Sampling for Subset Selection and Applications

Amit Deshpande Microsoft Research India

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Sample? why? when?

- Subsampling data when it is formidably large
- Feature selection, dimension reduction
- Randomized algorithms, hedging your bets against the adversary

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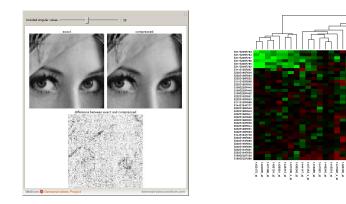
Outline

- Low-rank matrix approximation and SVD
- Row/column sampling techniques
- Determinantal Point Processes, rounding Lasserre solutions etc.

- DPPs for Machine Learning by Kulesza-Taskar (2012), http://arxiv.org/abs/1207.6083
- Guruswami-Sinop rounding of Lasserre SDPs (2011), http://www.math.ias.edu/~asinop/pubs/qip-gs11.pdf

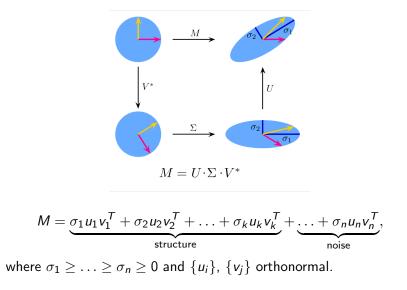
Data = structure + noise

In matrix data, structure is often captured by an underlying low-rank matrix, and can be recovered by SVD.



http://demonstrations.wolfram.com/ImageCompressionViaTheSingularValueDecomposition/ http://upload.wikimedia.org/wikipedia/commons/4/48/Heatmap.png

Singular vectors and SVD



http://commons.wikimedia.org/wiki/File:Singular-Value-Decomposition.svg

Low-rank matrix approximation

Given $A \in \mathbb{R}^{n \times d}$, find $B \in \mathbb{R}^{n \times d}$ of rank at most k that minimizes

$$\|A - B\|_F^2 = \sum_{ij} (A_{ij} - B_{ij})^2.$$

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- ▶ Best rank-*k* approximation $A_k = \sum_{i=1}^k \sigma_i u_i v_i^T$. Geometrically, project each rows of *A* onto span (v_1, \ldots, v_k) .
- SVD computation takes time O (min{nd², n²d}). Not fast enough for large data streams. Another drawback is that linear combinations of features/objects are not always meaningful. We rather want a subset of features/objects.

Dimension reduction

▶ Random projection aka Johnson-Lindenstrauss: $R \in \mathbb{R}^{d \times t}$, where $t = O\left(\frac{\log n}{\epsilon^2}\right)$ with i.i.d. $\sqrt{\frac{t}{d}} N(0,1)$ entries, followed by SVD of $AR \in \mathbb{R}^{n \times t}$ gives

$$\|A - (AR)_k\|_F^2 \le \|A - A_k\|_F^2 + \epsilon \|A\|_F^2$$
, w.h.p.

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Squared-length sampling by Frieze-Kannan-Vempala: Pick O(^k/_ϵ) rows of A with Pr(i) ∝ ||a_i||², project all rows onto their span to get Ã, and then compute SVD of Ã, which gives

$$\left\|A - \tilde{A}_k\right\|_F^2 \le \|A - A_k\|_F^2 + \epsilon \|A\|_F^2, \quad \text{w.h.p.}$$

w.h.p. here means extra log $\left(\frac{1}{\delta}\right)$ factor for success probability $1 - \delta$.

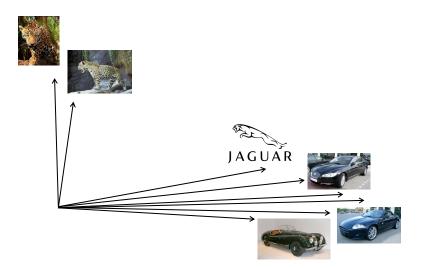
Adaptive sampling and volume sampling

We can pick $O\left(\frac{k}{\epsilon}\right)$ rows of A, in time $\tilde{O}\left(nd\frac{k}{\epsilon}\right)$, such that projecting onto their span followed by SVD gives

$$\left\|A - \tilde{A}_k\right\|_F^2 \le (1 + \epsilon) \left\|A - A_k\right\|_F^2$$
, w.h.p.

- D-Rademacher-Vempala-Wang and D-Vempala (2006), D-Rademacher (2010), Guruswami-Sinop (2012)
- Drineas-Mahoney-Muthukrishnan (2006), Boutsidis-Drineas-Magdon Ismail (2011), using leverage scores and Batson-Spielman-Srivastava sparsification technique
- Sarlos (2007), Dasgupta-Kumar-Sarlos (2010), Clarkson-Woodruff (2012), no row/column subset selection but much faster algorithms using sparse subspace embeddings

Adaptive sampling



Volume sampling

Probability distribution over all k-subsets of [n], where

probability of picking $S \propto \text{vol} (P_S)^2$,

where P_S is a parallelepiped formed by the rows $\{a_i : i \in S\}$.

Volume sampling

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- k = 1 gives squared-length sampling
- ► Can we sample from this distribution efficiently? Yes, in $O(knd^2)$ time. In fact, $(1 + \epsilon)$ -approximate sampling in $\tilde{O}\left(nd\frac{k^2}{\epsilon^2}\right)$ time, using generalization of JL lemma to volumes by Magen-Zouzias (2008).

Why can we do volume sampling efficiently?

Interesting identity using coeffs. of characteristic polynomial

$$\sum_{|S|=k} \operatorname{vol} (P_S)^2 = \sum_{i_1 < \ldots < i_k} \sigma_{i_1}^2 \sigma_{i_2}^2 \cdots \sigma_{i_k}^2 = \left| c_{n-k} (AA^T) \right|.$$

Easy cases
$$\sum_{i} \|a_i\|^2 = \sum_{i} \sigma_i^2$$
 and vol $(P_{[n]})^2 = \sigma_1^2 \cdots \sigma_n^2$.

Nice expression for marginals

$$egin{aligned} & \operatorname{Pr}\left(i\in\mathcal{S}
ight) \propto \sum_{egin{smallmatrix} |S|=k ext{ and } i\in\mathcal{S} \ & \in S \ & = \|a_i\|^2 \sum_{|T|=k-1} \operatorname{vol}\left(P_T'
ight)^2, \end{aligned}$$

where parallelepiped P'_{T} is formed by projections of a_j , for $j \in T$, orthogonal to a_i .

Deterministic row/column subset selection

- Volume sampling can be derandomized using the method of conditional expectations.
- Adaptive sampling part only uses pairwise independence, so can also be derandomized.
- Combining these almost matches the *deterministic* row/column subset selection of Boutsidis-Drineas-Magdon Ismail (2011) that used Batson-Spielman-Srivastava sparsification technique instead.
- Provides efficient rank-revealing RRQR decomposition improving upon Gu-Eisenstat (1996).

From volume sampling to DPPs

- Volume sampling is a special case of *Determinantal Point Processes* arising in quantum physics and random matrix theory. DPPs capture many interesting distributions including random spanning trees, non-intersecting random walks, eigenvalues of random matrices etc.
- ▶ Distribution over all subsets of [n] such that for a random subset R, $\Pr(S \subseteq R) = \det(M_{S,S})$, where $0 \preccurlyeq M \preccurlyeq I$.

Ben Hough-Krishnapur-Peres-Virág (2006) http://front.math.ucdavis.edu/math.PR/0503110

ML and big data applications of subset selection

- Determinantal point processes for machine learning, Kulesza-Taskar, Foundations and Trends in ML, NOW Publishers, December 2012. http://arxiv.org/pdf/1207.6083v4.pdf
- Sampling methods for the Nyström method, Kumar-Mohri-Talwalkar, JMLR'12.
 adaptive sampling to speed up kernel algorithms for image segmentation, manifold learning
- Spectral methods in machine learning and new strategies for very large datasets, Belabbas-Wolfe, PNAS'09. heuristic Metropolis algorithm for volume sampling

 CUR matrix decompositions for improved data analysis, Drineas-Mahoney, PNAS'09.
 row/column sampling on gene expression data

k-means++ clustering

- k-means clustering: Given points a₁, a₂,..., a_n ∈ ℝ^d, find k centers c₁,..., c_k ∈ ℝ^d that minimize sum of squared distances of all points to their nearest centers, respectively.
- Lloyd's iterative method starts with k initial centers, computes the corresponding clusters, then reassigns c_i's as their means, and iterates. Converges only to a local minimum and does not have good theoretical guarantees.
- k-means++ by Arthur-Vassilvitskii (2007) is initialization via adaptive sampling, and gives O (log k) approximation in expectation.
- Aggarwal-D-Kannan (2009) k-means++ actually gives O(1) approximation using 2k centers, w.h.p.

Guruswami-Sinop rounding of Lasserre SDPs

Lasserre SDP for sparsest cut problem produces vectors $x_S(f)$ for *small* subsets S of vertices and $f \in \{0,1\}^{|S|}$, and adds constraints to the usual SDP.

$$\begin{array}{ll} \text{minimize} & \sum_{ij \in E} \left\| x_{\{i\}}(1) - x_{\{j\}}(1) \right\|_{2}^{2}, \\ \text{subject to} & \sum_{i < j} \left\| x_{\{i\}}(1) - x_{\{j\}}(1) \right\|_{2}^{2} = 1, \\ & \| x_{\emptyset} \|_{2}^{2} > 0, \quad \text{and} \\ & x_{S}(f) \text{ satisfy Lasserre conditions for } |S| \leq r. \end{array}$$

Can we round $x_{\{i\}}(1)$'s using the extra information about $x_S(f)$'s?

Guruswami-Sinop rounding of Lasserre SDPs

► To round sparsest cut SDP, suffices to give a good ℓ₂²-to-ℓ₁ embedding of x_{i}(1)'s.

• Guruswami-Sinop give such embedding as $y_i = (\langle x_S(f), x_{\{i\}}(1) \rangle)_{f \in \{0,1\}^{|S|}}$, and show that

$$\left\|x_{\{i\}}(1) - x_{\{j\}(1)}\right\|_{2}^{2} \ge \left\|y_{i} - y_{j}\right\|_{1} \ge \left\|\mathsf{\Pi}_{\mathcal{S}}\left(x_{\{i\}}(1) - x_{\{j\}}(1)\right)\right\|_{2}^{2},$$

where Π_S is orthogonal projection onto the span of $\{x_{\{i\}}(1) : i \in S\}$.

And use row/column subset selection to pick S and obtain good approximation guarantees. For details, see http://arxiv.org/abs/1104.4746 and http://arxiv.org/abs/1112.4109.

Summary

- Adaptive/volume sampling as generalizations of squared-length sampling
- Determinantal Point Processes (DPPs)
- Applications to clustering, machine learning, optimization

Thank you. Any questions?