

Analysis of Probabilistic Systems

Boot camp Lecture 3: Probabilistic relations

Prakash Panangaden¹

¹School of Computer Science
McGill University

Fall 2016, Simons Institute

- 1 Relations
- 2 Monads and algebras
- 3 The category of measurable spaces
- 4 The Lawvere-Giry monad
- 5 Kozen's semantics for a language with while loops

Ordinary binary relations

- X, Y, Z sets and R, S relations.
- $R : X \rightarrow Y, S : Y \rightarrow Z; R \subseteq X \times Y, S \subseteq Y \times Z$.
- Compose $S \circ R \subseteq X \times Z$ given by $x(S \circ R)z$ iff $\exists y \in Y, xRy \wedge ySz$.
- Composition is associative.
- Rich algebraic structure: Kleene algebra, a compact closed category, the Kleisli category of the powerset monad.

The category **Rel**

- Objects: sets, an arrow X to Y is a binary relation $R \subseteq X \times Y$.
- Composition is relational composition. The identity on X is $I_X = \{\langle x, x \rangle : x \in X\}$; also often written as Δ .
- Shares many properties of the category of finite-dimensional vector spaces: tensor structure, transpose, trace, *etc.*
- Any relation $R \subseteq X \times Y$ corresponds uniquely to a function $f_R : X \rightarrow \mathcal{P}(Y) : f_R(x) = \{y : xRy\}$.
- Any function $f : X \rightarrow \mathcal{P}(Y)$ defines a binary relation.
- Any function $f : X \rightarrow \mathcal{P}(Y)$ can be *lifted* to a function $f^\dagger : \mathcal{P}(X) \rightarrow \mathcal{P}(Y)$ where
- $f^\dagger(A \subseteq X) = \bigcup_{a \in A} f(a)$. We usually write just $f(A)$.
- Composition of these functions is exactly the same as relational composition.
- Intimate relation between **Set**, **Rel** and the powerset operation.

Powerset categorically

- Recall **Set** the category of sets and functions.
- We have a *functor* $\mathcal{P}() : \mathbf{Set} \rightarrow \mathbf{Set}$ which $X \mapsto \mathcal{P}(X)$ and
- $f : X \rightarrow Y \mapsto \mathcal{P}(f)$ defined by $\mathcal{P}(f)(A \subseteq X) = f(A)$.
- This has extra structure: $\forall X, \exists \eta_X : X \rightarrow \mathcal{P}(X)$ given by $\eta_X(x) = \{x\}$.
- $\forall X, \exists \mu_X : \mathcal{P}(\mathcal{P}(X)) \rightarrow \mathcal{P}(X)$ given by union.
- These maps are very “natural”!

$$\begin{array}{ccc} X & \xrightarrow{f} & Y \\ \eta_X \downarrow & & \downarrow \eta_Y \\ \mathcal{P}(X) & \xrightarrow{\mathcal{P}(f)} & \mathcal{P}(Y) \end{array}$$

- \mathcal{C} a category, $T : \mathcal{C} \rightarrow \mathcal{C}$ an endofunctor.
- Natural transformations: $\eta : I \rightarrow T$ and $\mu : T^2 \rightarrow T$ satisfying

$$\begin{array}{ccc}
 T^3(X) & \xrightarrow{T\mu_X} & T^2(X) \\
 \mu_{T(X)} \downarrow & & \downarrow \mu_X \\
 T^2(X) & \xrightarrow{\mu_X} & T(X)
 \end{array}
 \quad \text{and} \quad
 \begin{array}{ccc}
 T(X) & \xrightarrow{T(\eta_X)} & T^2(X) \\
 \eta_{T(X)} \downarrow & \searrow & \downarrow \mu_X \\
 T^2(X) & \xrightarrow{\mu_X} & T(X)
 \end{array}$$

The Kleisli category of a monad

- Monads are the main ingredient in the categorical treatment of universal algebra. The Eilenberg-Moore category.
- But it will take us too far afield to do that.
- Given a monad $T : \mathcal{C} \rightarrow \mathcal{C}$ we define a new category \mathcal{C}_T : objects are the same as in \mathcal{C} . An arrow from X to Y in \mathcal{C}_T is an arrow of \mathcal{C} from X to TY .
- Composition? $f : X \rightarrow TY$, $g : Y \rightarrow TZ$.
- Apply T to g to get $Tg : TX \rightarrow T^2Y$, compose with f to get $Tg \circ f : X \rightarrow T^2Z$.
- Now compose with $\mu_Z : T^2Z \rightarrow TZ$ to get an arrow $X \rightarrow TZ$.
- Doing this with $\mathcal{P}(\cdot)$ is exactly what we did before and gives relational composition.
- Thus, the Kleisli category of the powerset monad is **Rel**.

Measurable spaces as a category

- **Mes**: objects (X, Σ) measurable spaces, arrows measurable functions.
- In many ways, just like **Set**: products, coproducts, pushouts etc.
- In fact it is a topological concrete category over **Set** so is complete and cocomplete.
- What about adding probability measures?
- **Prob**: objects (X, Σ, P) and arrows are measurable and *measure preserving*.
- $f : (X, \Sigma, P) \rightarrow (Y, \Lambda, Q)$ satisfies $Q = P \circ f^{-1}$.
- This category does not have products.
- Many variations are possible.
- Slogan: put the probabilities into the arrows.

The Lawvere-Gíry monad I

- The underlying category is **Mes**.
- $\Gamma : \mathbf{Mes} \rightarrow \mathbf{Mes}$ defined by
 $\Gamma(X, \Sigma) = \{\nu : \nu \text{ a prob. measure on } \Sigma\}$.
- But $\Gamma(X)$ needs a σ -algebra structure on it too.
- $\forall A \in \Sigma$, define $ev_A : \Gamma(X) \rightarrow [0, 1]$ by $ev_A(\nu) = \nu(A)$.
- Endow $\Gamma(X)$ with the *smallest* σ -algebra making all the p_A measurable.
- Given $f : (X, \Sigma) \rightarrow (Y, \Lambda)$ define $\Gamma(f)(\nu) = \nu \circ f^{-1}$.
- $\eta_X : X \rightarrow \Gamma(X)$ is $x \mapsto \delta_x$
- This is like a “probabilistic powerset” with a singleton embedding.
- But what is the analogue of union?

The Lawvere-Gíry monad II

- We need $\mu_X : \Gamma(\Gamma(X)) \rightarrow \Gamma(X)$.
- Let $\Omega \in \Gamma(\Gamma(X))$ *i.e.* a measure on $\Gamma(X)$. $\mu_X(\Omega)$ has to be a measure on (X, Σ) .
- It has to assign a number to any measurable set $A \in \Sigma$.
- Recall that $ev_A : \Gamma(X) \rightarrow [0, 1]$ is a measurable function.
- $\mu_X(\Omega)(A) = \int_{\Gamma(X)} ev_A d\Omega$.
- Checking the various equations is readily done with the monotone convergence theorem.

The Kleisli category – probabilistic relations

- The objects are measurable spaces (X, Σ) .
- A map h from (X, Σ) to (Y, Λ) is a measurable function from X to $\Gamma(Y)$.
- $h : X \rightarrow (\Lambda \rightarrow [0, 1])$ or, currying, we get
- $h : X \times \Lambda \rightarrow [0, 1]$. Write it as $h(x, B)$ for $x \in X$ and $B \in \Lambda$.
- $h(\cdot, B)$ is measurable and $h(x, \cdot)$ is a probability measure.
- In fact these are precisely disintegrations, aka regular conditional probability densities aka Markov kernels.
- Composition $h : X \rightarrow Y, k : Y \rightarrow Z$ and $(k \circ h)(x, C) = \int_Y k(y, C) dh(x, \cdot)$.
- This is the analogue of relational composition with integration replacing \exists .
- In finite discrete spaces this is just the formula for matrix multiplication.
- We will call this category **SRel** for “stochastic relations.”

Kozen's Language

$$S ::= x_i := f(\vec{x}) \mid S_1; S_2 \mid \text{if } \mathbf{B} \text{ then } S_1 \text{ else } S_2 \mid \text{while } \mathbf{B} \text{ do } S.$$

- There are a fixed set of variables \vec{x} taking values in a measurable space (X, Σ_X) .
- f is a measurable function.
- B is a measurable subset.

- State transformer semantics: distribution (measure) transformer semantics.
- Meaning of statements: Markov kernels *i.e.* **SRel** morphisms.
- The only subtle part: how to give fixed-point semantics to the while loop?

A tiny variation of Giry's monad

- Instead of Γ we define $\Pi : (X, \Sigma) = \{\nu \mid \nu(X) \leq 1\}$.
- Other structure defined exactly as in Γ .
- We will use **SRel** to stand for the Kleisli category of Π .
- Why make this tiny change?

Partially additive structure

- Now we can “add” **SRel** morphisms!
- Not always, the sum may exceed 1, but we can define *summable families* which may even be countably infinite.
- The homsets of **SRel** form *partially additive monoids*.
- The sums can be rearranged at will (partition-associativity).
- Limit property: If F is a countable family in which every *finite* subfamily is summable then F is summable.
- In the category **SRel**, the sums interact properly with composition.
- If $\{f_i \mid i \in \mathbb{N}\}$ is a countable set of morphisms from X to Y and there is a morphism $f : X \rightarrow (Y + Y + \dots)$ such that when projected onto the Y 's we get the f_i , then the family is summable.

Arbib and Manes

Given a partially additive category \mathcal{C} and $f : X \rightarrow X + Y$ we can find a unique pair $f_1 : X \rightarrow X$ and $f_2 : X \rightarrow Y$ such that $f = \iota_1 \circ f_1 + \iota_2 \circ f_2$. Furthermore, there is a morphism $f^* : X \rightarrow Y$ given by

$$f^* = \sum_{n=0}^{\infty} f_2 \circ f_1^n.$$

The theorem says that the family $f_2 \circ f_1^n$ is summable. It is the *iterate* of f .

Semantics of Kozen's Language I

- Statements are **SRel** morphisms of type $(X^n, \Sigma^n) \rightarrow (X^n, \Sigma^n)$.
- **Assignment:** $x := f(\vec{x})$

$$\llbracket x_i := f(\vec{x}) \rrbracket(\vec{x}, \vec{A}) = \delta(x_1, A_1) \dots \delta(x_{i-1}, A_{i-1}) \delta(f(\vec{x}), A_i) \delta(x_{i+1}, A_{i+1}) \dots$$

- **Sequential Composition:** $S_1; S_2$

$$\llbracket S_1; S_2 \rrbracket = \llbracket S_2 \rrbracket \circ \llbracket S_1 \rrbracket$$

where the composition on the right hand side is the composition in **SRel**.

- **Conditionals:** *if* **B** *then* S_1 *else* S_2

$$\llbracket \text{if } \mathbf{B} \text{ then } S_1 \text{ else } S_2 \rrbracket(\vec{x}, \vec{A}) = \delta(\vec{x}, \mathbf{B}) \llbracket S_1 \rrbracket(\vec{x}, \vec{A}) + \delta(\vec{x}, \mathbf{B}^c) \llbracket S_2 \rrbracket(\vec{x}, \vec{A})$$

While Loops: *while* **B** *do* *S*

$$\llbracket \textit{while } \mathbf{B} \textit{ do } S \rrbracket = h^*$$

where we are using the $*$ in **SRel** and the morphism

$$h : (X^n, \Sigma^n) \rightarrow (X^n, \Sigma^n) + (X^n, \Sigma^n)$$

is given by

$$h(\vec{x}, \vec{A}_1 \uplus \vec{A}_2) = \delta(\vec{x}, \mathbf{B}) \llbracket S \rrbracket(\vec{x}, \vec{A}_1) + \delta(\vec{x}, \mathbf{B}^c) \delta(\vec{x}, \vec{A}_2).$$

Weakest precondition semantics

- We can construct a category of probabilistic predicate transformers: **SPT**.
- Objects are measurable spaces.
- Given (X, Σ_X) we can construct the (Banach) space of bounded measurable functions on X (the “predicates”) $\mathcal{F}(X)$.
- A morphism $X \rightarrow Y$ in **SPT** is a bounded (continuous) linear map from $\mathcal{F}(X)$ to $\mathcal{F}(Y)$.



$$\mathbf{SPT} \simeq \mathbf{SRel}^{op}.$$

- This gives us the structure needed for a **wp** semantics.