## Sampling for Subset Selection and Applications

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## Sample? why? when?

- $\triangleright$  Subsampling data when it is formidably large
- $\blacktriangleright$  Feature selection, dimension reduction
- $\blacktriangleright$  Randomized algorithms, hedging your bets against the adversary

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### **Outline**

- $\blacktriangleright$  Low-rank matrix approximation and SVD
- $\triangleright$  Row/column sampling techniques
- $\triangleright$  Determinantal Point Processes, rounding Lasserre solutions etc.

- 1. DPPs for Machine Learning by Kulesza-Taskar (2012), <http://arxiv.org/abs/1207.6083>
- 2. Guruswami-Sinop rounding of Lasserre SDPs (2011), <http://www.math.ias.edu/~asinop/pubs/qip-gs11.pdf>

#### $Data = structure + noise$

In matrix data, structure is often captured by an underlying low-rank matrix, and can be recovered by SVD.





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<http://demonstrations.wolfram.com/ImageCompressionViaTheSingularValueDecomposition/> <http://upload.wikimedia.org/wikipedia/commons/4/48/Heatmap.png>

#### Singular vectors and SVD



<http://commons.wikimedia.org/wiki/File:Singular-Value-Decomposition.svg>

#### Low-rank matrix approximation

Given  $A \in \mathbb{R}^{n \times d}$ , find  $B \in \mathbb{R}^{n \times d}$  of rank at most k that minimizes

$$
||A - B||_F^2 = \sum_{ij} (A_{ij} - B_{ij})^2.
$$

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- Best rank-*k* approximation  $A_k = \sum_{i=1}^k \sigma_i u_i v_i^T$ . Geometrically, project each rows of A onto span  $(v_1, \ldots, v_k)$ .
- SVD computation takes time  $O(min\{nd^2, n^2d\})$ . Not fast enough for large data streams. Another drawback is that linear combinations of features/objects are not always meaningful. We rather want a subset of features/objects.

#### Dimension reduction

► Random projection aka Johnson-Lindenstrauss:  $R \in \mathbb{R}^{d \times t}$ , where  $t = O\left(\frac{\log n}{\epsilon^2}\right)$  $\frac{\log n}{\epsilon^2}\Big)$  with i.i.d.  $\sqrt{\frac{t}{d}}$   $\mathcal{N}(0,1)$  entries, followed by SVD of  $AR \in \mathbb{R}^{n \times t}$  gives

$$
||A - (AR)_k||_F^2 \le ||A - A_k||_F^2 + \epsilon ||A||_F^2, \qquad \text{w.h.p.}
$$

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$$

▶ Squared-length sampling by Frieze-Kannan-Vempala: Pick  $O\left(\frac{k}{\epsilon}\right)$  $\frac{k}{\epsilon}$ ) rows of A with Pr $(i) \propto \|a_i\|^2$ , project all rows onto their span to get  $\tilde{A}$ , and then compute SVD of  $\tilde{A}$ , which gives

$$
\left\|A-\tilde{A}_k\right\|_F^2\leq \|A-A_k\|_F^2+\epsilon\, \|A\|_F^2\,,\qquad \text{w.h.p.}
$$

w.h.p. here means extra log  $\left(\frac{1}{\delta}\right)$  factor for success probability  $1-\delta.$ 

#### Adaptive sampling and volume sampling

We can pick  $O\left(\frac{k}{\epsilon}\right)$  $\frac{k}{\epsilon}$ ) rows of A, in time  $\tilde{O}\left(nd\frac{k}{\epsilon}\right)$ , such that projecting onto their span followed by SVD gives

$$
\left\|A-\tilde{A}_k\right\|_F^2\leq (1+\epsilon)\left\|A-A_k\right\|_F^2, \qquad \text{w.h.p.}
$$

- $\triangleright$  D-Rademacher-Vempala-Wang and D-Vempala (2006), D-Rademacher (2010), Guruswami-Sinop (2012)
- ▶ Drineas-Mahoney-Muthukrishnan (2006), Boutsidis-Drineas-Magdon Ismail (2011), using leverage scores and Batson-Spielman-Srivastava sparsification technique
- ▶ Sarlos (2007), Dasgupta-Kumar-Sarlos (2010), Clarkson-Woodruff (2012), no row/column subset selection but much faster algorithms using sparse subspace embeddings

# Adaptive sampling



## Volume sampling

Probability distribution over all  $k$ -subsets of  $[n]$ , where

probability of picking  $S \propto$  vol  $\left( P_S \right)^2,$ 

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where  $P_{\mathcal{S}}$  is a parallelepiped formed by the rows  $\{a_i\ :\ i\in \mathcal{S}\}.$ 

## Volume sampling

Probability distribution over all *k*-subsets of  $[n]$ , where probability of picking  $S \propto$  vol  $\left( P_S \right)^2,$ 

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- $\blacktriangleright$   $k = 1$  gives squared-length sampling
- $\triangleright$  Can we sample from this distribution efficiently? Yes, in  $O(knd^2)$  time. In fact,  $(1 + \epsilon)$ -approximate sampling in  $\tilde{O} \left( n d \frac{k^2}{\epsilon^2} \right)$  $\frac{k^2}{\epsilon^2}\Big)$  time, using generalization of JL lemma to volumes by Magen-Zouzias (2008).

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#### Why can we do volume sampling efficiently?

Interesting identity using coeffs. of characteristic polynomial

$$
\sum_{|S|=k} \text{vol}(P_S)^2 = \sum_{i_1 < \ldots < i_k} \sigma_{i_1}^2 \sigma_{i_2}^2 \cdots \sigma_{i_k}^2 = \left| c_{n-k} (AA^T) \right|.
$$

Easy cases 
$$
\sum_i ||a_i||^2 = \sum_i \sigma_i^2
$$
 and vol  $(P_{[n]})^2 = \sigma_1^2 \cdots \sigma_n^2$ .

 $\triangleright$  Nice expression for marginals

$$
Pr(i \in S) \propto \sum_{|S|=k \text{ and } i \in S} vol(P_S)^2
$$
  
=  $||a_i||^2 \sum_{|T|=k-1} vol(P'_T)^2$ ,

where parallelepiped  $P_T'$  is formed by projections of  $a_j$ , for  $j \in \mathcal{T}$ , orthogonal to  $a_i$ .

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## Deterministic row/column subset selection

- $\triangleright$  Volume sampling can be derandomized using the method of conditional expectations.
- $\triangleright$  Adaptive sampling part only uses pairwise independence, so can also be derandomized.
- $\triangleright$  Combining these almost matches the *deterministic* row/column subset selection of Boutsidis-Drineas-Magdon Ismail (2011) that used Batson-Spielman-Srivastava sparsification technique instead.
- $\triangleright$  Provides efficient rank-revealing RRQR decomposition improving upon Gu-Eisenstat (1996).

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## From volume sampling to DPPs

- $\triangleright$  Volume sampling is a special case of Determinantal Point Processes arising in quantum physics and random matrix theory. DPPs capture many interesting distributions including random spanning trees, non-intersecting random walks, eigenvalues of random matrices etc.
- $\triangleright$  Distribution over all subsets of  $[n]$  such that for a random subset R, Pr  $(S \subseteq R) = \det(M_{S,S})$ , where  $0 \preccurlyeq M \preccurlyeq I$ .

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 $\triangleright$  Ben Hough-Krishnapur-Peres-Virág (2006) <http://front.math.ucdavis.edu/math.PR/0503110>

## ML and big data applications of subset selection

- $\triangleright$  Determinantal point processes for machine learning, Kulesza-Taskar, Foundations and Trends in ML, NOW Publishers, December 2012. <http://arxiv.org/pdf/1207.6083v4.pdf>
- $\triangleright$  Sampling methods for the Nyström method, Kumar-Mohri-Talwalkar, JMLR'12. adaptive sampling to speed up kernel algorithms for image segmentation, manifold learning
- $\triangleright$  Spectral methods in machine learning and new strategies for very large datasets, Belabbas-Wolfe, PNAS'09. heuristic Metropolis algorithm for volume sampling

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 $\triangleright$  CUR matrix decompositions for improved data analysis, Drineas-Mahoney, PNAS'09. row/column sampling on gene expression data

#### $k$ -means $++$  clustering

- ► *k*-means clustering: Given points  $a_1, a_2, \ldots, a_n \in \mathbb{R}^d$ , find k centers  $c_1,\ldots,c_k\in\mathbb{R}^d$  that minimize sum of squared distances of all points to their nearest centers, respectively.
- I Lloyd's iterative method starts with  $k$  initial centers, computes the corresponding clusters, then reassigns  $c_i$ 's as their means, and iterates. Converges only to a local minimum and does not have good theoretical guarantees.
- $\triangleright$  k-means + + by Arthur-Vassilvitskii (2007) is initialization via adaptive sampling, and gives  $O(\log k)$  approximation in expectation.
- Aggarwal-D-Kannan (2009) k-means $++$  actually gives  $O(1)$ approximation using 2k centers, w.h.p.

## Guruswami-Sinop rounding of Lasserre SDPs

Lasserre SDP for sparsest cut problem produces vectors  $x_S(f)$  for *small* subsets  $S$  of vertices and  $f \in \{0,1\}^{|S|}$ , and adds constraints to the usual SDP.

minimize 
$$
\sum_{ij \in E} ||x_{\{i\}}(1) - x_{\{j\}}(1)||_2^2,
$$
  
subject to 
$$
\sum_{i < j} ||x_{\{i\}}(1) - x_{\{j\}}(1)||_2^2 = 1,
$$

$$
||x_0||_2^2 > 0, \text{ and}
$$

$$
x_S(f) \text{ satisfy Lasserre conditions for } |S| \le r.
$$

Can we round  $x_{\{i\}}(1)$ 's using the extra information about  $x_{\mathcal{S}}(f)$ 's?

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## Guruswami-Sinop rounding of Lasserre SDPs

- $\blacktriangleright$  To round sparsest cut SDP, suffices to give a good  $\ell_2^2$ -to- $\ell_1$ embedding of  $x_{\{i\}}(1)$ 's.
- $\triangleright$  Guruswami-Sinop give such embedding as  $\mathsf{y}_{i}=\bigl(\bigl\langle \mathsf{x}_{\mathsf{S}}(f), \mathsf{x}_{\{i\}}(1)\bigr\rangle\bigr)_{f\in\{0,1\}^{|\mathsf{S}|}},$  and show that

$$
\left\|x_{\{i\}}(1)-x_{\{j\}(1)}\right\|_{2}^{2} \geq \left\|y_{i}-y_{j}\right\|_{1} \geq \left\|\Pi_{S}\left(x_{\{i\}}(1)-x_{\{j\}}(1)\right)\right\|_{2}^{2},
$$

where  $\Pi_{\mathcal{S}}$  is orthogonal projection onto the span of  $\{x_{\{i\}}(1) : i \in S\}.$ 

And use row/column subset selection to pick  $S$  and obtain good approximation guarantees. For details, see <http://arxiv.org/abs/1104.4746> and <http://arxiv.org/abs/1112.4109>.

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# Summary

- $\triangleright$  Adaptive/volume sampling as generalizations of squared-length sampling
- **Determinantal Point Processes (DPPs)**
- $\triangleright$  Applications to clustering, machine learning, optimization

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## Thank you. Any questions?

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