size non-neg factorization

## PART III

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# THE LOWER BOUND ON THE CORRELATION POLYTOPE

# Correlation polytope (1)

The **correlation polytope** is

$$COR = \text{conv}\{bb^T : b \in \{0, 1\}^n\}$$

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**Observation:** The polytope is **NP**-hard.

For graph  $G = ([n], E)$  with adjacency matrix  $A_G$

$$\text{maxcut}(G) = \max_{x \in \{0,1\}^n} (D_G - A_G) \bullet xx^T = \sum_{(i,j) \in E} \underbrace{(x_i + x_j - 2x_i x_j)}_{=1 \text{ if } x_i \neq x_j, 0 \text{ o.w.}}$$

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Theorem (Fiorini, Massar, Pokutta, Tiwary, de Wolf '12)

$$\text{xc}(COR) \geq 2^{\Omega(n)}.$$

- Here: Simplified proof by Kaibel and Weltge

## Correlation polytope (2)

### Lemma

For all  $a \in \{0, 1\}^n$ ,  $(2\text{diag}(a) - aa^T) \bullet Y \leq 1$  is a feasible inequality for  $Y \in \text{COR}$ .

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- Suffices to check slack for  $Y = bb^T$ .

The diagram illustrates the decomposition of the inequality matrix  $(2\text{diag}(a) - aa^T)$  into two terms:

$$1 - 2 \cdot \underbrace{\begin{bmatrix} 1 & & & & \\ & 1 & & & \\ & & 1 & & \\ & & & 1 & \\ & & & & 0 & \\ & & & & & 0 & \\ & & & & & & 0 \end{bmatrix}}_{\text{supp}(a)} \bullet \underbrace{\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix}}_{\text{supp}(b)} + \underbrace{\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix}}_{\text{supp}(a)} \bullet \underbrace{\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix}}_{\text{supp}(b)}$$

The first term represents  $(\text{diag}(a) - aa^T) \bullet Y$  and the second term represents  $(2\text{diag}(a) - aa^T) \bullet Y$ .



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### Lemma

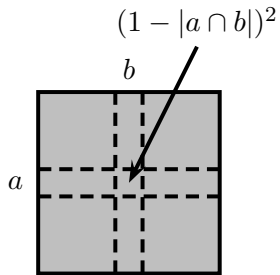
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$$\begin{array}{ccccccc}
 1 - 2 \cdot & \begin{array}{|c|} \hline 1 & & & & & & \\ & 1 & & & & & \\ & & 1 & & & & \\ & & & 1 & & & \\ & & & & 0 & & \\ & & & & & 0 & \\ & & & & & & 0 \\ \hline \end{array} & \bullet & \begin{array}{|c|} \hline & & & & & & \\ & 1 & 1 & 1 & 1 & & \\ & 1 & 1 & 1 & 1 & & \\ & 1 & 1 & 1 & 1 & & \\ & 1 & 1 & 1 & 1 & & \\ \hline \end{array} & + & \begin{array}{|c|} \hline 1 & 1 & 1 & 1 & & & \\ 1 & 1 & 1 & 1 & & & \\ 1 & 1 & 1 & 1 & & & \\ 1 & 1 & 1 & 1 & & & \\ \hline \end{array} & \bullet & \begin{array}{|c|} \hline & & & & & & \\ & 1 & 1 & 1 & 1 & & \\ & 1 & 1 & 1 & 1 & & \\ & 1 & 1 & 1 & 1 & & \\ & 1 & 1 & 1 & 1 & & \\ \hline \end{array} \\
 \text{supp}(a) & & \text{supp}(b) & & \text{supp}(a) & & \text{supp}(b)
 \end{array}$$

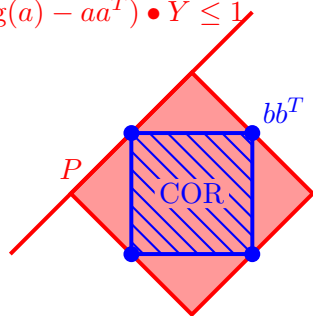
$$= 1 - 2|a \cap b| + |a \cap b|^2 = (1 - |a \cap b|)^2 \geq 0$$

# Correlation polytope (3)

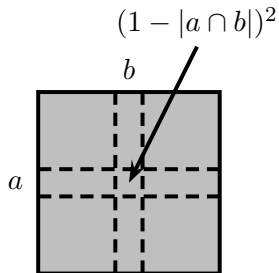


slack matrix  $S$

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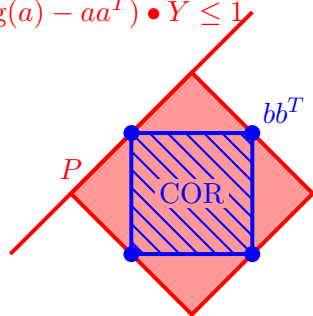


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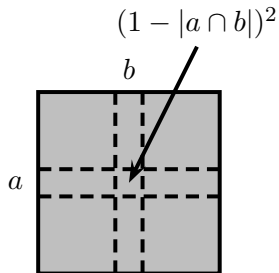
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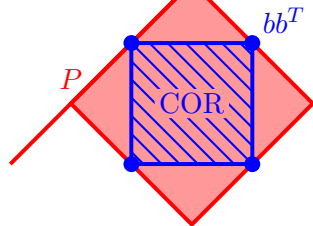
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## Correlation polytope (3)



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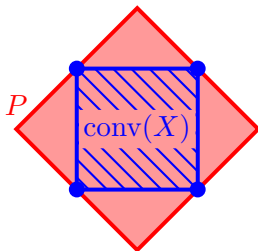
$$S_{ab} = \begin{cases} 1 & |a \cap b| = 0 \\ 0 & |a \cap b| = 1 \end{cases}$$

# Incomplete slack matrices

## Lemma

For a polytope  $P = \{x \mid Ax \leq b\}$  and  $X = \{x_1, \dots, x_v\} \subseteq P$  define a matrix  $S$  with  $S_{i,j} := b_i - A_i x_j$ . Then

$$\text{rk}_{\geq 0}(S) = \min\{\text{xc}(Q) : X \subseteq Q \subseteq P\}$$

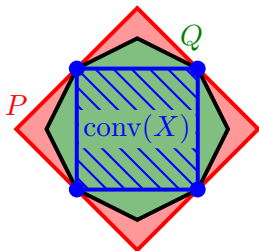


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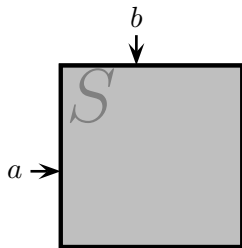
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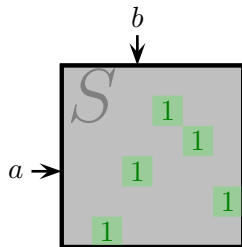


## Correlation polytope (3)



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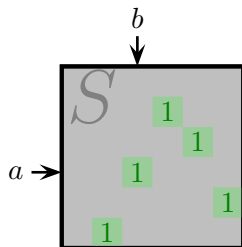


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- ▶ Define **disjoint pairs**  $\mathcal{P}_0 := \{(a, b) : |a \cap b| = 0\}$



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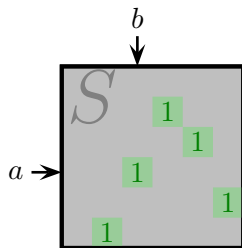
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Claim

$$|\mathcal{P}_0| = 3^n.$$

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$$S_{ab} = \begin{cases} 1 & |a \cap b| = 0 \\ 0 & |a \cap b| = 1 \end{cases}$$

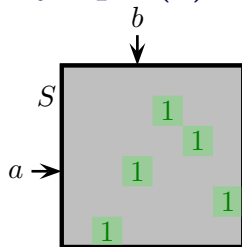
- ▶ Define **disjoint pairs**  $\mathcal{P}_0 := \{(a, b) : |a \cap b| = 0\}$

### Claim

$$|\mathcal{P}_0| = 3^n.$$

- ▶ For disjoint pair  $(a, b)$ , for coordinate  $i$  there are 3 options
  - ▶  $a_i = 0, b_i = 0$
  - ▶  $a_i = 1, b_i = 0$
  - ▶  $a_i = 0, b_i = 1$

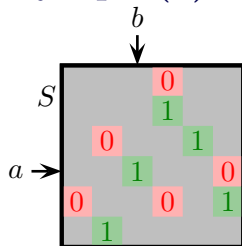
## Correlation polytope (4)



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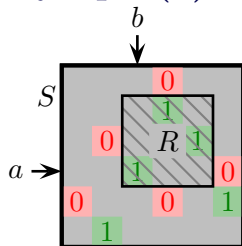
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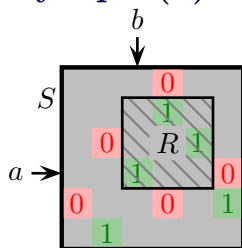
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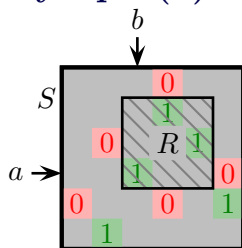
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### Lemma

Any rectangle  $R$  without forbidden pairs has  $|R \cap \mathcal{P}_0| \leq 2^n$ .

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### Lemma

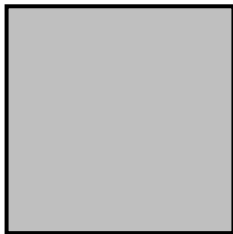
Any rectangle  $R$  without forbidden pairs has  $|R \cap \mathcal{P}_0| \leq 2^n$ .

- ▶ By rectangle covering lower bound

$$\text{xc(COR)} \geq \frac{|\mathcal{P}_0|}{2^n} = \left(\frac{3}{2}\right)^n$$

## Correlation polytope (5)

$R$





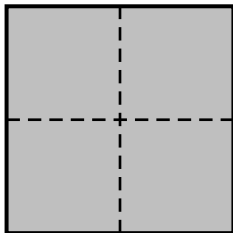
# Correlation polytope (5)

$b : 1 \notin b$     $b : 1 \in b$

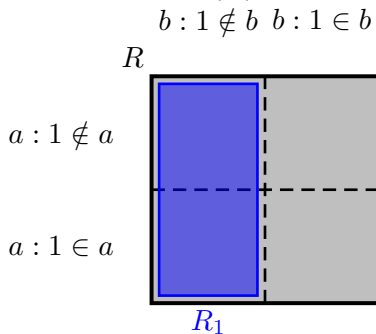
$R$

$a : 1 \notin a$

$a : 1 \in a$

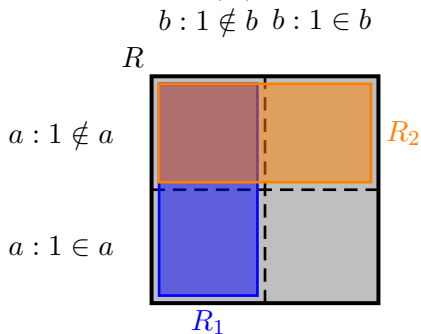


## Correlation polytope (5)



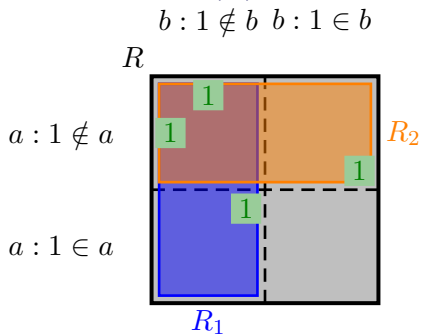
- Define rectangles  $R_1 = \{(a, b) \in R : 1 \notin b\}$

## Correlation polytope (5)



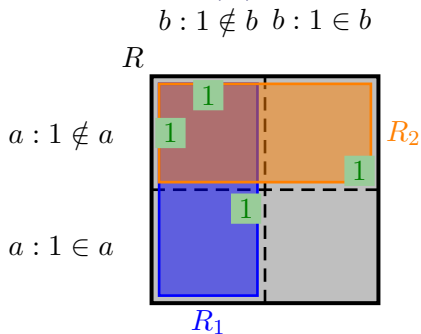
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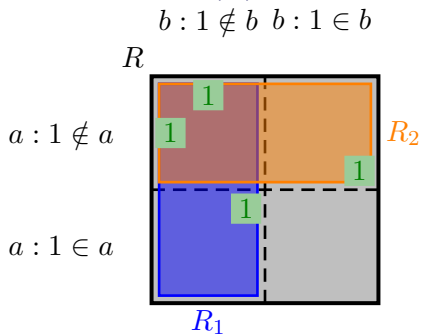
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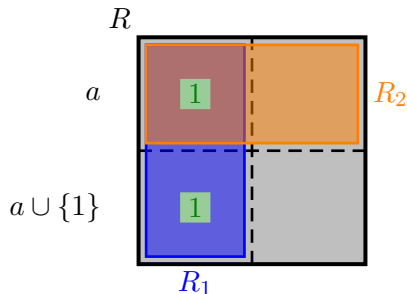
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  - ▶ Delete symbol 1 from all tuples and apply induction
- $$|\mathcal{P}_0 \cap R| \leq |\mathcal{P}_0(n-1) \cap R_1| + |\mathcal{P}_0(n-1) \cap R_2| \leq 2 \cdot 2^{n-1} = 2^n$$

## Correlation polytope (5)



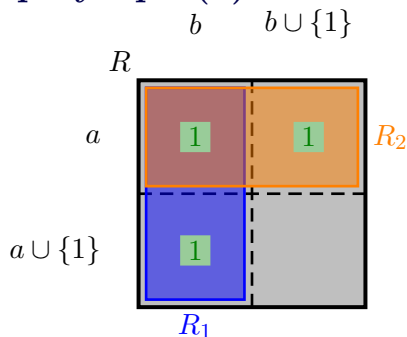
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- ▶ Potential problem: Diff. tuples collapse to the same one

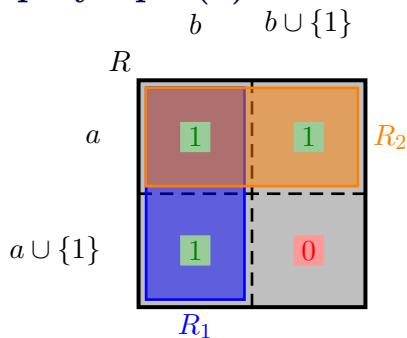
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The end

Thanks for your attention