

Recovery of algebraic-exponential data from moments

Jean B. Lasserre

LAAS-CNRS and Institute of Mathematics, Toulouse, France

SIMONS Institute, October 2014

★ Part of this work is joint with [M. Putinar](#)

- Motivation
- An important property of **Positively Homogeneous Functions (PHF)**
- Some properties (convexity, polarity)
- Sub-level sets of minimum volume containing **K**
- Exact reconstruction from moments
- Recovery of the defining function of a semi-algebraic set

- Motivation
- An important property of **Positively Homogeneous Functions (PHF)**
- Some properties (convexity, polarity)
- Sub-level sets of minimum volume containing K
- Exact reconstruction from moments
- Recovery of the defining function of a semi-algebraic set

- Motivation
- An important property of **Positively Homogeneous Functions (PHF)**
- Some properties (convexity, polarity)
- Sub-level sets of minimum volume containing K
- Exact reconstruction from moments
- Recovery of the defining function of a semi-algebraic set

- Motivation
- An important property of **Positively Homogeneous Functions (PHF)**
- Some properties (convexity, polarity)
- Sub-level sets of minimum volume containing **K**
- Exact reconstruction from moments
- Recovery of the defining function of a semi-algebraic set

- Motivation
- An important property of **Positively Homogeneous Functions (PHF)**
- Some properties (convexity, polarity)
- Sub-level sets of minimum volume containing **K**
- Exact reconstruction from moments
- Recovery of the defining function of a semi-algebraic set

- Motivation
- An important property of **Positively Homogeneous Functions (PHF)**
- Some properties (convexity, polarity)
- Sub-level sets of minimum volume containing **K**
- Exact reconstruction from moments
- Recovery of the defining function of a semi-algebraic set

Exact reconstruction

Reconstruction of a shape $\mathbf{K} \subset \mathbb{R}^n$ (convex or not)

from knowledge of **finitely many** moments

$$y_\alpha = \int_{\mathbf{K}} x_1^{\alpha_1} \cdots x_n^{\alpha_n} dx, \quad \alpha \in \mathbb{N}_d^n,$$

for some integer d , is a difficult and challenging problem!

EXACT recovery of \mathbf{K}

from $y = (y_\alpha)$, $\alpha \in \mathbb{N}_d^n$, is even more difficult and challenging!

Exact reconstruction

Reconstruction of a shape $\mathbf{K} \subset \mathbb{R}^n$ (convex or not)

from knowledge of **finitely many** moments

$$y_\alpha = \int_{\mathbf{K}} x_1^{\alpha_1} \cdots x_n^{\alpha_n} dx, \quad \alpha \in \mathbb{N}_d^n,$$

for some integer d , is a difficult and challenging problem!

EXACT recovery of \mathbf{K}

from $y = (y_\alpha)$, $\alpha \in \mathbb{N}_d^n$, is even more difficult and challenging!

Exact recovery (continued)

Examples of exact recovery:

- **Quadrature (planar) Domains** in (\mathbb{R}^2) (Gustafsson, He, Milanfar and Putinar (Inverse Problems, 2000))
 - via an exponential transform
- **Convex Polytopes** (in \mathbb{R}^n) (Gravin, Lasserre, Pasechnik and Robins (Discrete & Comput. Geometry (2012))
 - Use Brion-Barvinok-Khovanski-Lawrence-Pukhlikov moment formula for projections $\int_P \langle c, x \rangle^j dx$ combined with a **Prony**-type method to recover the **vertices** of P .
- and extension to **Non convex polyhedra** by Pasechnik et al.
 - via inversion of Fantappiè transform

Exact recovery (continued)

Examples of exact recovery:

- **Quadrature (planar) Domains** in (\mathbb{R}^2) (Gustafsson, He, Milanfar and Putinar (Inverse Problems, 2000))
 - via an exponential transform
- **Convex Polytopes** (in \mathbb{R}^n) (Gravin, Lasserre, Pasechnik and Robins (Discrete & Comput. Geometry (2012))
 - Use Brion-Barvinok-Khovanski-Lawrence-Pukhlikov moment formula for projections $\int_P \langle c, x \rangle^j dx$ combined with a **Prony**-type method to recover the **vertices** of P .
- and extension to **Non convex polyhedra** by Pasechnik et al.
 - via inversion of Fantappiè transform

Approximate recovery can be done in multi-dimensions

(Cuyt, Golub, Milanfar and Verdonk, 2005) via :

- (multi-dimensional versions of) **homogeneous Padé approximants** applied to the Stieltjes transform.
- cubature formula at each point of grid
- solving a linear system of equations to retrieve the indicator function of **K**

This talk: I

- Exact recovery.
- $K = \{x \in \mathbb{R}^n : g(x) \leq 1\}$ compact.
- g is a nonnegative homogeneous polynomial
- Data are finitely many moments:

$$y_\alpha = \int_K \mathbf{x}^\alpha d\mathbf{x}, \quad \alpha \in \mathbb{N}_d^n.$$

- Also works for Quasi-homogeneous polynomials, i.e., when

$$g(\lambda^{u_1} x_1, \dots, \lambda^{u_n} x_n) = \lambda g(x), \quad x \in \mathbb{R}^n, \lambda > 0$$

for some vector $u \in \mathbb{Q}^n$.

(d -Homogeneous = u -quasi homogeneous with $u_i = \frac{1}{d}$ for all i).

This talk: I

- Exact recovery.
- $\mathbf{K} = \{ \mathbf{x} \in \mathbb{R}^n : g(\mathbf{x}) \leq 1 \}$ compact.
- g is a nonnegative homogeneous polynomial
- Data are finitely many moments:

$$y_\alpha = \int_{\mathbf{K}} \mathbf{x}^\alpha d\mathbf{x}, \quad \alpha \in \mathbb{N}_d^n.$$

- Also works for Quasi-homogeneous polynomials, i.e., when

$$g(\lambda^{u_1} x_1, \dots, \lambda^{u_n} x_n) = \lambda g(x), \quad x \in \mathbb{R}^n, \lambda > 0$$

for some vector $u \in \mathbb{Q}^n$.

(d -Homogeneous = u -quasi homogeneous with $u_i = \frac{1}{d}$ for all i).

This talk: I

- Exact recovery.
- $\mathbf{K} = \{ \mathbf{x} \in \mathbb{R}^n : g(\mathbf{x}) \leq 1 \}$ compact.
- g is a **nonnegative homogeneous polynomial**
- Data are **finitely many** moments:

$$y_\alpha = \int_{\mathbf{K}} \mathbf{x}^\alpha d\mathbf{x}, \quad \alpha \in \mathbb{N}_d^n.$$

- Also works for **Quasi-homogeneous** polynomials, i.e., when

$$g(\lambda^{u_1} x_1, \dots, \lambda^{u_n} x_n) = \lambda g(x), \quad x \in \mathbb{R}^n, \lambda > 0$$

for some vector $u \in \mathbb{Q}^n$.

(d -Homogeneous = u -quasi homogeneous with $u_i = \frac{1}{d}$ for all i).

This talk: I

- Exact recovery.
- $\mathbf{K} = \{ \mathbf{x} \in \mathbb{R}^n : g(\mathbf{x}) \leq 1 \}$ compact.
- g is a **nonnegative homogeneous polynomial**
- Data are **finitely many** moments:

$$y_\alpha = \int_{\mathbf{K}} \mathbf{x}^\alpha d\mathbf{x}, \quad \alpha \in \mathbb{N}_d^n.$$

- Also works for **Quasi-homogeneous** polynomials, i.e., when

$$g(\lambda^{u_1} x_1, \dots, \lambda^{u_n} x_n) = \lambda g(x), \quad x \in \mathbb{R}^n, \lambda > 0$$

for some vector $u \in \mathbb{Q}^n$.

(d -Homogeneous = u -quasi homogeneous with $u_i = \frac{1}{d}$ for all i).

This talk: I

- Exact recovery.
- $\mathbf{K} = \{ \mathbf{x} \in \mathbb{R}^n : g(\mathbf{x}) \leq 1 \}$ compact.
- g is a **nonnegative homogeneous polynomial**
- Data are **finitely many** moments:

$$y_\alpha = \int_{\mathbf{K}} \mathbf{x}^\alpha d\mathbf{x}, \quad \alpha \in \mathbb{N}_d^n.$$

- Also works for **Quasi-homogeneous** polynomials, i.e., when

$$g(\lambda^{u_1} x_1, \dots, \lambda^{u_n} x_n) = \lambda g(x), \quad x \in \mathbb{R}^n, \lambda > 0$$

for some vector $\mathbf{u} \in \mathbb{Q}^n$.

(d -Homogeneous = \mathbf{u} -quasi homogeneous with $u_i = \frac{1}{d}$ for all i).

This talk: II

- Exact recovery.
- $\mathbf{G} \subset \mathbb{R}^n$ is open with $\mathbf{G} = \text{int } \overline{\mathbf{G}}$ and with real algebraic boundary $\partial\mathbf{G}$. A polynomial of degree d vanishes on $\partial\mathbf{G}$.
- Data are **finitely many** moments:

$$y_\alpha = \int_{\mathbf{K}} \mathbf{x}^\alpha d\mathbf{x}, \quad \alpha \in \mathbb{N}_d^n.$$

This talk: II

- Exact recovery.
- $\mathbf{G} \subset \mathbb{R}^n$ is open with $\mathbf{G} = \text{int } \overline{\mathbf{G}}$ and with real algebraic boundary $\partial\mathbf{G}$. A polynomial of degree d vanishes on $\partial\mathbf{G}$.
- Data are **finitely many** moments:

$$y_\alpha = \int_{\mathbf{K}} \mathbf{x}^\alpha d\mathbf{x}, \quad \alpha \in \mathbb{N}_d^n.$$

This talk: II

- Exact recovery.
- $\mathbf{G} \subset \mathbb{R}^n$ is open with $\mathbf{G} = \text{int } \overline{\mathbf{G}}$ and with real algebraic boundary $\partial\mathbf{G}$. A polynomial of degree d vanishes on $\partial\mathbf{G}$.
- Data are **finitely many** moments:

$$y_\alpha = \int_{\mathbf{K}} \mathbf{x}^\alpha d\mathbf{x}, \quad \alpha \in \mathbb{N}_d^n.$$

A little detour

Positively Homogeneous functions (**PHF**) form a wide class of functions encountered in many applications. As a consequence of **homogeneity**, they enjoy very particular properties, and among them the celebrated and very useful **Euler's identity** which allows to deduce additional properties of PHFs in various contexts.

Another (apparently not well-known) property of PHFs yields surprising and unexpected results, some of them already known in particular cases.

The case of **homogeneous polynomials** is even more interesting!

A little detour

Positively Homogeneous functions (**PHF**) form a wide class of functions encountered in many applications. As a consequence of **homogeneity**, they enjoy very particular properties, and among them the celebrated and very useful **Euler's identity** which allows to deduce additional properties of PHFs in various contexts.

Another (apparently not well-known) property of PHFs yields surprising and unexpected results, some of them already known in particular cases.

The case of **homogeneous polynomials** is even more interesting!

So we are now concerned with PHFs, their **sublevel sets** and in particular, the **integral**

$$y \mapsto I_{g,h}(y) := \int_{\{x: g(x) \leq y\}} h(x) dx,$$

as a function $I_{g,h} : \mathbb{R}_+ \rightarrow \mathbb{R}$ when g, h are PHFs.

With y fixed, we are also interested in

$$g \mapsto I_{g,h}(y),$$

now as a function of g , especially when g is a nonnegative **homogeneous polynomial**.

Nonnegative homogeneous polynomials are particularly interesting as they can be used to approximate norms; see e.g. **Barvinok**

So we are now concerned with PHFs, their **sublevel sets** and in particular, the **integral**

$$y \mapsto I_{g,h}(y) := \int_{\{x: g(x) \leq y\}} h(x) dx,$$

as a function $I_{g,h} : \mathbb{R}_+ \rightarrow \mathbb{R}$ when g, h are PHFs.

With y fixed, we are also interested in

$$g \mapsto I_{g,h}(y),$$

now as a function of g , especially when g is a nonnegative **homogeneous polynomial**.

Nonnegative homogeneous polynomials are particularly interesting as they can be used to approximate norms; see e.g. **Barvinok**

Some motivation

Interestingly, the latter integral is related in a simple and remarkable manner to the non-Gaussian integral

$$\int_{\mathbb{R}^n} h \exp(-g) dx.$$

Functional integrals appear frequently in quantum Physics

... where a challenging issue is to provide

exact formulas for $\int \exp(-g) dx$, the most well-known being when $\deg g = 2$, i.e., $g(\mathbf{x}) = \mathbf{x}^T Q \mathbf{x}$, with $Q \succ 0$,

$$d = 2 \Rightarrow \int \exp(-g) dx = \frac{\text{Cte}}{\sqrt{\det(Q)}}.$$

Observe that $\det(Q)$ is an algebraic invariant of g ,

Some motivation

Interestingly, the latter integral is related in a simple and remarkable manner to the non-Gaussian integral

$$\int_{\mathbb{R}^n} h \exp(-g) dx.$$

Functional integrals appear frequently in quantum Physics

... where a challenging issue is to provide

exact formulas for $\int \exp(-g) dx$, the most well-known being when $\deg g = 2$, i.e., $g(\mathbf{x}) = \mathbf{x}^T \mathbf{Q} \mathbf{x}$, with $\mathbf{Q} \succ 0$,

$$d = 2 \Rightarrow \int \exp(-g) dx = \frac{\text{Cte}}{\sqrt{\det(\mathbf{Q})}}.$$

Observe that $\det(\mathbf{Q})$ is an algebraic invariant of g ,

The key tools are **discriminants** and $SL(n)$ -invariants.

An integral

$$J(g) := \int \exp(-g) dx$$

is called a **discriminant integral**.

Next if one write

$$\mathbf{x} \mapsto g(\mathbf{x}) = \sum_{a \in \mathbb{N}^n} g_a \mathbf{x}^a \quad (= \sum_{a \in \mathbb{N}^n} g_a \mathbf{x}_1^{a_1} \cdots \mathbf{x}_n^{a_n}).$$

The key tools are **discriminants** and $SL(n)$ -invariants.

An integral

$$J(g) := \int \exp(-g) dx$$

is called a **discriminant integral**.

Next if one write

$$\mathbf{x} \mapsto g(\mathbf{x}) = \sum_{\mathbf{a} \in \mathbb{N}^n} g_{\mathbf{a}} \mathbf{x}^{\mathbf{a}} \quad (= \sum_{\mathbf{a} \in \mathbb{N}^n} g_{\mathbf{a}} \mathbf{x}_1^{a_1} \cdots \mathbf{x}_n^{a_n}).$$

Integral discriminants satisfy **WARD Identities**

$$\left(\frac{\partial}{\partial g_{a_1 \dots a_n}} \frac{\partial}{\partial g_{b_1 \dots b_n}} - \frac{\partial}{\partial g_{c_1 \dots c_n}} \frac{\partial}{\partial g_{d_1 \dots d_n}} \right) \cdot J(g) = 0,$$

where $a_i + b_i = c_i + d_i$ for all i .

which in some (few) low-dimensional cases, permits to obtain exact formulas in terms of **algebraic invariants** of g . See e.g. **Morosov and Shakirov**¹

¹**New and old results in Resultant theory**, arXiv.0911.5278v1. 

In particular, as a by-product in the important particular case when $h = 1$, they have proved that for all forms g of degree d ,

$$\begin{aligned}\text{Vol}(\{x : g(x) \leq 1\}) &= \int_{\{x : g(x) \leq 1\}} dx \\ &= \text{cte}(d) \cdot \int_{\mathbb{R}^n} \exp(-g) d\mathbf{x},\end{aligned}$$

where the constant depends only on d and n .

In fact, a formula of exactly the same flavor was already known for **convex sets**, and was the initial motivation of our work. Namely, if $C \subset \mathbb{R}^n$ is convex, its **support function**

$$x \mapsto \sigma_C(x) := \sup \{x^T y : y \in C\},$$

is a PHF of degree 1, and the **polar** $C^\circ \subset \mathbb{R}^n$ of C is the **convex set** $\{x : \sigma_C(x) \leq 1\}$.

Then ...

$$\text{vol}(C^\circ) = \frac{1}{n!} \int_{\mathbb{R}^n} \exp(-\sigma_C(x)) dx, \quad \forall C.$$

I. An important property of PHF's

Let $\phi_1, \phi_2 : \mathbb{R}_+ \rightarrow \mathbb{R}$ be measurable mappings, and let $g \geq 0$ and h be PHFs of respective degree $0 \neq d, p \in \mathbb{Z}$.

We next show that

$$\frac{\int \phi_1(g) h \, d\mathbf{x}}{\int \phi_2(g) h \, d\mathbf{x}} = C(\phi_1, \phi_2, d, p),$$

that is

The ratio DOES DEPENDS ONLY on ϕ_1, ϕ_2 and the degree of homogeneity of g and h !

With $t \mapsto \phi_1(t) = 1_{[0,1]}(t) : \rightarrow \int_{\{g(\mathbf{x}) \leq 1\}} h(\mathbf{x}) \, d\mathbf{x}$.

With $t \mapsto \phi_2(t) = \exp(-t) : \rightarrow \int_{\mathbb{R}^n} h(\mathbf{x}) \exp(-g(\mathbf{x})) \, d\mathbf{x}$

Theorem

Let $\phi : \mathbb{R}_+ \rightarrow \mathbb{R}$ be a measurable mapping, and let $g \geq 0$ and h be PHFs of respective degree $0 \neq d, p \in \mathbb{Z}$ and such that $\int |h| \exp(-g) dx$ is finite,

$$\int_{\mathbb{R}^n} \phi(g(x)) h(x) dx = C(\phi, d, p) \cdot \int_{\mathbb{R}^n} h \exp(-g) dx,$$

where the constant $C(\phi, d, p)$ depends only on ϕ, d, p .
In particular, if the sublevel set $\{x : g(x) \leq 1\}$ is bounded, then

$$\int_{\{x : g(x) \leq y\}} h dx = \frac{y^{(n+p)/d}}{\Gamma(1 + (n+p)/d)} \int_{\mathbb{R}^n} h \exp(-g) dx,$$

with Γ being the standard Gamma function

Proof for nonnegative h

For simplicity assume that $g(x) > 0$ if $x \neq 0$. With $z = (z_1, \dots, z_{n-1})$, do the change of variable $x_1 = t$, $x_2 = tz_1, \dots, x_n = tz_{n-1}$ so that one may decompose $\int_{\mathbb{R}^n} \phi(g(x)) h(x) dx$ into the sum

$$\begin{aligned} & \int_{\mathbb{R}_+ \times \mathbb{R}^{n-1}} t^{n+p-1} \phi(t^d g(1, z)) h(1, z) dt dz \\ & + \int_{\mathbb{R}_+ \times \mathbb{R}^{n-1}} t^{n+p-1} \phi(t^d g(-1, -z)) h(-1, z) dt dz, \\ & = \int_{\mathbb{R}^{n-1}} \left(\int_0^\infty t^{n+p-1} \phi(t^d g(1, z)) dt \right) h(1, z) dz \\ & + \int_{\mathbb{R}^{n-1}} \left(\int_0^\infty t^{n+p-1} \phi(t^d g(-1, -z)) dt \right) h(-1, -z) dz, \end{aligned}$$

where the last two integrals are obtained from the sum of the previous two by using Tonelli's Theorem.

Proof (continued)

Next, with the change of variable $u = t g(1, z)^{1/d}$ and $u = t g(-1, -z)^{1/d}$

$$\int_{\mathbb{R}^n} \phi(g(x)) h(x) dx = \underbrace{\left(\int_{\mathbb{R}_+} u^{n+p-1} \phi(u^d) du \right)}_{\text{Cte}(\phi, p, d)} \cdot A(g, h),$$

with

$$A(g, h) = \int_{\mathbb{R}^{n-1}} \left(\frac{h(1, z)}{g(1, z)^{(n+p)/d}} + \frac{h(-1, -z)}{g(-1, -z)^{(n+p)/d}} \right) dz.$$

□

Choosing $\phi(t) = \exp(-t)$ on $[0, +\infty)$ yields:

$$\int_{\mathbb{R}^n} \exp(-g(x)) h(x) dx = \frac{\Gamma(1 + (n+p)/d)}{n+p} \cdot A(g, h),$$

whereas, choosing $\phi(t) = I_{[0,1]}(t)$ on $[0, +\infty)$ yields:

$$\int_{\{x : g(x) \leq 1\}} h(x) dx = \frac{1}{n+p} \cdot A(g, h),$$

Choosing $\phi(t) = \exp(-t)$ on $[0, +\infty)$ yields:

$$\int_{\mathbb{R}^n} \exp(-g(x)) h(x) dx = \frac{\Gamma(1 + (n+p)/d)}{n+p} \cdot A(g, h),$$

whereas, choosing $\phi(t) = I_{[0,1]}(t)$ on $[0, +\infty)$ yields:

$$\int_{\{x : g(x) \leq 1\}} h(x) dx = \frac{1}{n+p} \cdot A(g, h),$$

And so in particular, whenever g is nonnegative and $\{x : g(x) \leq 1\}$ has finite Lebesgue volume:

Theorem

If g, h are PHFs of degree $0 < d$ and p respectively, then:

$$\int_{\{x : g(x) \leq y\}} h \, dx = \frac{y^{(n+p)/d}}{\Gamma(1 + (n+p)/d)} \int_{\mathbb{R}^n} \exp(-g) h \, dx$$

$$\text{vol}(\{x : g(x) \leq y\}) = \frac{y^{n/d}}{\Gamma(1 + n/d)} \int_{\mathbb{R}^n} \exp(-g) \, dx$$

An alternative proof

Let g, h be nonnegative so that $I_{g,h}(y)$ vanishes on $(-\infty, 0]$. For $0 < \lambda \in \mathbb{R}$, its Laplace transform

$\lambda \mapsto \mathcal{L}_{I_{g,h}}(\lambda) = \int_0^\infty \exp(-\lambda y) I_{g,h}(y) dy$ reads:

$$\begin{aligned}\mathcal{L}_{I_{g,h}}(\lambda) &= \int_0^\infty \exp(-\lambda y) \left(\int_{\{x: g(x) \leq y\}} h dx \right) dy \\ &= \int_{\mathbb{R}^n} h(x) \left(\int_{g(x)}^\infty \exp(-\lambda y) dy \right) dx \quad [\text{by Fubini}] \\ &= \frac{1}{\lambda} \int_{\mathbb{R}^n} h(x) \exp(-\lambda g(x)) dx \\ &= \frac{1}{\lambda^{1+(n+p)/d}} \int_{\mathbb{R}^n} h(z) \exp(-g(z)) dz \quad [\text{by homog}] \\ &= \frac{\int_{\mathbb{R}^n} h(z) \exp(-g(z)) dz}{\Gamma(1 + (n+p)/d)} \mathcal{L}_{y^{(n+p)/d}}(\lambda).\end{aligned}$$

And so, by analyticity and the Identity theorem of analytical functions

$$I_{g,h}(y) = \frac{y^{(n+p)/d}}{\Gamma(1 + (n+p)/d)} \int_{\mathbb{R}^n} h(x) \exp(-g(x)) dx,$$

II. Approximating a non gaussian integral

Hence computing the non Gaussian integral $\int \exp(-g) dx$

reduces to computing the **volume** of the **level set**

$$G := \{x : g(x) \leq 1\},$$

... which is the same as solving the optimization problem:

$$\begin{aligned} \max_{\mu} \quad & \mu(G) \\ \text{s.t.} \quad & \mu + \nu = \lambda \\ & \mu(\mathbf{B} \setminus G) = 0 \end{aligned}$$

where :

- \mathbf{B} is a box $[-a, a]^n$ containing G and
- λ is the Lebesgue measure.

II. Approximating a non gaussian integral

Hence computing the non Gaussian integral $\int \exp(-g) dx$

reduces to computing the **volume** of the **level set**

$$G := \{x : g(x) \leq 1\},$$

... which is the same as solving the optimization problem:

$$\begin{aligned} \max_{\mu} \quad & \mu(G) \\ \text{s.t.} \quad & \mu + \nu = \lambda \\ & \mu(\mathbf{B} \setminus G) = 0 \end{aligned}$$

where :

- \mathbf{B} is a box $[-a, a]^n$ containing G and
- λ is the Lebesgue measure.

... and we know how to

approximate as closely as desired $\mu(G)$ and any FIXED number of moments of μ , by solving an appropriate hierarchy of semidefinite programs (SDP).

(see: *Approximate volume and integration for basic semi algebraic sets*, Henrion, Lasserre and Savorgnan, SIAM Review 51, 2009.)

However ...

the resulting SDPs are numerically difficult to solve.

Solving the dual reduces to approximating the indicator function $I(G)$ by polynomials of increasing degrees \rightarrow Gibbs effect, etc.

... and we know how to

approximate as closely as desired $\mu(G)$ and any FIXED number of moments of μ , by solving an appropriate hierarchy of semidefinite programs (SDP).

(see: *Approximate volume and integration for basic semi algebraic sets*, Henrion, Lasserre and Savorgnan, SIAM Review 51, 2009.)

However ...

the resulting SDPs are numerically difficult to solve.

Solving the dual reduces to approximating the indicator function $I(G)$ by polynomials of increasing degrees \rightarrow Gibbs effect, etc.

Let $G \subseteq B := [-1, 1]^n$ (possibly after scaling), and let $z = (z_\alpha)$, $\alpha \in \mathbb{N}_{2k}^n$, be the moments of the Lebesgue measure λ on B .

Solve the hierarchy of semidefinite programs:

$$\begin{aligned} \rho_k = \max \quad & y_0 \\ \text{s.t.} \quad & \mathbf{M}_k(y), \mathbf{M}_k(v) \succeq 0, \\ & \mathbf{M}_{k-\lceil(d)/2\rceil}(gy) \succeq 0 \\ & \mathbf{M}_{k-1}((1-x_i^2)v) \succeq 0, \quad i = 1, \dots, n \\ & y_\alpha + v_\alpha = z_\alpha, \quad \alpha \in \mathbb{N}_{2k}^n \end{aligned}$$

for some moment and localizing matrices $\mathbf{M}_k(y)$ and $\mathbf{M}_k(g, y)$.

- The linear constraints $y_\alpha + v_\alpha = z_\alpha$ for all $\alpha \in \mathbb{N}_{2k}^n$ “ensure” $\mu + \nu = \lambda$, while the “ $\succeq 0$ ” constraints “ensure” $\text{supp } \mu = G$ and $\text{supp } \nu = B$.

Let $G \subseteq B := [-1, 1]^n$ (possibly after scaling), and let $z = (z_\alpha)$, $\alpha \in \mathbb{N}_{2k}^n$, be the moments of the Lebesgue measure λ on B .

Solve the hierarchy of semidefinite programs:

$$\begin{aligned} \rho_k = \max \quad & y_0 \\ \text{s.t.} \quad & \mathbf{M}_k(y), \mathbf{M}_k(v) \succeq 0, \\ & \mathbf{M}_{k-\lceil d/2 \rceil}(gy) \succeq 0 \\ & \mathbf{M}_{k-1}((1-x_i^2)v) \succeq 0, \quad i = 1, \dots, n \\ & y_\alpha + v_\alpha = z_\alpha, \quad \alpha \in \mathbb{N}_{2k}^n \end{aligned}$$

for some **moment** and **localizing** matrices $\mathbf{M}_k(y)$ and $\mathbf{M}_k(g, y)$.

- The linear constraints $y_\alpha + v_\alpha = z_\alpha$ for all $\alpha \in \mathbb{N}_{2k}^n$ “ensure” $\mu + \nu = \lambda$, while the “ $\succeq 0$ ” constraints “ensure” $\text{supp } \mu = G$ and $\text{supp } \nu = B$.

Another identity

Corollary

If g has degree d and G has finite volume then

$$\frac{\int_{\{x: g(x) \leq y\}} \exp(-g) dx}{\int_{\mathbb{R}^n} \exp(-g) dx} = \frac{\int_0^y t^{n/d-1} \exp(-t) dt}{\int_0^\infty t^{n/d-1} \exp(-t) dt} = \frac{\int_0^y t^{n/d-1} \exp(-t) dt}{\Gamma(n/d)}$$

expresses how fast $\mu(\{x : g(x) \leq y\})$ goes to $\mu(\mathbb{R}^n)$ as $y \rightarrow \infty$, for the Borel measure $d\mu = \exp(-g) dx$.

It is like for the Gamma function $\Gamma(n/d)$ when approximated by $\int_0^y t^{n/d-1} \exp(-t) dt$.

III. Convexity

An interesting issue is to analyze how the Lebesgue volume $\text{vol} \{x \in \mathbb{R}^n : g(x) \leq 1\}$, (i.e. $\text{vol}(G)$) changes with g .

Corollary

Let h be a PHF of degree p and let $C_d \subset \mathbb{R}[x]_d$ be the convex cone of homogeneous polynomials of degree at most d such that $\text{vol}(G)$ is finite. Then the function $f_h : C_d \rightarrow \mathbb{R}$,

$$g \mapsto f_h(g) := \int_G h \, dx, \quad g \in C_d,$$

- is a PHF of degree $-(n+p)/d$,
- **convex** whenever h is **nonnegative** and **strictly convex** if $h > 0$ on $\mathbb{R}^n \setminus \{0\}$

Corollary (continued)

Moreover, if h is continuous and $\int |h| \exp(-g) dx < \infty$ then:

$$\begin{aligned}\frac{\partial f_h(g)}{\partial g_\alpha} &= \frac{-1}{\Gamma(1 + (n+p)/d)} \int_{\mathbb{R}^n} x^\alpha h \exp(-g) dx \\ &= \frac{-\Gamma(2 + (n+p)/d)}{\Gamma(1 + (n+p)/d)} \int_G x^\alpha h dx \\ \frac{\partial^2 f_h(g)}{\partial g_\alpha \partial g_\beta} &= \frac{-1}{\Gamma(1 + (n+p)/d)} \int_{\mathbb{R}^n} x^{\alpha+\beta} h \exp(-g) dx\end{aligned}$$

PROOF: Just use

$$\int_{\{x: g(x) \leq 1\}} h \, dx = \frac{1}{\Gamma(1 + (n + p)/d)} \int_{\mathbb{R}^n} h \exp(-g) \, dx$$

Notice that proving convexity **directly** would be non trivial but becomes easy when using the previous lemma!

PROOF: Just use

$$\int_{\{x: g(x) \leq 1\}} h \, dx = \frac{1}{\Gamma(1 + (n + p)/d)} \int_{\mathbb{R}^n} h \exp(-g) \, dx$$

Notice that proving convexity **directly** would be non trivial but becomes easy when using the previous lemma!

III. Polarity

For a set $C \subset \mathbb{R}^n$, recall:

- The support function $x \mapsto \sigma_C(x) := \sup_y \{x^T y : y \in C\}$
- The POLAR $C^\circ := \{x \in \mathbb{R}^n : \sigma_C(x) \leq 1\}$
- and for a PHF g of degree d , its Legendre-Fenchel conjugate $g^*(x) = \sup_y \{x^T y - g(y)\}$ is a PHF of degree q with $\frac{1}{d} + \frac{1}{q} = 1$.

Lemma

Let g be a *closed proper convex PHF* of degree $1 < d$ and let $G = \{x : g(x) \leq 1/d\}$. Then:

$$G^\circ = \{x \in \mathbb{R}^n : g^*(x) \leq 1/q\}$$

$$\text{vol}(G) = \frac{p^{-n/p}}{\Gamma(1 + n/p)} \int \exp(-g) dx$$

$$\text{vol}(G^\circ) = \frac{q^{-n/q}}{\Gamma(1 + n/q)} \int \exp(-g^*) dx$$

→ yields completely symmetric formulas for g and its conjugate g^* .

Examples

- $g(x) = |x|^3$ so that $g^*(x) = \frac{2}{3\sqrt{3}}|x|^{3/2}$. And so

$$G = [-3^{-1/3}, 3^{-1/3}]; \quad G^\circ = [-3^{1/3}, 3^{1/3}].$$

- TV screen: $g(x) = x_1^4 + x_2^4$ so that $g^*(x) = 4^{-4/3}3(x_1^{4/3} + x_2^{4/3})$. And,

$$G = \{x : x_1^2 + x_2^4 \leq \frac{1}{4}\}; \quad G^\circ = \{x : x_1^{4/3} + x_2^{4/3} \leq 4^{1/3}\}.$$

- $g(x) = |x|$ so that $d \not\geq 1$, and $g^*(x) = 0$ if $x \in [-1, 1]$, and $+\infty$ otherwise. Hence $G = \{x : |x| \leq 1\} = [-1, 1]$ and with $q = +\infty$,

$$G^\circ = [-1, 1] = \{x : g^*(x) \leq \frac{1}{q} = 0\}.$$

IV. A variational property of homogeneous polynomials

Let $\mathbf{v}_d(x)$ be the vector of monomials (x^α) of degree d , i.e., such that $\alpha_1 + \dots + \alpha_n = d$. (And so $\mathbf{v}_1(x) = x$.)

If $g \in \mathbb{R}[x]_{2d}$ is homogeneous and SOS then

$$g(x) = \frac{1}{2} \mathbf{v}_d(x)^T \Sigma \mathbf{v}_d(x),$$

for some real symmetric positive semidefinite matrix $\Sigma \succeq 0$.

And if $d = 1$ one has the Gaussian property

$$\int_{\mathbb{R}^n} \exp(-g) dx = \frac{(2\pi)^{n/2}}{\sqrt{\det \Sigma}},$$
$$\frac{\int_{\mathbb{R}^n} \mathbf{v}_d(x) \mathbf{v}_d(x)^T \exp(-g) dx}{\int_{\mathbb{R}^n} \exp(-g) dx} = \Sigma^{-1}.$$

IV. A variational property of homogeneous polynomials

Let $\mathbf{v}_d(x)$ be the vector of monomials (x^α) of degree d , i.e., such that $\alpha_1 + \dots + \alpha_n = d$. (And so $\mathbf{v}_1(x) = x$.)

If $g \in \mathbb{R}[x]_{2d}$ is **homogeneous** and **SOS** then

$$g(x) = \frac{1}{2} \mathbf{v}_d(x)^T \Sigma \mathbf{v}_d(x),$$

for some real symmetric positive semidefinite matrix $\Sigma \succeq 0$.

And if $d = 1$ one has the **Gaussian** property

$$\int_{\mathbb{R}^n} \exp(-g) dx = \frac{(2\pi)^{n/2}}{\sqrt{\det \Sigma}},$$
$$\frac{\int_{\mathbb{R}^n} \mathbf{v}_d(x) \mathbf{v}_d(x)^T \exp(-g) dx}{\int_{\mathbb{R}^n} \exp(-g) dx} = \Sigma^{-1}.$$

In other words, if μ is the Gaussian measure

$$\mu(B) := \frac{\int_B \exp\left(-\frac{1}{2}x^T \Sigma x\right) dx}{\int_{\mathbb{R}^n} \exp\left(-\frac{1}{2}x^T \Sigma x\right) dx}, \quad \forall B,$$

then its (covariance) matrix of moments of order 2 satisfies:

$$\mathbf{M}_1(\Sigma) := \int_{\mathbb{R}^n} x x^T d\mu(x) = \Sigma^{-1},$$

and the function

$$\theta_1(\Sigma) := (\det \Sigma)^{1/2} \int_{\mathbb{R}^n} \exp\left(-\frac{1}{2}\mathbf{v}_1(x)^T \Sigma \mathbf{v}_1(x)\right) dx.$$

is constant!

... not true anymore for $d > 1$!

However, let $\ell(\mathbf{d}) = \binom{n+d-1}{d}$, and $\mathcal{S}_{++}^{\ell(\mathbf{d})}$ be the cone of real positive definite $\ell(\mathbf{d}) \times \ell(\mathbf{d})$ matrices. Let $k := n/(2d\ell(\mathbf{d}))$.

With $\Sigma \in \mathcal{S}_{++}^{\ell(\mathbf{d})}$, define the probability measure μ

$$\mu(B) := \frac{\int_B \exp\left(-k\mathbf{v}_d(x)^T \Sigma \mathbf{v}_d(x)\right) dx}{\int_{\mathbb{R}^n} \exp\left(-k\mathbf{v}_d(x)^T \Sigma \mathbf{v}_d(x)\right) dx}, \quad \forall B,$$

with matrix of moments of order $2d$ given by:

$$\mathbf{M}_d(\Sigma) := \int_{\mathbb{R}^n} \mathbf{v}_d(x) \mathbf{v}_d(x)^T d\mu(x).$$

Define $\theta_d : \mathcal{S}_{++}^{\ell(d)} \rightarrow \mathbb{R}$ to be the function

$$\Sigma \mapsto \theta_d(\Sigma) := (\det \Sigma)^k \int_{\mathbb{R}^n} \exp\left(-k \mathbf{v}_d(x)^T \Sigma \mathbf{v}_d(x)\right) dx.$$

Theorem

$$\mathbf{M}_d(\Sigma) = \Sigma^{-1} \iff \nabla \theta_d(\Sigma) = 0$$

Hence *critical points* Σ^* of θ_d have the Gaussian property

$$\frac{\int \mathbf{v}_d(x) \mathbf{v}_d(x)^T \exp\left(-k \mathbf{v}_d(x)^T \Sigma^* \mathbf{v}_d(x)\right) dx}{\int \exp\left(-k \mathbf{v}_d(x)^T \Sigma^* \mathbf{v}_d(x)\right) dx} = (\Sigma^*)^{-1}$$

- ★ If $d = 1$ then $\theta_d(\cdot)$ is constant and so $\nabla \theta_d(\cdot) = 0$.
- ★ If $d > 1$ then $\theta_d(\cdot)$ is constant in each ray $\lambda \Sigma$, $\lambda > 0$.

$$\begin{aligned}
 \nabla \theta_d(\Sigma) &= k \frac{\Sigma^A}{\det \Sigma} \theta_d(\Sigma) \\
 &\quad - k (\det \Sigma)^k \int_{\mathbb{R}^n} \mathbf{v}_d(x) \mathbf{v}_d(x)^T \exp\left(-k \mathbf{v}_d(x)^T \Sigma \mathbf{v}_d(x)\right) dx \\
 &= k \theta_d(\Sigma) \left[\Sigma^{-1} - \mathbf{M}_d(\Sigma) \right]
 \end{aligned}$$

and so

$$\mathbf{M}_d(\Sigma) = \Sigma^{-1} \quad \Rightarrow \quad \nabla \theta_d(\Sigma) = 0.$$

V. Sublevel sets G of minimum volume

If $\mathbf{K} \subset \mathbb{R}^n$ is compact then computing the **ellipsoid** ξ of minimum **volume** containing \mathbf{K} is a classical problem whose optimal solution is called the **Löwner-John** ellipsoid.
So consider the following problem:

*Find an **homogeneous** polynomial $g \in \mathbb{R}[x]_{2d}$ such that its sublevel set $G := \{x : g(x) \leq 1\}$ contains \mathbf{K} and has minimum volume among all such levels sets with this inclusion property.*

Let $\mathbf{P}[x]_{2d}$ be the convex cone of homogeneous polynomials of degree $2d$ whose sub-level set $\mathbf{G} = \{x : g(x) \leq 1\}$ has **finite Lebesgue volume** and with $\mathbf{K} \subset \mathbb{R}^n$, let $C_{2d}(\mathbf{K})$ be the convex cone of polynomials nonnegative on \mathbf{K} .

Lemma

Let $\mathbf{K} \subset \mathbb{R}^n$ be compact. The **minimum volume** of a sublevel set $\mathbf{G} = \{x : g(x) \leq 1\}$, $g \in \mathbf{P}[x]_{2d}$, that contains $\mathbf{K} \subset \mathbb{R}^n$ is $\rho/\Gamma(1 + n/2d)$ where:

$$\mathcal{P} : \quad \rho = \inf_{g \in \mathbf{P}[x]_{2d}} \left\{ \int_{\mathbb{R}^n} \exp(-g) dx : 1 - g \in C_{2d}(\mathbf{K}) \right\}.$$

a **finite-dimensional convex optimization problem!**

Let $\mathbf{P}[x]_{2d}$ be the convex cone of homogeneous polynomials of degree $2d$ whose sub-level set $\mathbf{G} = \{x : g(x) \leq 1\}$ has **finite Lebesgue volume** and with $\mathbf{K} \subset \mathbb{R}^n$, let $C_{2d}(\mathbf{K})$ be the convex cone of polynomials nonnegative on \mathbf{K} .

Lemma

Let $\mathbf{K} \subset \mathbb{R}^n$ be compact. The **minimum volume** of a sublevel set $\mathbf{G} = \{\mathbf{x} : g(\mathbf{x}) \leq 1\}$, $g \in \mathbf{P}[x]_{2d}$, that contains $\mathbf{K} \subset \mathbb{R}^n$ is $\rho/\Gamma(1 + n/2d)$ where:

$$\mathcal{P} : \quad \rho = \inf_{g \in \mathbf{P}[x]_{2d}} \left\{ \int_{\mathbb{R}^n} \exp(-g) dx : 1 - g \in C_{2d}(\mathbf{K}) \right\}.$$

a **finite-dimensional convex optimization problem!**

- We have seen that:

$$\text{vol}(\{x : g(x) \leq 1\}) = \frac{1}{\Gamma(1 + n/2d)} \int_{\mathbb{R}^n} \exp(-g) dx.$$

Moreover, the sub-level set $\{x : g(x) \leq 1\}$ contains \mathbf{K} if and only if $1 - g \in C_{2d}(\mathbf{K})$, and so $\rho/\Gamma(1 + n/2d)$ is the minimum value of all volumes of sub-levels sets $\{x : g(x) \leq 1\}$, $g \in \mathbf{P}[\mathbf{x}]_{2d}$, that contain \mathbf{K} .

- Now since $g \mapsto \int_{\mathbb{R}^n} \exp(-g) dx$ is strictly convex and $C_{2d}(\mathbf{K})$ is a convex cone, problem \mathcal{P} is a finite-dimensional convex optimization problem. \square

V (continued). Characterizing an optimal solution

Theorem

(a) \mathcal{P} has a unique optimal solution $g^* \in \mathbf{P}[x]_{2d}$ and there exists a Borel measure μ^* supported on \mathbf{K} such that:

$$(*) : \begin{cases} \int_{\mathbb{R}^n} x^\alpha \exp(-g^*) dx = \int_{\mathbf{K}} x^\alpha d\mu^*, & \forall |\alpha| = 2d \\ \int_{\mathbf{K}} (1 - g^*) d\mu^* = 0 \end{cases}$$

In particular, μ^* is supported on the real variety

$V := \{x \in \mathbf{K} : g^*(x) = 1\}$ and in fact, μ^* can be substituted with another measure ν^* supported on at most $\binom{n+2d-1}{2d}$ points of V .

(b) Conversely, if $g^* \in \mathbf{P}[x]_{2d}$ and μ^* satisfy (*) then g^* is an optimal solution of \mathcal{P} .

V (continued). Characterizing an optimal solution

Theorem

(a) \mathcal{P} has a unique optimal solution $g^* \in \mathbf{P}[x]_{2d}$ and there exists a Borel measure μ^* supported on \mathbf{K} such that:

$$(*) : \begin{cases} \int_{\mathbb{R}^n} x^\alpha \exp(-g^*) dx = \int_{\mathbf{K}} x^\alpha d\mu^*, & \forall |\alpha| = 2d \\ \int_{\mathbf{K}} (1 - g^*) d\mu^* = 0 \end{cases}$$

In particular, μ^* is supported on the real variety

$V := \{x \in \mathbf{K} : g^*(x) = 1\}$ and in fact, μ^* can be substituted with another measure ν^* supported on at most $\binom{n+2d-1}{2d}$ points of V .

(b) Conversely, if $g^* \in \mathbf{P}[x]_{2d}$ and μ^* satisfy (*) then g^* is an optimal solution of \mathcal{P} .

Example

Let $\mathbf{K} \subset \mathbb{R}^2$ be the box $[-1, 1]^2$.

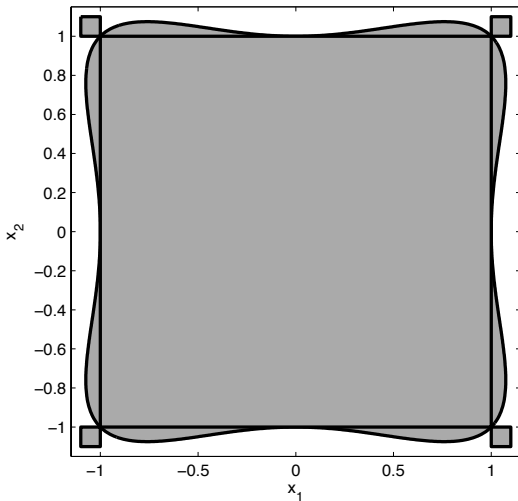
The set $\mathbf{G}_4 := \{\mathbf{x} : g(\mathbf{x}) \leq 1\}$ with g homogeneous of degree 4 which contains \mathbf{K} and has minimum volume is

$$\mathbf{x} \mapsto g_4(\mathbf{x}) := x_1^4 + y_1^4 - x_1^2 x_2^2,$$

with $\text{vol}(\mathbf{G}_4) \approx 4.39$ much better than

- $\pi R^2 = 2\pi \approx 6.28$ for the Löwner-John ellipsoid of minimum volume, and

- the (convex) TV screen $\mathbf{G} := \{\mathbf{x} : (x_1^4 + x_2^4)/2 \leq 1\}$ with volume > 5 .



Example (continued)

Let $\mathbf{K} \subset \mathbb{R}^2$ be the box $[-1, 1]^2$.

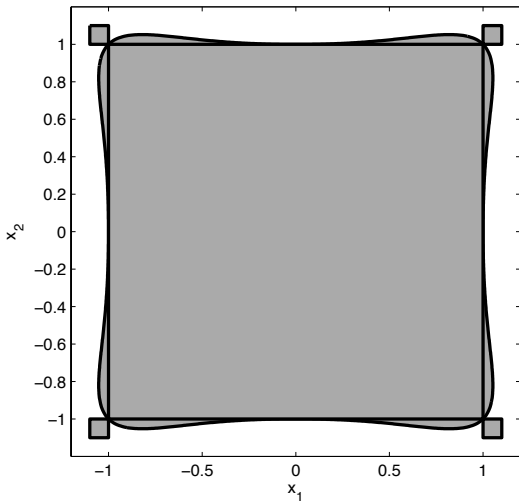
The set $\mathbf{G}_6 := \{\mathbf{x} : g(\mathbf{x}) \leq 1\}$ with g homogeneous of degree 6 which contains \mathbf{K} and has minimum volume is

$$\mathbf{x} \mapsto g_6(\mathbf{x}) := x_1^6 + y_1^6 - (x_1^4 x_2^2 + x_1^2 x_2^4)/2,$$

with $\text{vol}(\mathbf{G}_6) \approx 4.19$ much better than

- $\pi R^2 = 2\pi \approx 6.28$ for the Löwner-John ellipsoid of minimum volume, and

- better than the set \mathbf{G}_4 with volume 4.39.



VI. Recovering g from moments of G

Write $g(x) = \sum_{\beta} g_{\beta} x^{\beta}$.

Lemma

If g is nonnegative and d -homogeneous with G compact then:

$$\underbrace{\int_G x^{\alpha} g(x) dx}_{\sum_{\beta} g_{\beta} y_{\alpha+\beta}} = \frac{n + |\alpha|}{n + d + |\alpha|} \underbrace{\int_G x^{\alpha} dx}_{y_{\alpha}}, \quad \alpha \in \mathbb{N}^n.$$

and so we see that the moments (y_{α}) satisfy **linear relationships** explicit in terms of the coefficients of the polynomial g that describes the boundary of G .

So let us write $\mathbf{g} \in \mathbb{R}^{s(d)}$ the **unknown** vector of coefficients of the unknown polynomial g .

Let $\mathbf{M}_d(\mathbf{y})$ be the **moment matrix** of order d whose rows and columns are indexed in the canonical basis of monomials (x^α) , $\alpha \in \mathbb{N}_d^n$, and with entries

$$\mathbf{M}_d(\mathbf{y})(\alpha, \beta) = y_{\alpha+\beta}, \quad \alpha, \beta \in \mathbb{N}_d^n.$$

and let \mathbf{y}^d be the vector (y_α) , $\alpha \in \mathbb{N}_d^n$.

Previous Lemma states that

$$\mathbf{M}_d(\mathbf{y}) \mathbf{g} = \mathbf{y}^d,$$

or, equivalently,

$$\mathbf{g} = \mathbf{M}_d(\mathbf{y})^{-1} \mathbf{y}^d,$$

because the moment matrix $\mathbf{M}_d(\mathbf{y})$ is nonsingular whenever G has nonempty interior.

In other words ...

one may recover g EXACTLY from knowledge of moments (y_α)
of order d and $2d$!

Non homogeneous polynomials

If g is not quasi-homogeneous then one cannot directly relate

$$\int_{\{\mathbf{x}:g(\mathbf{x})\leq 1\}} d\mathbf{x} \quad \text{and} \quad \int_{\mathbb{R}^n} \exp(-g(\mathbf{x})) d\mathbf{x}.$$

But still the Laplace transform $\lambda \mapsto F(\lambda)$ of the function

$$y \mapsto f(y) := \int_{\{\mathbf{x}:|g(\mathbf{x})|\leq y\}} d\mathbf{x}$$

is the non Gaussian integral

$$\lambda \mapsto F(\lambda) = \frac{1}{\lambda} \int_{\mathbb{R}^n} \exp(-\lambda |g(\mathbf{x})|) d\mathbf{x}.$$

Nice asymptotic results are available (Vassiliev)

$$f(y) \approx y^a \ln(y)^b, \quad \text{as } y \rightarrow \infty$$

for some rationals a , b obtained from the Newton polytope of g .

One even has asymptotic results for

$$y \mapsto \tilde{f}(y) := \# (\{\mathbf{x} : |g(\mathbf{x})| \leq y\} \cap \mathbf{Z}^n), \quad \text{as } y \rightarrow \infty$$

still in the form

$$\tilde{f}(y) \approx y^{a'} \ln(y)^{b'}, \quad \text{as } y \rightarrow \infty$$

for some rationals a' , b' obtained from the (modified) Newton polytope of g .

Exact recovery

Given a polynomial $g \in \mathbb{R}[\mathbf{x}]_d$ write $g(\mathbf{x}) = \sum_{k=0}^d g_k(\mathbf{x})$, where each g_k is homogeneous of degree k .

Lemma

Let $g \in \mathbb{R}[\mathbf{x}]_d$ be such that its level set $\mathbf{G} := \{\mathbf{x} : g(\mathbf{x}) \leq 1\}$ is bounded. Then for every $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$:

$$\int_{\mathbf{G}} \mathbf{x}^\alpha (1 - g(\mathbf{x})) \, d\mathbf{x} = \sum_{k=1}^d \frac{k}{n + |\alpha|} \int_{\mathbf{G}} \mathbf{x}^\alpha g_k(\mathbf{x}) \, d\mathbf{x}$$

Observe that for each fixed arbitrary $\alpha \in \mathbb{N}^n$...

One obtains **LINEAR EQUALITIES** between **MOMENTS** of the Lebesgue measure on \mathbf{G} !

Exact recovery

Given a polynomial $g \in \mathbb{R}[\mathbf{x}]_d$ write $g(\mathbf{x}) = \sum_{k=0}^d g_k(\mathbf{x})$, where each g_k is homogeneous of degree k .

Lemma

Let $g \in \mathbb{R}[\mathbf{x}]_d$ be such that its level set $\mathbf{G} := \{\mathbf{x} : g(\mathbf{x}) \leq 1\}$ is bounded. Then for every $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$:

$$\int_{\mathbf{G}} \mathbf{x}^\alpha (1 - g(\mathbf{x})) \, d\mathbf{x} = \sum_{k=1}^d \frac{k}{n + |\alpha|} \int_{\mathbf{G}} \mathbf{x}^\alpha g_k(\mathbf{x}) \, d\mathbf{x}$$

Observe that for each fixed arbitrary $\alpha \in \mathbb{N}^n$...

One obtains **LINEAR EQUALITIES** between **MOMENTS** of the Lebesgue measure on \mathbf{G} !

Proof:

- Use Stokes' formula

$$\int_{\mathbf{G}} \operatorname{Div}(X) f(\mathbf{x}) d\mathbf{x} + \int_{\mathbf{G}} \langle X, \nabla f(\mathbf{x}) \rangle d\mathbf{x} = \int_{\partial \mathbf{G}} \langle X, \vec{n}_{\mathbf{x}} \rangle f d\sigma,$$

with vector field $X = \mathbf{x}$ and $f(\mathbf{x}) = \mathbf{x}^\alpha (1 - g(\mathbf{x}))$.

- Then observe that $\operatorname{Div}(X) = n$ and:

$$\langle X, \nabla f(\mathbf{x}) \rangle = |\alpha| f - \mathbf{x}^\alpha \sum_{k=1}^d k g_k(\mathbf{x}).$$

★ In the general case, when $\partial \mathbf{G}$ may have singular points, or lower dimensional components, we can invoke Sard's theorem, for the (smooth) sublevel sets

$$G_\gamma = \{ \mathbf{x} : g(\mathbf{x}) < \gamma \}$$

and pass to the limit $\gamma \rightarrow 1$, $\gamma < 1$. \square

Proof:

- Use Stokes' formula

$$\int_{\mathbf{G}} \operatorname{Div}(X) f(\mathbf{x}) d\mathbf{x} + \int_{\mathbf{G}} \langle X, \nabla f(\mathbf{x}) \rangle d\mathbf{x} = \int_{\partial \mathbf{G}} \langle X, \vec{n}_{\mathbf{x}} \rangle f d\sigma,$$

with vector field $X = \mathbf{x}$ and $f(\mathbf{x}) = \mathbf{x}^\alpha (1 - g(\mathbf{x}))$.

- Then observe that $\operatorname{Div}(X) = n$ and:

$$\langle X, \nabla f(\mathbf{x}) \rangle = |\alpha| f - \mathbf{x}^\alpha \sum_{k=1}^d k g_k(\mathbf{x}).$$

★ In the general case, when $\partial \mathbf{G}$ may have singular points, or lower dimensional components, we can invoke Sard's theorem, for the (smooth) sublevel sets

$$G_\gamma = \{ \mathbf{x} : g(\mathbf{x}) < \gamma \}$$

and pass to the limit $\gamma \rightarrow 1$, $\gamma < 1$. \square

Let $\mathbf{G} \subset \mathbb{R}^n$ be open with $\mathbf{G} = \text{int } \overline{\mathbf{G}}$ and with real algebraic boundary $\partial\mathbf{G}$. A polynomial of degree d vanishes on $\partial\mathbf{G}$.

Define a renormalised moment-type matrix $\mathbf{M}_k^d(\mathbf{y})$ as follows:

- $s(d) (= \binom{n+d}{n})$ columns indexed by $\beta \in \mathbb{N}_d^n$,
 - countably many rows indexed by $\alpha \in \mathbb{N}_k^n$,
- and with entries:

$$\mathbf{M}_k^d(\mathbf{y})(\alpha, \beta) := \frac{n + |\alpha| + |\beta|}{n + |\alpha|} y_{\alpha+\beta}, \quad \alpha \in \mathbb{N}_k^n, \beta \in \mathbb{N}_d^n.$$

Theorem

Let $\mathbf{G} \subset \mathbb{R}^n$ be a bounded open set with real algebraic boundary. Assume that $\mathbf{G} = \text{int } \overline{\mathbf{G}}$ and a polynomial of degree d vanishes on $\partial\mathbf{G}$ and not at 0. Then the linear system

$$\mathbf{M}_{2d}^d(\mathbf{y}) \begin{bmatrix} -1 \\ \mathbf{g} \end{bmatrix} = 0,$$

admits a *unique* solution $\mathbf{g} \in \mathbb{R}^{s(d)-1}$, and the polynomial g with coefficients $(0, \mathbf{g})$ satisfies

$$(\mathbf{x} \in \partial\mathbf{G}) \Rightarrow (g(\mathbf{x}) = 1).$$

Sketch of the proof

The identity (obtained from Stokes' theorem)

$$\int_{\mathbf{G}} \mathbf{x}^\alpha (1 - \mathbf{g}(\mathbf{x})) d\mathbf{x} = \sum_{k=1}^d \frac{k}{n + |\alpha|} \int_{\mathbf{G}} \mathbf{x}^\alpha g_k(\mathbf{x}) d\mathbf{x}$$

for all $\alpha \in \mathbb{N}_k^n$

in fact reads:

$$\mathbf{M}_k^d(\mathbf{y}) \begin{bmatrix} -1 \\ \mathbf{g} \end{bmatrix} = 0,$$

Conversely, if \mathbf{g} solves

$$\mathbf{M}_{2d}^d(\mathbf{y}) \begin{bmatrix} -1 \\ \mathbf{g} \end{bmatrix} = 0,$$

then

$$\int_{\partial \mathbf{G}} \langle \mathbf{x}, \vec{n}_{\mathbf{x}} \rangle (1 - \mathbf{g}(\mathbf{x})) \mathbf{x}^\alpha d\sigma = 0, \quad \forall \alpha \in \mathbb{N}_{2d}^n.$$

Sketch of the proof

The identity (obtained from Stokes' theorem)

$$\int_{\mathbf{G}} \mathbf{x}^\alpha (1 - \mathbf{g}(\mathbf{x})) d\mathbf{x} = \sum_{k=1}^d \frac{k}{n + |\alpha|} \int_{\mathbf{G}} \mathbf{x}^\alpha g_k(\mathbf{x}) d\mathbf{x}$$

for all $\alpha \in \mathbb{N}_k^n$

in fact reads:

$$\mathbf{M}_k^d(\mathbf{y}) \begin{bmatrix} -1 \\ \mathbf{g} \end{bmatrix} = 0,$$

Conversely, if \mathbf{g} solves

$$\mathbf{M}_{2d}^d(\mathbf{y}) \begin{bmatrix} -1 \\ \mathbf{g} \end{bmatrix} = 0,$$

then

$$\int_{\partial \mathbf{G}} \langle \mathbf{x}, \vec{n}_{\mathbf{x}} \rangle (1 - \mathbf{g}(\mathbf{x})) \mathbf{x}^\alpha d\sigma = 0, \quad \forall \alpha \in \mathbb{N}_{2d}^n.$$

As $\partial \mathbf{G}$ is algebraic, one may write

$$\vec{n}_{\mathbf{x}} = \frac{\nabla h(\mathbf{x})}{\|\nabla h(\mathbf{x})\|},$$

for some polynomial h . Therefore

$$\begin{aligned} 0 &= \int_{\partial \mathbf{G}} \langle \mathbf{x}, \vec{n}_{\mathbf{x}} \rangle (1 - g(\mathbf{x})) \mathbf{x}^\alpha d\sigma \quad \forall \alpha \in \mathbb{N}_{2d}^n \\ &= \int_{\partial \mathbf{G}} \underbrace{\langle \mathbf{x}, \nabla h(\mathbf{x}) \rangle}_{\in \mathbb{R}[\mathbf{x}]_d} \underbrace{(1 - g(\mathbf{x}))}_{\in \mathbb{R}[\mathbf{x}]_d} \mathbf{x}^\alpha \underbrace{\frac{1}{\|\nabla h\|} d\sigma}_{d\sigma'} \quad \forall \alpha \in \mathbb{N}_{2d}^n \\ &\Rightarrow \int_{\partial \mathbf{G}} \underbrace{\langle \mathbf{x}, \nabla h(\mathbf{x}) \rangle^2}_{\neq 0 \text{ } \sigma\text{-a.e.}} (1 - g(\mathbf{x}))^2 d\sigma' = 0 \quad \square \end{aligned}$$

As $\partial\mathbf{G}$ is algebraic, one may write

$$\vec{n}_{\mathbf{x}} = \frac{\nabla h(\mathbf{x})}{\|\nabla h(\mathbf{x})\|},$$

for some polynomial h . Therefore

$$\begin{aligned} 0 &= \int_{\partial\mathbf{G}} \langle \mathbf{x}, \vec{n}_{\mathbf{x}} \rangle (1 - g(\mathbf{x})) \mathbf{x}^\alpha d\sigma \quad \forall \alpha \in \mathbb{N}_{2d}^n \\ &= \int_{\partial\mathbf{G}} \underbrace{\langle \mathbf{x}, \nabla h(\mathbf{x}) \rangle}_{\in \mathbb{R}[\mathbf{x}]_d} \underbrace{(1 - g(\mathbf{x}))}_{\in \mathbb{R}[\mathbf{x}]_d} \mathbf{x}^\alpha \underbrace{\frac{1}{\|\nabla h\|} d\sigma}_{d\sigma'} \quad \forall \alpha \in \mathbb{N}_{2d}^n \\ &\Rightarrow \int_{\partial\mathbf{G}} \underbrace{\langle \mathbf{x}, \nabla h(\mathbf{x}) \rangle^2}_{\neq 0 \text{ } \sigma\text{-a.e.}} (1 - g(\mathbf{x}))^2 d\sigma' = 0 \quad \square \end{aligned}$$

For sake of rigor the boundary $\partial\mathbf{G}$ can be written

$$\partial\mathbf{G} = Z_0 \cup Z_1,$$

with Z_0 being a finite union of smooth $n - 1$ -submanifolds of \mathbb{R}^n leaving \mathbf{G} on one side, Z_1 is a union of the lower dimensional strata, and $\sigma(Z_1) = 0$.

Theorem

Let $\mathbf{G} \subset \mathbb{R}^n$ be a bounded *convex* open set with real algebraic boundary. Assume that $\mathbf{G} = \text{int } \overline{\mathbf{G}}$, $0 \in \mathbf{G}$, and a polynomial of degree d vanishes on $\partial \mathbf{G}$ and not at 0. Then the linear system

$$\mathbf{M}_d^d(\mathbf{y}) \begin{bmatrix} -1 \\ \mathbf{g} \end{bmatrix} = 0,$$

admits a unique solution $\mathbf{g} \in \mathbb{R}^{s(d)-1}$, and the polynomial g with coefficients $(0, \mathbf{g})$ satisfies

$$(\mathbf{x} \in \partial \mathbf{G}) \Rightarrow (g(\mathbf{x}) = 1).$$

★ As in the previous proof, if

$$\mathbf{M}_d^d(\mathbf{y}) \begin{bmatrix} -1 \\ g \end{bmatrix} = 0,$$

then

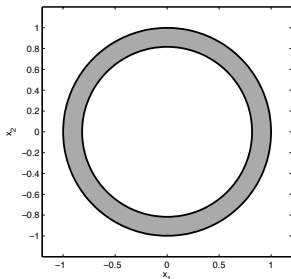
$$\int_{\partial \mathbf{G}} \langle \mathbf{x}, \vec{n}_{\mathbf{x}} \rangle (1 - g(\mathbf{x}))^2 d\sigma = 0.$$

But one now uses that if $0 \in \mathbf{G}$ then $\langle \mathbf{x}, \vec{n}_{\mathbf{x}} \rangle \geq 0$.

Example

Let us consider the two-dimensional example of the annulus

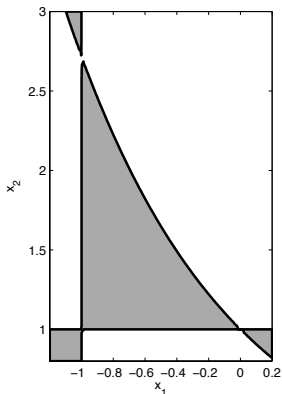
$$\mathbf{G} := \{ \mathbf{x} \in \mathbb{R}^2 : 1 - x_1^2 - x_2^2 \geq 0; x_1^2 + x_2^2 - 2/3 \geq 0 \}.$$



The polynomial $(1 - x_1^2 - x_2^2)(x_1^2 + x_2^2 - 2/3)$ is the unique solution of $\mathbf{M}_4^4(\mathbf{y})[-1, \mathbf{g}] = 0$.

Example continued: Non-algebraic boundary

Let $\mathbf{G} = \{\mathbf{x} \in \mathbb{R}^2 : x_1 \geq -1; x_2 \geq 1; x_2 \leq \exp(-x_1)\}$.



We now look as the eigenvector g of the smallest eigenvalue of $\mathbf{M}_3^3(y)$.

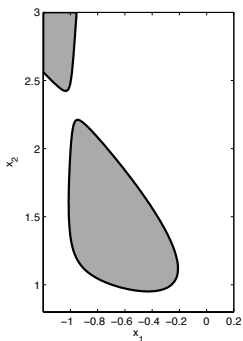


Figure: Shape $\mathbf{G}' = \{\mathbf{x} : g(\mathbf{x}) \leq 0\}$ with $d = 3$

We now look at the eigenvector g of the smallest eigenvalue of $\mathbf{M}_4^4(y)$.

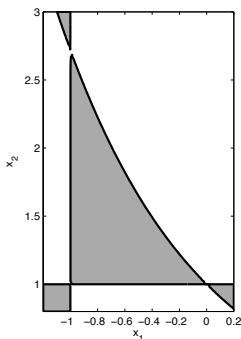


Figure: Shape $\mathbf{G}' = \{\mathbf{x} : g(\mathbf{x}) \leq 0\}$ with $d = 4$

A consequence in Probability

Consider the Probability measure μ

uniformly supported on a set G of the form $\{\mathbf{x} : g(\mathbf{x}) \leq 1\}$, for some polynomial $g \in \mathbb{R}[\mathbf{x}]_d$.

Then :

- **ALL** moments $y_\alpha := \int_G \mathbf{x}^\alpha d\mu$, $\alpha \in \mathbb{N}^n$, are determined from those up to order $3d$ (and $2d$ if G is convex) !
 - A similar result holds true if now μ has a density $\exp(h(\mathbf{x}))$ on G (for some $h \in \mathbb{R}[\mathbf{x}]$).

→ is an extension to such measures of a well-known result for **exponential families**

A consequence in Probability

Consider the Probability measure μ

uniformly supported on a set G of the form $\{\mathbf{x} : g(\mathbf{x}) \leq 1\}$, for some polynomial $g \in \mathbb{R}[\mathbf{x}]_d$.

Then :

- **ALL** moments $y_\alpha := \int_G \mathbf{x}^\alpha d\mu$, $\alpha \in \mathbb{N}^n$, are determined from those up to order $3d$ (and $2d$ if G is convex) !
 - A similar result holds true if now μ has a density $\exp(h(\mathbf{x}))$ on G (for some $h \in \mathbb{R}[\mathbf{x}]$).

→ is an extension to such measures of a well-known result for **exponential families**

A consequence in Probability

Consider the Probability measure μ

uniformly supported on a set G of the form $\{\mathbf{x} : g(\mathbf{x}) \leq 1\}$, for some polynomial $g \in \mathbb{R}[\mathbf{x}]_d$.

Then :

- **ALL** moments $y_\alpha := \int_G \mathbf{x}^\alpha d\mu$, $\alpha \in \mathbb{N}^n$, are determined from those up to order $3d$ (and $2d$ if G is convex) !
 - A similar result holds true if now μ has a density $\exp(h(\mathbf{x}))$ on G (for some $h \in \mathbb{R}[\mathbf{x}]$).

→ is an extension to such measures of a well-known result for **exponential families**

A consequence in Probability

Consider the Probability measure μ

uniformly supported on a set G of the form $\{\mathbf{x} : g(\mathbf{x}) \leq 1\}$, for some polynomial $g \in \mathbb{R}[\mathbf{x}]_d$.

Then :

- **ALL** moments $y_\alpha := \int_G \mathbf{x}^\alpha d\mu$, $\alpha \in \mathbb{N}^n$, are determined from those up to order $3d$ (and $2d$ if G is convex) !
 - A similar result holds true if now μ has a density $\exp(h(\mathbf{x}))$ on G (for some $h \in \mathbb{R}[\mathbf{x}]$).

→ is an extension to such measures of a well-known result for **exponential families**

Conclusion

- Compact **sub-level sets** $G := \{x : g(x) \leq y\}$ of **homogeneous polynomials** exhibit surprising properties. E.g.:
 - **convexity** of $\text{volume}(G)$ with respect to the coefficients of g
 - **Integrating** a PHF h on G reduce to evaluating the non Gaussian integral $\int h \exp(-g) dx$
 - A variational property yields a Gaussian-like property
 - exact recovery of G from finitely moments.
(Also works for **quasi-homogeneous** polynomials with bounded sublevel sets!)
 - exact recovery for sets with algebraic boundary of known degree

- **COMPUTATION!**: Efficient evaluation of $\int_{\mathbb{R}^n} \exp(-g) dx$, or equivalently, evaluation of $\text{vol}(\{x : g(x) \leq 1\})!$
- The property

$$\int_G \mathbf{x}^\alpha g(x) dx = \frac{n + |\alpha|}{n + d + |\alpha|} \int_G x^\alpha dx, \quad \forall \alpha,$$

helps a lot to improve efficiency of the method in **Henrion, Lasserre and Savorgnan** (SIAM Review)

Some references

- J.B. Lasserre. A Generalization of Löwner-John's ellipsoid Theorem. *Math. Program.*, to appear.
- J.B. Lasserre. Recovering an homogeneous polynomial from moments of its level set. *Discrete & Comput. Geom.* **50**, pp. 673–678, 2013.
- J.B. Lasserre and M. Putinar. Reconstruction of algebraic-exponential data from moments. Submitted
- J.B. Lasserre. Unit balls of constant volume: which one has optimal representation? submitted.

THANK YOU!