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Active learning for multidimensional experimental spaces of biological responses **Robert F. Murphy Ray & Stephanie Lane Professor of Computational Biology, Biological Sciences, Biomedical Engineering** and Machine Learning Head, Computational Biology Department, **School of Computer Science**

Big problems, Little Data: Drug Development

- Diseases can be extremely heterogeneous and based on many factors (e.g., diabetes)
- Drug effects can be very different depending on the patient and disease
- Ideally, need to know how all drugs will affect all diseases in all patients
- Too many combinations to measure everything

Further...

- Leading cause of drug failures in early development is not lack of effectiveness but safety concerns (and in late development, discovery of undesirable side effects)
- Drug development is not just about finding compounds that hit a desired target-also about finding compounds that miss all other targets

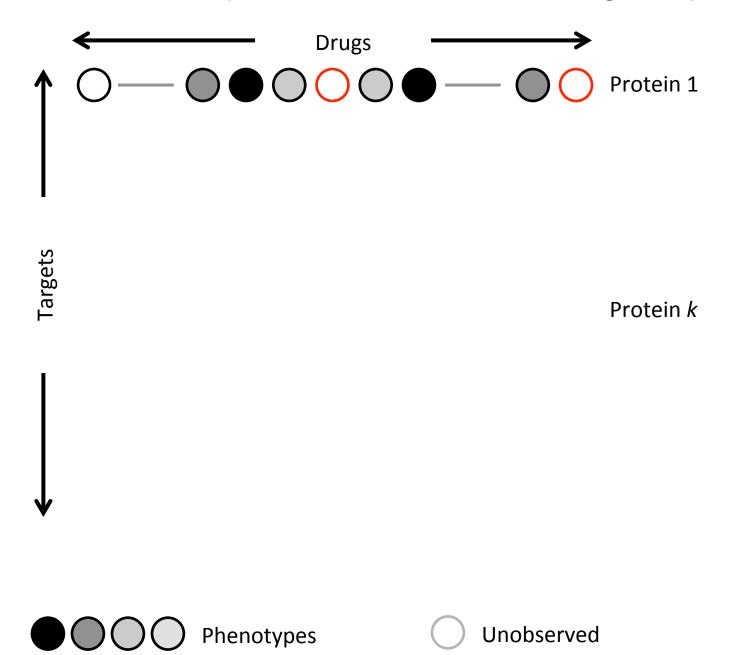
Big problems, Little Data: Basic Biological Research

- Cells/Tissues/Organisms are complex systems without rules/laws
- Every process/cell type/organelle/protein may be affected by drugs, gene variation, environment
- Need to learn all of these changes
- Millions of potential perturbations/gene variations, tens of thousands of proteins, hundreds of cell types

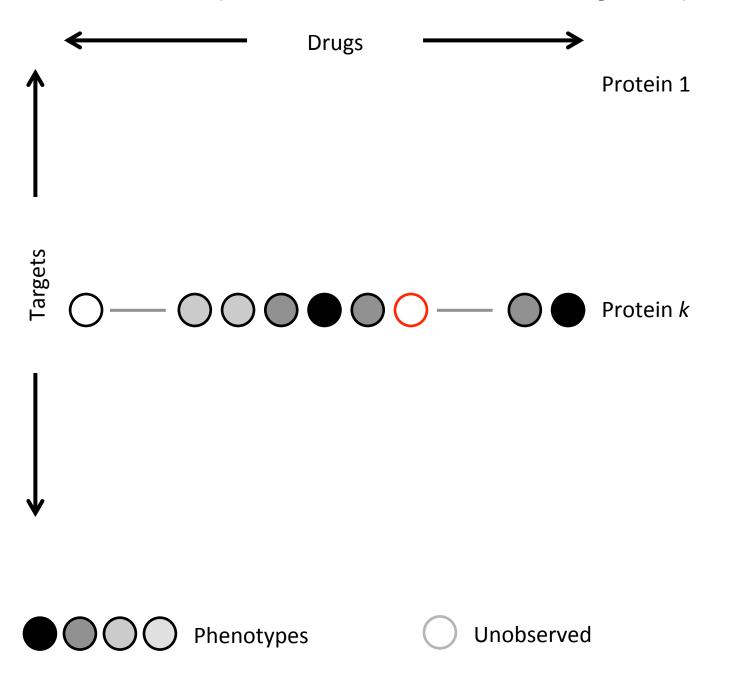
Predictive modeling

- Need to learn a complete matrix/tensor to show whether a particular drug affects a particular target in a particular genotype
- Same for which genes affect which metabolic processes, etc.
- Try to learn the matrix without doing all experiments
- Measure some and build a predictive model for the rest
- But which measurements should be done?

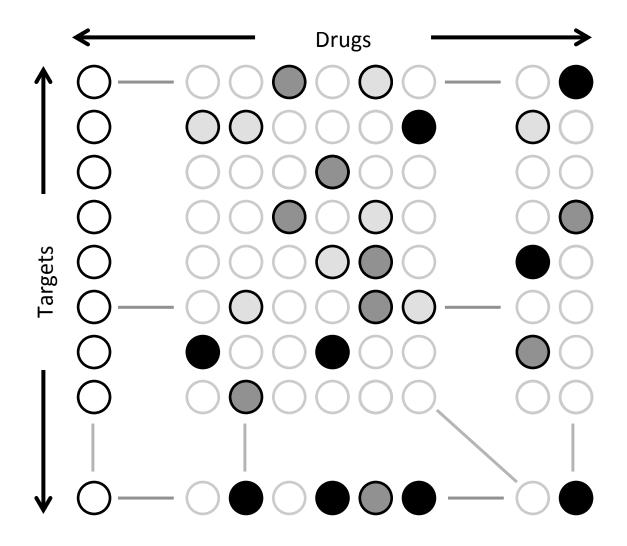
Current practice: consider each target separately



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Can set up a Sparse, Matrix Factorization/Completion Problem



Dempster et al (1977) Hill et al. (1995); Lee & Seung (1999); Buchanan & Fitzgibbon (2005); Salakhutdinov & Mnih (2008); Mitra (2010); Gönen (2012); ...

Three considerations

- How much/what data is missing?
 - Little: matrix completion (passive learning)
 - None for some, all for others: matrix factorization
 - Most/all: <u>not addressed</u> (need active learning)
- Any basis for *ab initio* predictions?
 - Yes, features for drugs/targets
 - e.g., chemical fingerprints
 - <u>No</u>
- What are we predicting?
 - Real values or binary values (all prior work)
 - <u>Classes</u>

Retrospective Studies

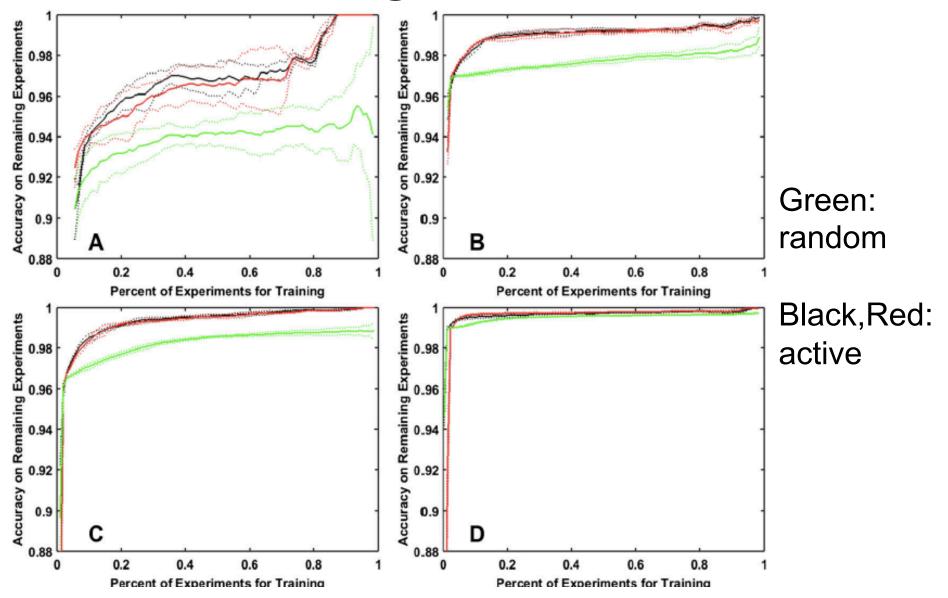
- Widely used for demonstrating "real worldapplicability" of methods
- Always concern about generalizability of results due to possibility of making model choices using testing data
- In drug effects space, mostly done with small datasets (50-500 drugs, 20-700 targets) for which complete data was available

Use Curated Drug Interaction Datasets

DATA	ND	NT	INTERACTIONS
NR	54	26	90
GPCR	223	95	635
ION CHANNEL	210	204	1476
ENZYME	445	665	2926

Previous studies (e.g., Gönen 2012) tested ability to predict for 20% of drugs using training with 80% Temerinac-Ott, Naik & Murphy, BMC Bioinformatics 2015

Active learning of factored models



Active Learning of 80% compared to random or clustering by features

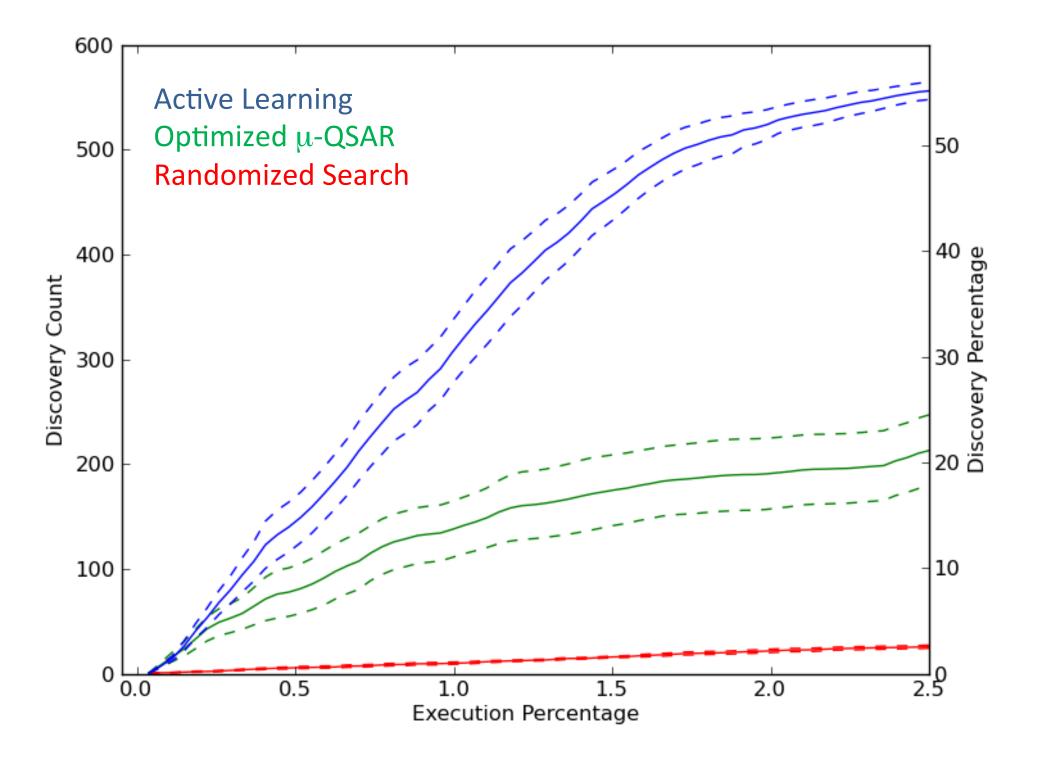
	Goenen results	Pre-clustering	AL	
Dataset	AUC (%)	AUC (%)	AUC (%)	
NR	82.4	84.0	93.6	
GPCR	85.7	86.4	90.6	
IC	79.9	85.3	86.8	
Enz	83.2	85.8	90.3	

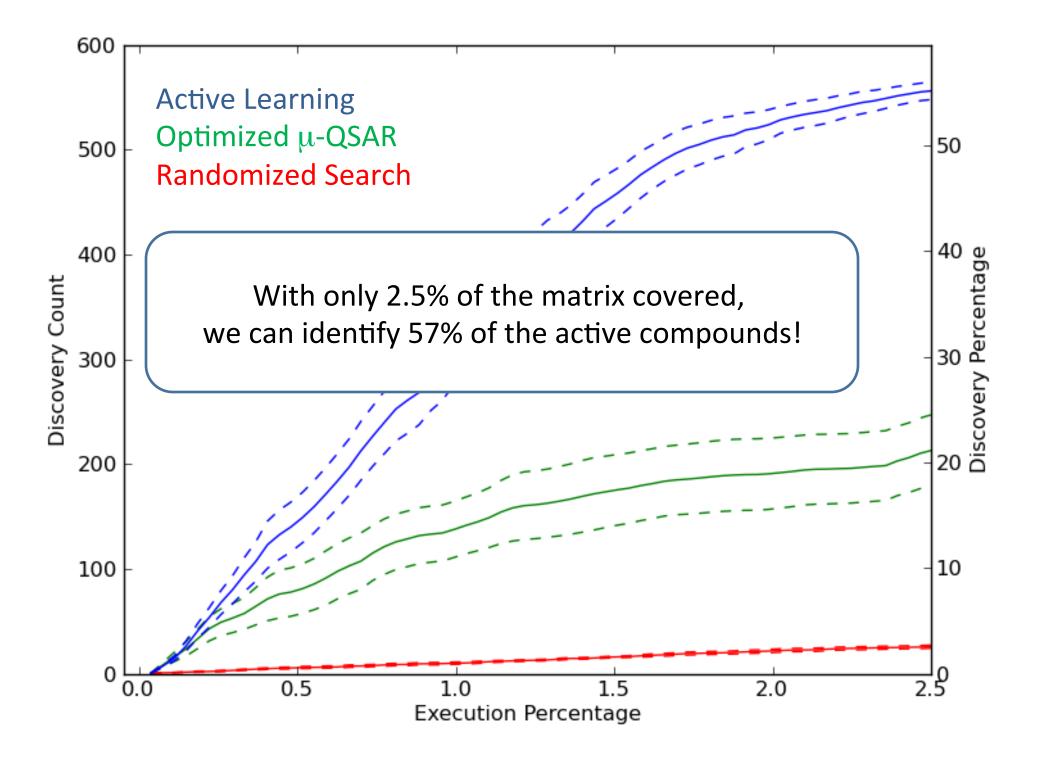
Use subset of PubChem Data

- Assays: 177
- Unique Protein Targets: 133
- Compounds: 20,000
- Experiments: ~1,000,000 (30% coverage)
- Use features to measure similarity between drugs and between targets
- Compare discovery rate across different methods
 - Discovery: a drug-protein pair whose |rank score| > 80

Sparse model

- Need model that can be built from very limited data during initial acquisition
- Used LASSO models for each target and for each drug, average predictions from each
- Used 50% greedy/50% uncertainty hybrid
- Used "memory limitation" to focus learning models from recently acquired data

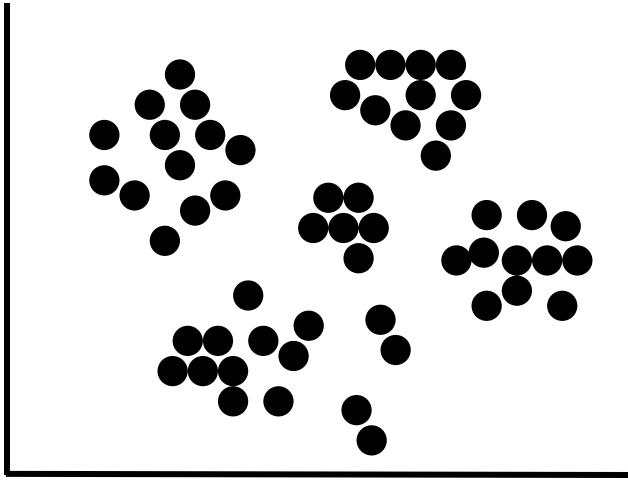




- These methods are based on
 - having estimates of similarity among drugs and/or targets (normally both), typically from descriptive features
 - permits predictions to be made about drugs or targets for which few or no experiments have been done
 - having binary or real-valued experimental outputs
- What do we do when
 - features are not reliable, or not possible
 - outputs are multidimensional?

Example: image-based screening Drugs Drug j Proteins Protein *k*

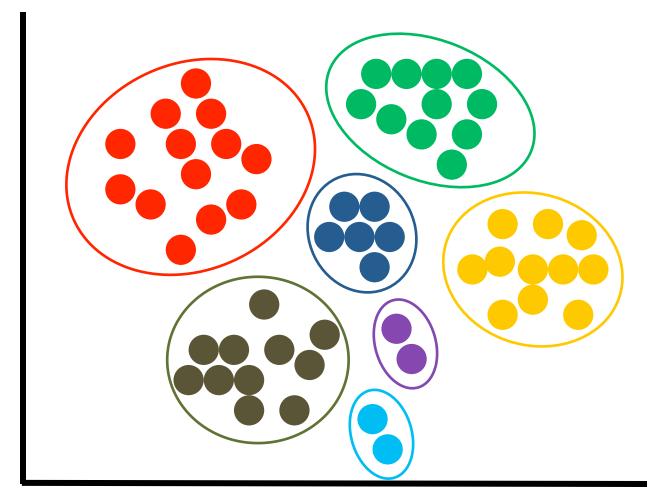
Consider each experiment in a Feature Space



Feature Component 1

Feature Component 2

Cluster to form Phenotypes

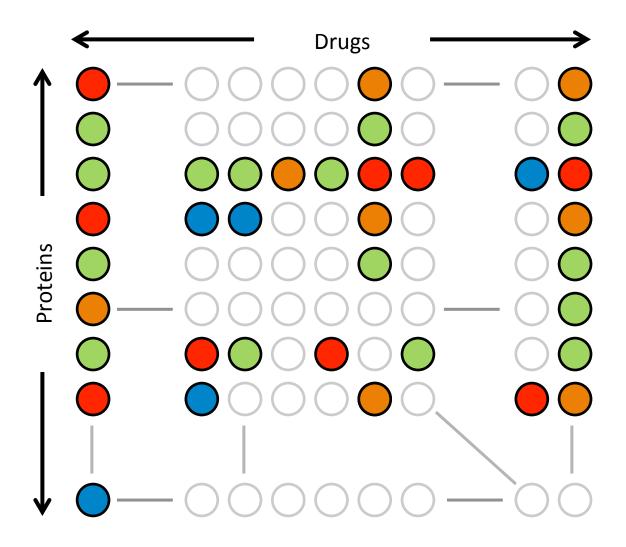


Feature Component 1



Feature Component 2

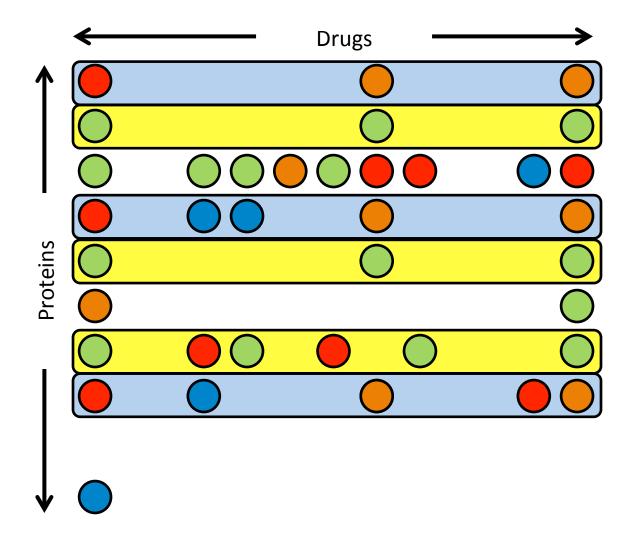
How do we form Predictions for Unobserved Experiments?





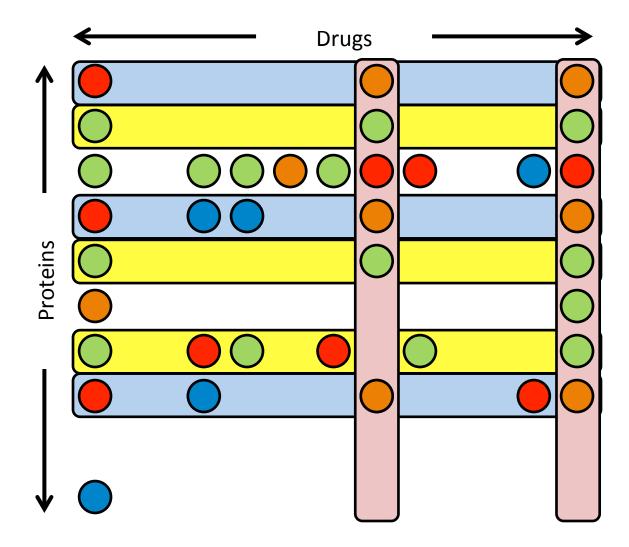
Unobserved

Identify Proteins with Similar Responses to Drugs



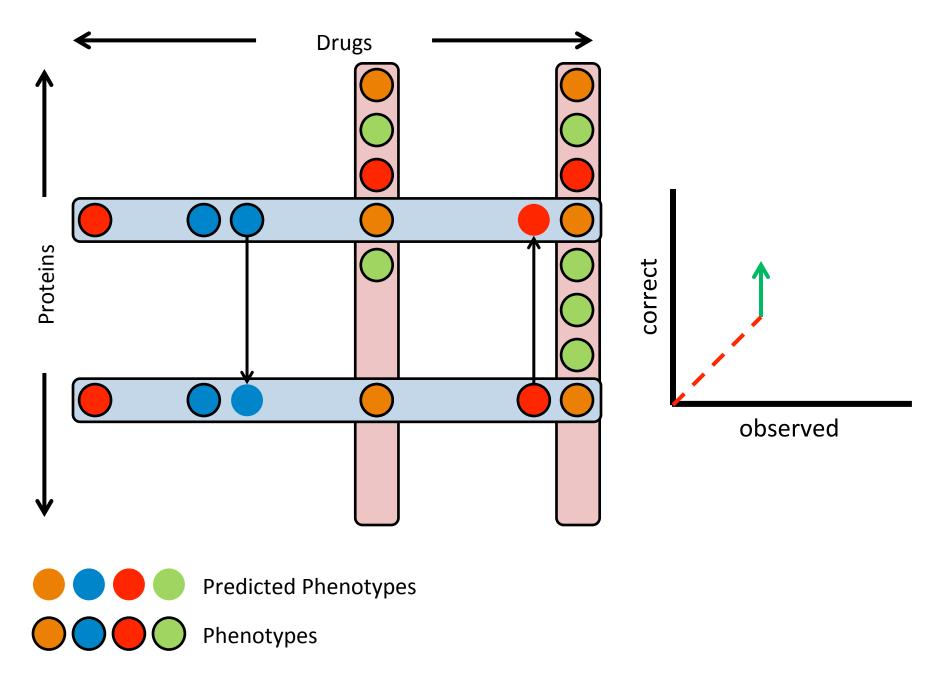


Identify Drugs with Similar Effects on Proteins

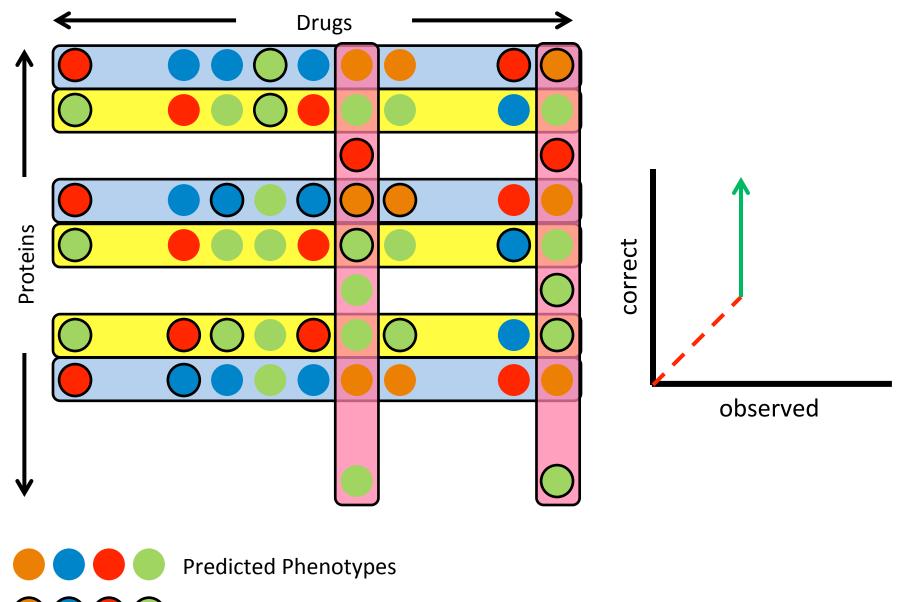


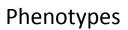


Use Similarities to Predict (matrix factorization without prior kernels)

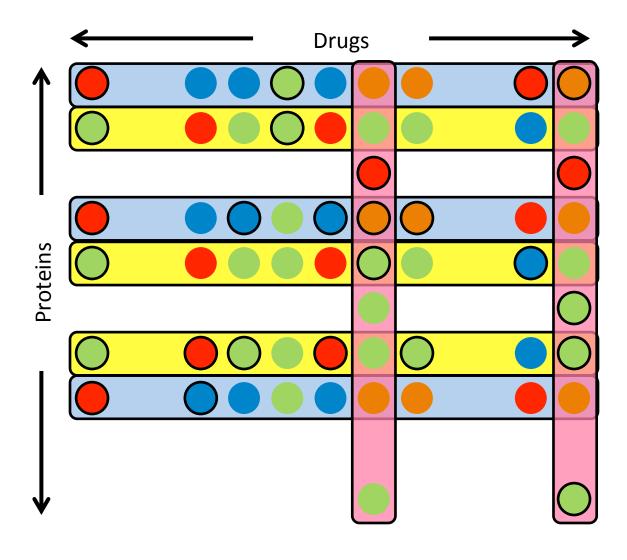


These considerations lead to a predictive model



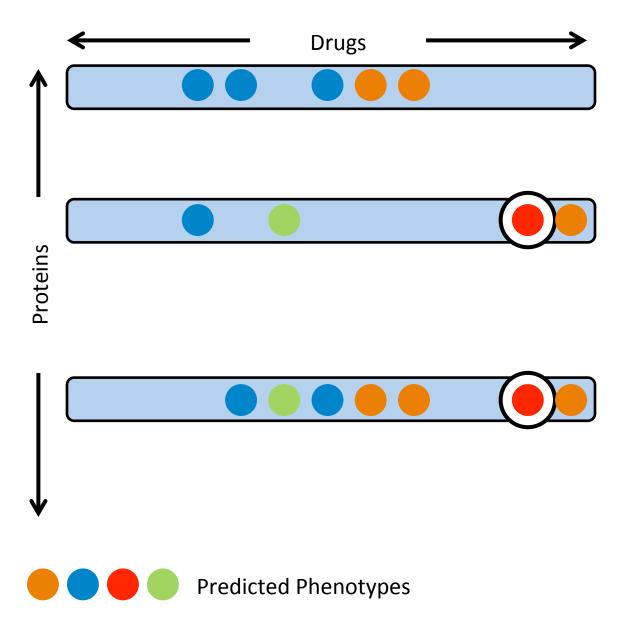


How do we choose the next experiments?

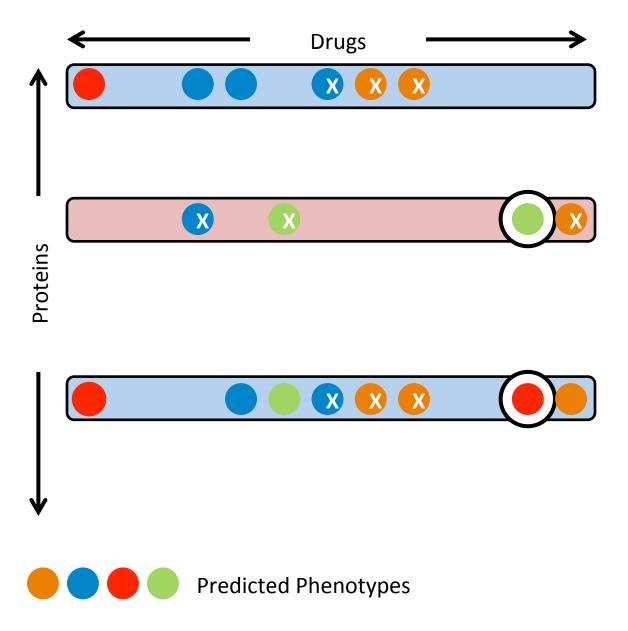




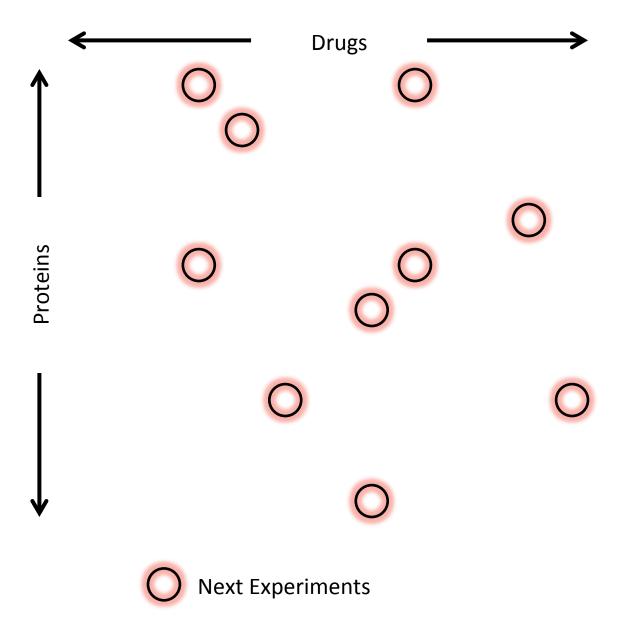
Which experiments test equivalences?



Impact of falsification of equivalence



Identify an Informative Batch of Experiments to Perform Next

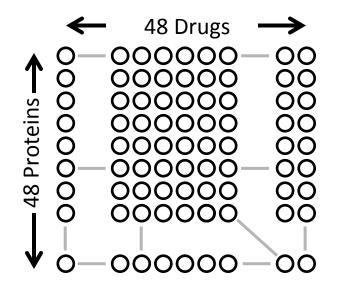


Testing Prospectively

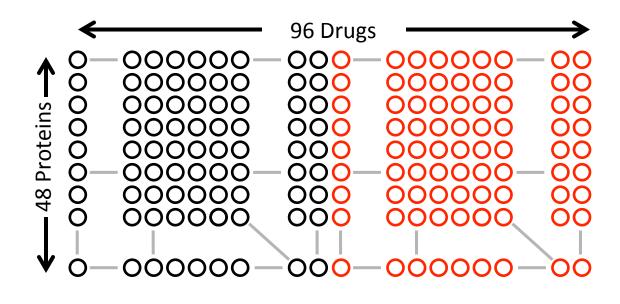
 Learning the effects of many compounds (drugs) on the subcellular localization of many proteins

NIH-3T3	1	2	3	4	5	6	7
8	9	10	11	12	13	14	15
16	17	18	19	20	21	22	23
24	25	26	27	28	29	30	31
32	33	34	35	36	37	38	39
40	41	42	43	44	45	47	48

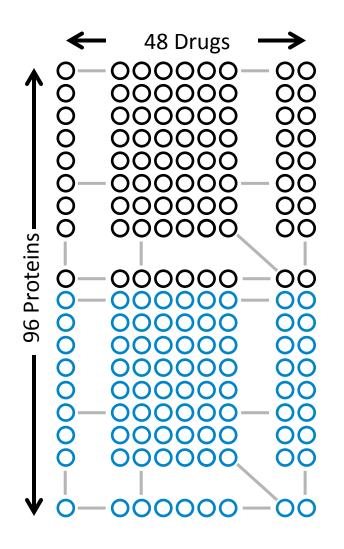
Underlying Experiment Space: 48 Proteins x 48 Drugs



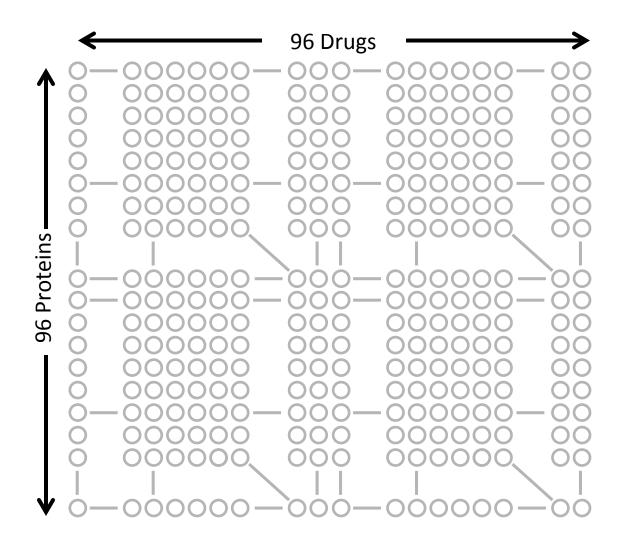
Since no information available on what effects to expect, need some way to evaluate effectiveness of active learning. → Use "hidden" duplication of drugs and proteins Silently Duplicate Drugs



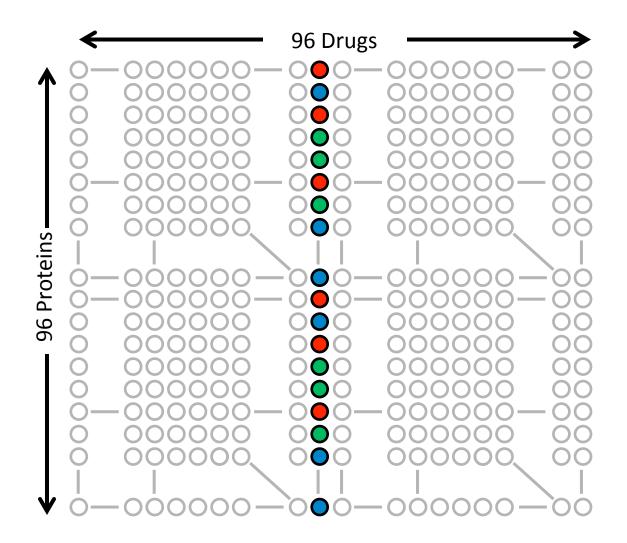
Silently Duplicate Proteins



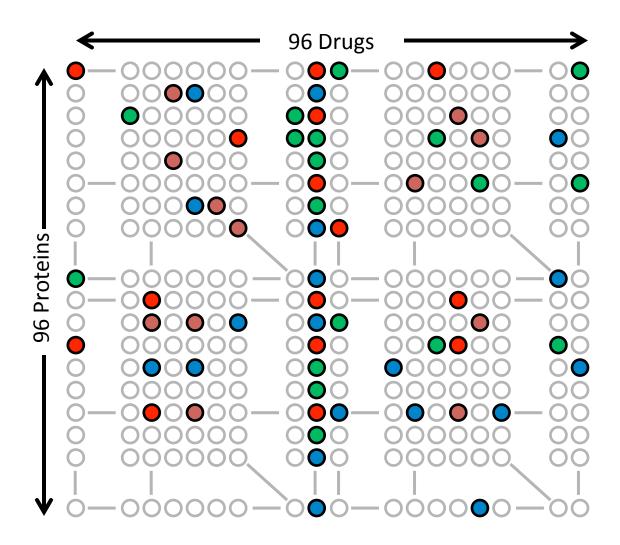
Silently Duplicate Proteins and Drugs to 96x96



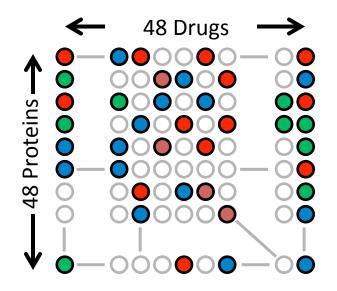
Starting data: All 96 Proteins with No Drug



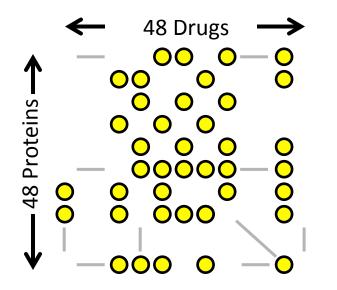
Actively Sampled 30 Batches (=28% of the 96x96 experiment space)



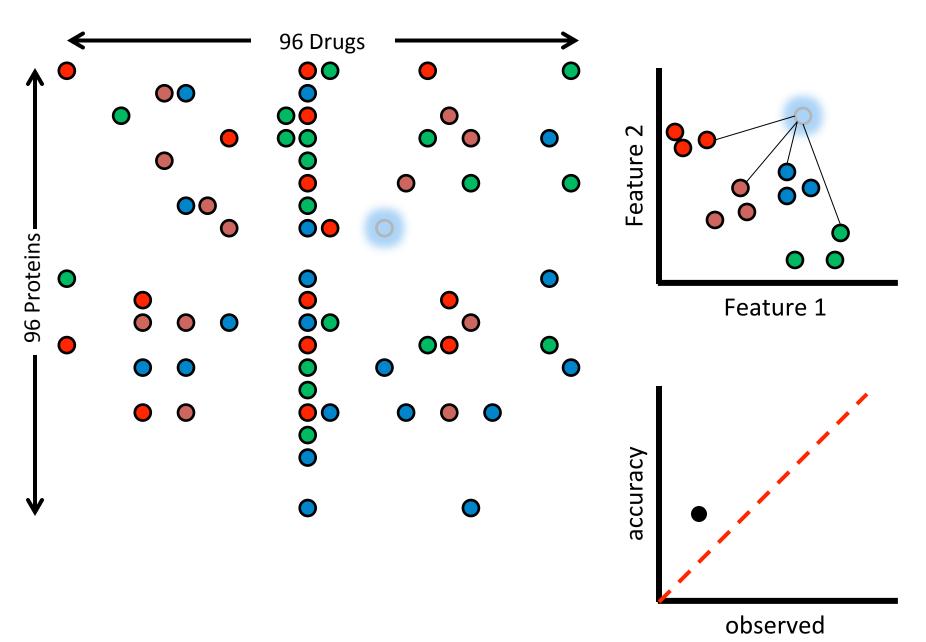
The 30 Batches covered 72% of the 48x48 space



Performed remaining unique (protein, drug) combinations



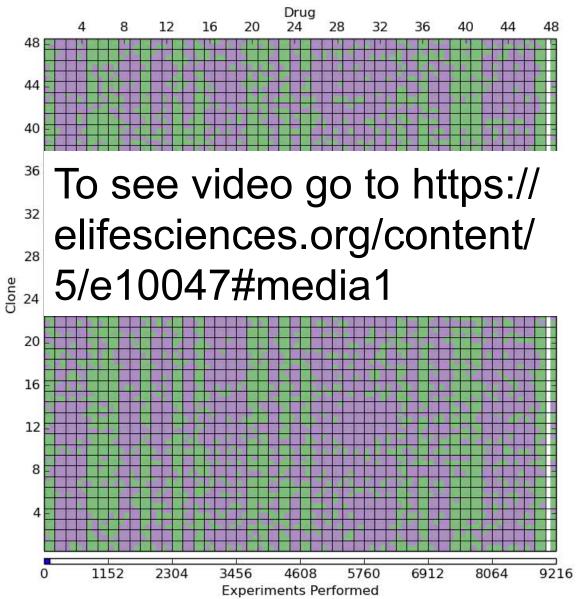
• 48x48 space filled in data

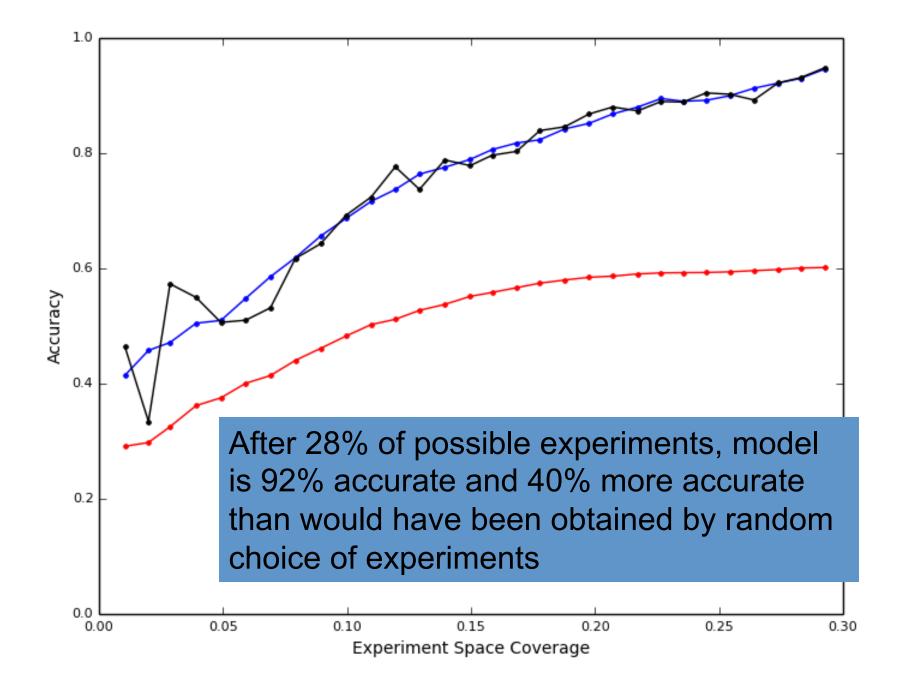


How well did it learn? Measure generalization performance

Automated, Prospective Active Learning

- Each small box is one drug and one target (but due to duplication there are four combinations)
- Green shows accurate prediction, purple is inaccurate, white shows experiments done





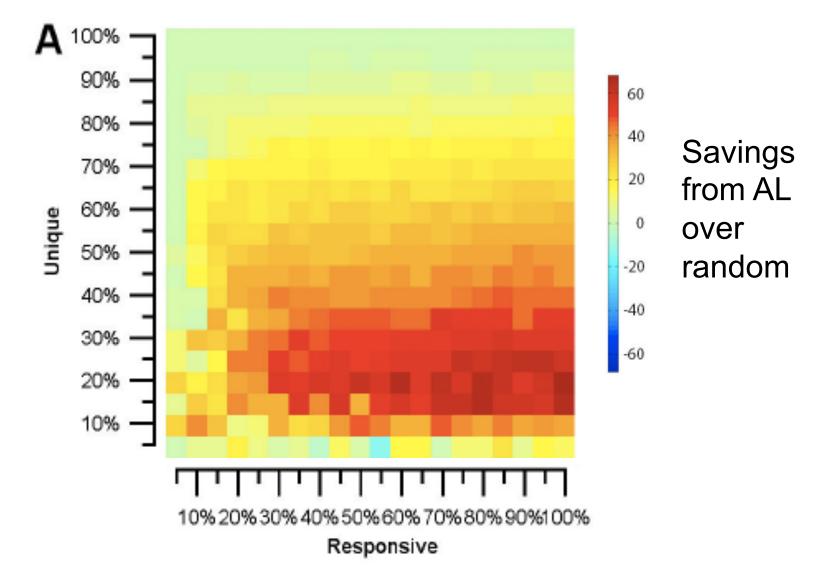
Knowing when to stop AL

- When evaluating retrospectively, can calculate accuracy of any model using full data to decide how well we are doing
- In any prospective application, can't do that
- Need stopping criterion
- Past proposals of single criterion, typically based upon consistency/confidence of predictions
- We propose a machine learned criterion based on active learning trajectory

Characterizing experimental spaces

- Basis of both matrix factorization and active learning is presence of correlations (low rank)
- Sparseness of interactions influences ability to learn correlations
- Define uniqueness as probability that all drugs and targets have different responses (100% = full rank)
- Define responsiveness as probability that any drug will affect any target (low%=sparse)

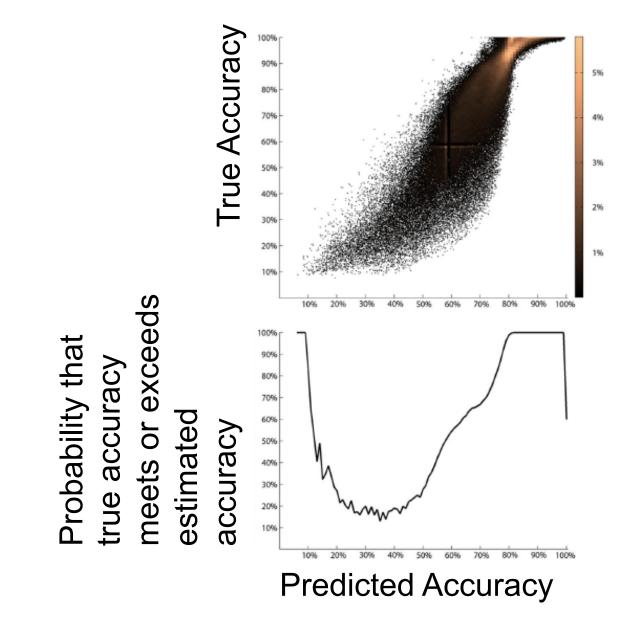
Active learning simulations for different experimental spaces



Learning a stopping criterion

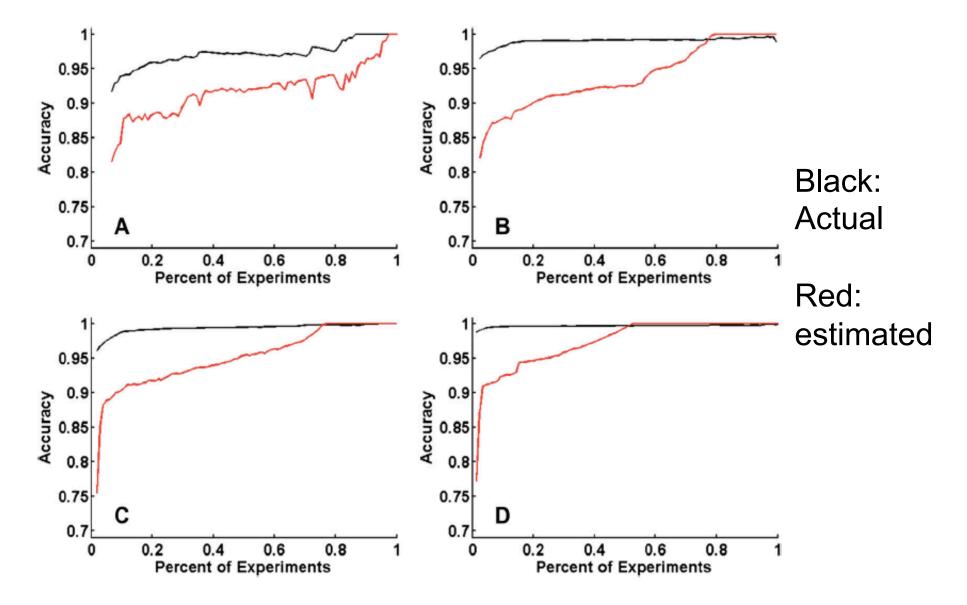
- Assuming a parameterization of an experimental space (such as uniqueness and responsiveness), perform many simulations over that space and record features for each active learning run (e.g., number of phenotypes observed, consistency of new experiments with predictions, number of conditions that differ within a target)
- Learn a regression function over all simulations to predict accuracy of model from these features

Learning the stopping criterion



Temerinac-Ott, Naik & Murphy, BMC Bioinformatics 2015

Estimating accuracy during active learning



Reduced number of experiments chosen by stopping criterion

Dataset	Goenen results AUC (%)	With stopping rule	
		AUC(%)	experiments (%)
NR	82.4	81.7	52.9
GPCR	85.7	81.6	39.3
IC	79.9	83.8	44.2
Enz	83.2	77.8	29.7

Stopping when estimated accuracy = 90%

Summary

- Empirical results for value of active learning for "large" heterogeneous experimental spaces starting with little data
- First prospective demonstration of active learning driven experimentation for unknown phenotypes
- Machine learning approach for learning stopping criteria

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