

# On the critical point method and deciding connectivity queries in real algebraic sets: from theory to practice

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# Polynomial system solving over the reals: what can exact computation do nowadays?

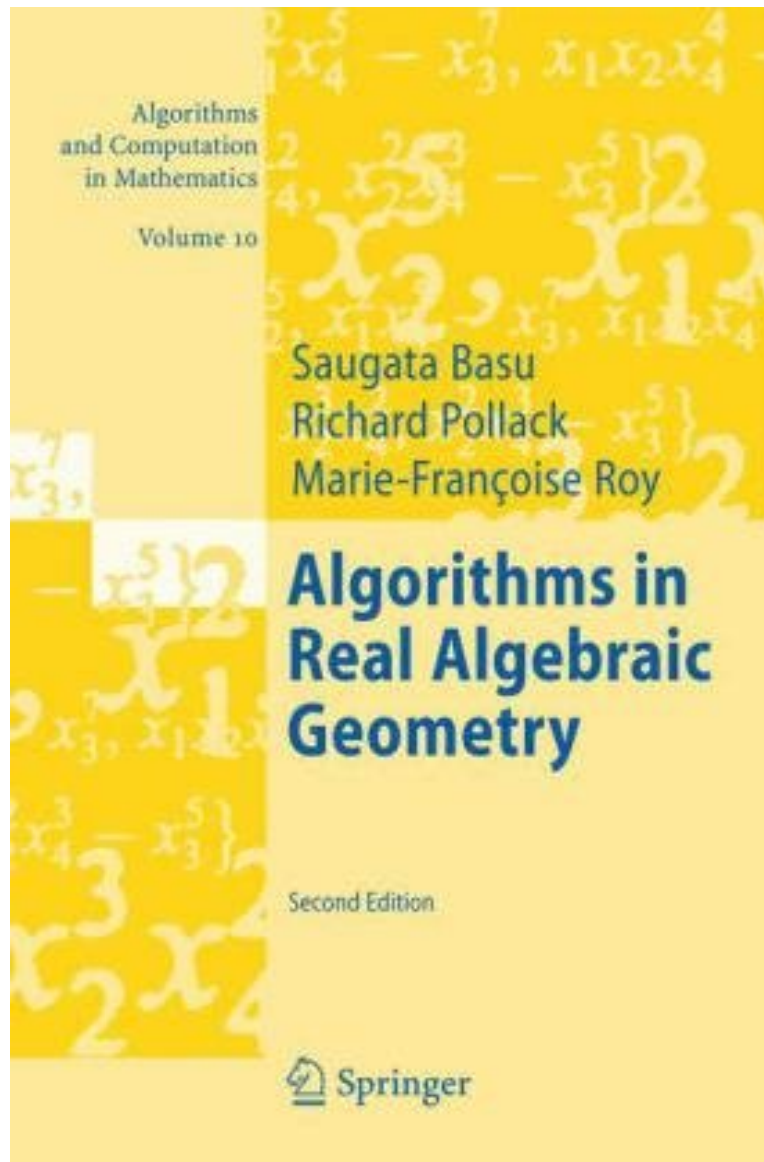
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**NOT** in this talk

- ▷ Univariate problems / zero-dimensional problems.
- ▷ Cylindrical Algebraic Decomposition of real solution sets.
- ▷ Certificates of positivity.  
*Peyrl/Parillo, Kaltofen/Yang/Zhi*

We will focus on Chap. 13 → 16.

# Real Algebraic Geometry and some Applications

Basic objects.

$$F_1 = \cdots = F_p = 0, \quad G_1 > 0, \dots, G_s > 0$$

in  $\mathbb{Q}[X_1, \dots, X_n]$  of degree  $\leq D$

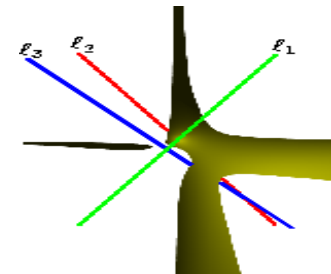
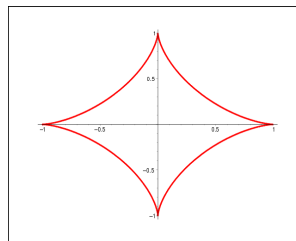
→ semi-algebraic set  $S$  in  $\mathbb{R}^n$

Existence of real solutions?

Projection of  $S$  on  $X_1, \dots, X_r$

Topological informations (connectivity, dimension, etc.)

Need of fast and reliable software – complexity estimates



## State-of-the-art and what we want to do

**Collins** ~ 70's Cylindrical algebraic decomposition – doubly exponential in  $n$

Hong, McCallum, Arnon, Brown, Strzebonski, Anai, Sturm, Weispfenning

**Software:** QEPCAD, Redlog, SyNRAC, Mathematica, Maple, ...

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▷ Quest for algorithms **singly exponential** in the number of variables

Grigoriev/Vorobjov, Canny, Renegar, Heintz/Roy/Solerno, Basu/Pollack/Roy

**Existence**  $D^{O(n)}$

**Dimension**  $D^{O(n \dim)}$

**Connectivity**  $D^{O(n^2)}$

▷ **Primary goal: obtain fast and reliable software**

▷ Better understanding of the complexity → **constant in the exponent?**

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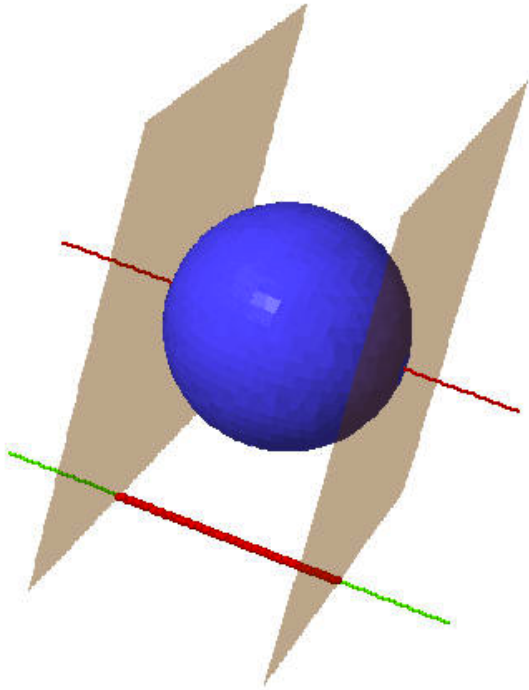
<b>Existence</b>	$D^{O(n)}$	$\sim O(\delta^3)$ (regular systems) else $\sim O(\delta^4)$ with $\delta = D^p(D-1)^{n-p} \binom{n-1}{p-1}$	
<b>Dimension</b>	$D^{O(n \dim)}$	$\sim O(D^{4n \dim}) \rightsquigarrow$ hypersurfaces	Bannwarth/S.
<b>Connectivity</b>	$D^{O(n^2)}$		

**Software: RAGlib**

▷ **Primary goal: obtain fast and reliable software**

▷ Better understanding of the complexity  $\rightarrow$  **constant in the exponent?**

# Critical Point Method: Basic Ideas



Reduction of the dimension  
through Global Optimization

## Properties of Critical Points

Vorobjov, Renegar, Gournay/Risler,  
Heintz/Roy/Solerno, Basu/Pollack/Roy 96

- ▷ **Existence:** from  $n$ -variate to univariate problems.

$$q(T) = 0, \quad X_i = q_i(T)/q_0(T), \quad (1 \leq i \leq n)$$

- ▷ **One-block quantifier elimination.**

$$q(Y_1, \dots, Y_r, T) = 0, \quad X_i = q_i(Y_1, \dots, Y_r, T)/q_0(Y_1, \dots, Y_r, T)$$

- ▷ **Connectivity queries:** reduction to the curve case.

$$q(U, T) = 0, \quad X_i = q_i(U, T)/q_0(U, T)$$

# Polar varieties – definition

Todd/Severi  $\sim$  30's – Piene/Teissier  $\sim$  75's

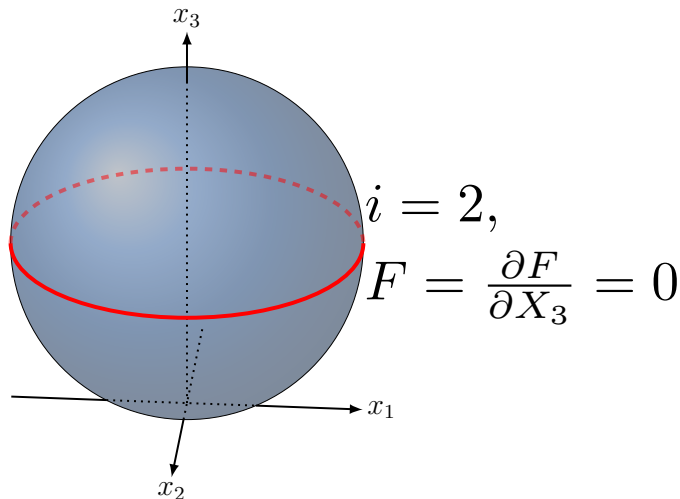
For  $1 \leq i \leq n$ , let  $\pi_i : (\mathbf{x}_1, \dots, \mathbf{x}_n) \rightarrow (\mathbf{x}_1, \dots, \mathbf{x}_i)$

**Polar variety  $W_i$  associated to  $\pi_i$  and  $V(F_1, \dots, F_p)$**

$$F_1 = \dots = F_p = 0 \quad \text{and} \quad \text{rank} \left( \begin{bmatrix} \frac{\partial F_1}{\partial X_{i+1}} & \dots & \dots & \frac{\partial F_1}{\partial X_n} \\ \frac{\partial F_2}{\partial X_{i+1}} & \dots & \dots & \frac{\partial F_2}{\partial X_n} \\ \vdots & & & \vdots \\ \frac{\partial F_p}{\partial X_{i+1}} & \dots & \dots & \frac{\partial F_p}{\partial X_n} \end{bmatrix} \right) \leq p - 1$$

**Example:**  $F_1 = X_1^2 + X_2^2 + X_3^2 - 1$

## Modelings



- ▷ Minors of the truncated jacobian matrix  $\rightsquigarrow$  **Determinantal modeling**
- ▷ Linearly independent vectors in the kernel  $\rightsquigarrow$  **Lagrange system**

$$\mathbf{F} = 0, \quad \Lambda \cdot \text{jac}(\mathbf{F}, 1) = \mathbf{0}, \quad \mathbf{u} \cdot \Lambda = 1$$



# Geometry of polar varieties

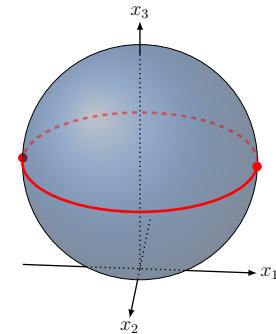
Let  $V = \{\mathbf{x} \in \mathbb{C}^n \mid F_1(\mathbf{x}) = \cdots = F_p(\mathbf{x}) = 0\}$   $\rightarrow$  regularity assumptions

Transfer of properties of  $V$  to polar varieties in generic coordinates.

▷ Dimension is well controlled

$$\dim(W_1) = 0, \dim(W_2) = 1, \dots, \dim(W_i) = i - 1$$

Bank/Giusti/Heintz/M'bakop/Pardo 97



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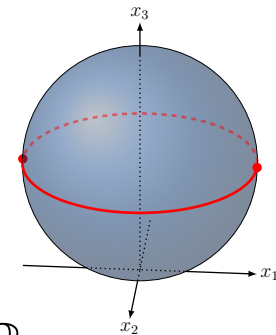
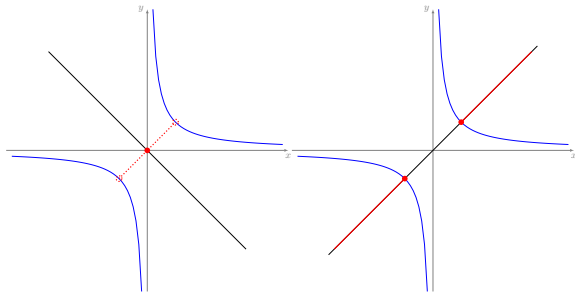
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Bank/Giusti/Heintz/M'bakop/Pardo 97

▷ Closedness of projections

$$W_1 \cap (V \cap \mathbb{R}^n) = \emptyset \text{ and } V \cap \mathbb{R}^n \neq \emptyset \implies \pi_1(V \cap \mathbb{R}^n) = \mathbb{R}$$



S./Schost 03

Transfer of **Noether position** properties to polar varieties.

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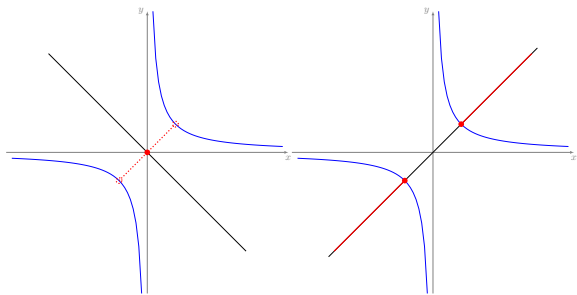
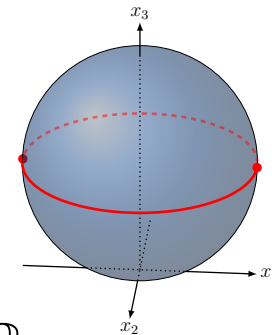
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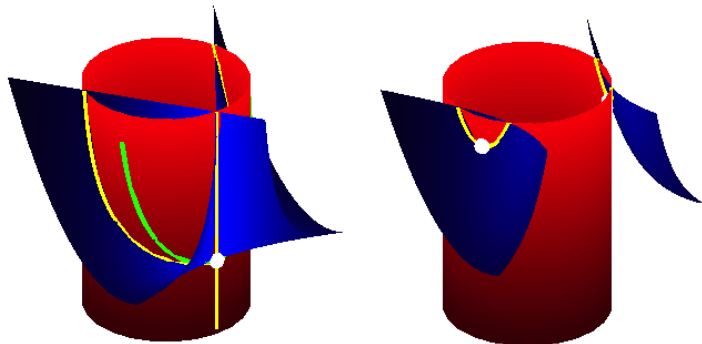
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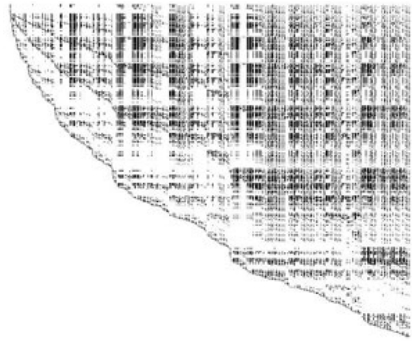
S./Schost 03

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Removal of regularity assumptions **Hong/S.**

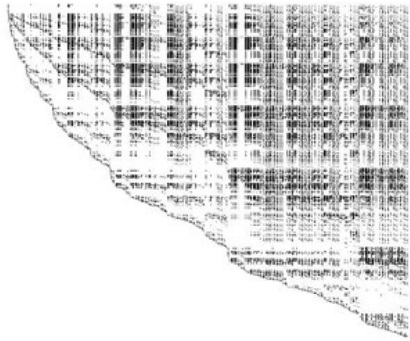
- Deformation techniques without using infinitesimal arithmetic
- Ideal theoretic operations



## (Arithmetic) Complexity results

(determinantal modeling,  $\deg(F_i) = D$  for  $1 \leq i \leq p$ )

- ▷  $\mathbb{D}_{\text{reg}} \leq D(p-1) + (D-2)n + 2$
- ▷ When  $D = 2$ ,  $O(n^{2p\omega})$
- ▷  $O\left(\frac{1}{\sqrt{n}}((D-1)e)^{n\omega}\right)$  if  $D > 2$  and  $p$  is fixed.



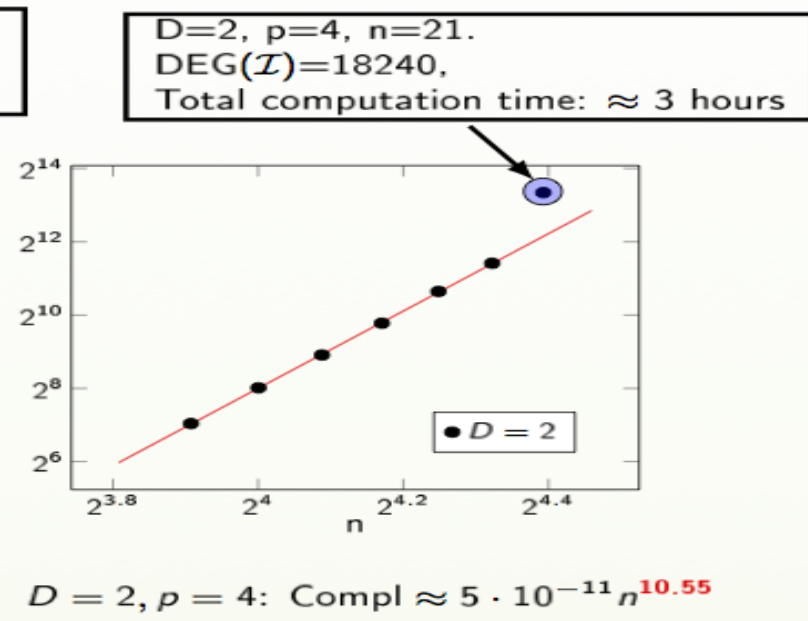
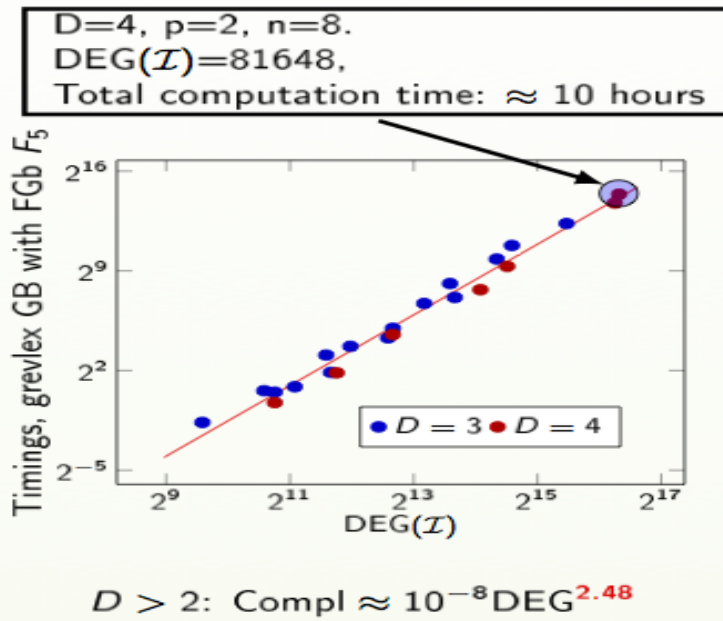
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## Polar varieties and homotopy techniques

$$\delta = D^p (D - 1)^{n-p} \binom{n-1}{p-1} \rightarrow \text{generic degree of the 0-dim. polar variety}$$

▷ **Symbolic homotopy (Geometric Resolution Algorithm)**

(Giusti/Lecerf/Salvy, Heintz, Montana, Solerno, Pardo, etc.)

**Incremental algorithm** → well-suited for complete intersections

Use of **Lagrange system** yields a complexity  $\sim O(\delta^3)$  S./Schost

▷ **(Semi-)Numerical homotopy**

Sommese/Wampler Bates, Hauenstein, Leykin, Verschelde, etc.

Path-tracking from a “good” start system  $\rightsquigarrow$  **Lagrange system**

BUT far from being optimal for **mixed** degrees.

**On-going work (Hauenstein/S.):**

- ▷ Dedicated homotopy in the case of mixed systems.
- ▷ Possible generalization to determinantal systems.

# Summary

**Software RAGlib (Real Algebraic Geometry Library)**

Scales to  $\simeq 8$ – $10$  variables ( $D = 4$ ,  $n = 6$ , dense equation  $\rightarrow 2$  hours)

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**Applications** in biology, comput. geometry, numerical analysis, robotics, etc.

- Non-validity of models in bio-informatics
  - Discovery fo the stability region of MacCormack's scheme for PDEs
  - Computational geometry: Voronoi diagram, Perspective problems, etc.
- 



**Used for an engineering application**

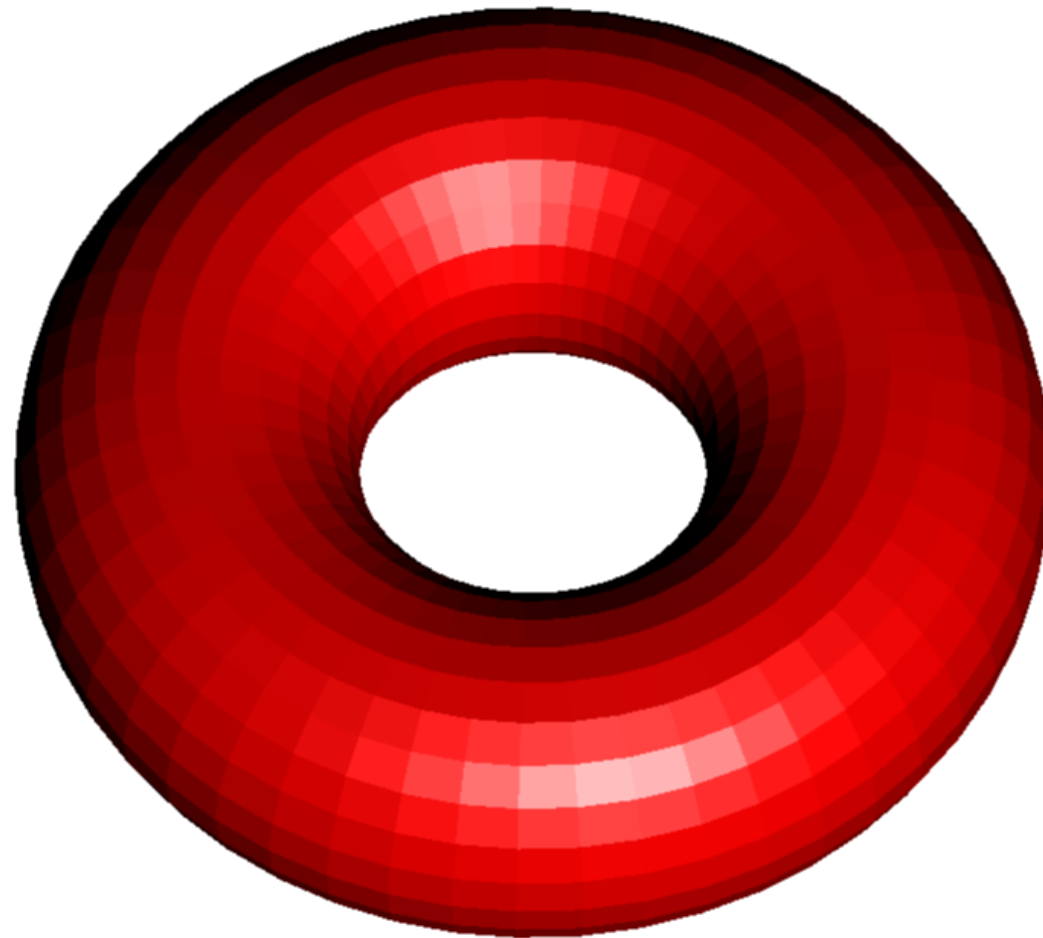
Systems of inequalities with  $\simeq 6 \rightarrow 8$  variables

**Unreachable by current CAD implementations**

through Erich Kaltofen's consulting activity

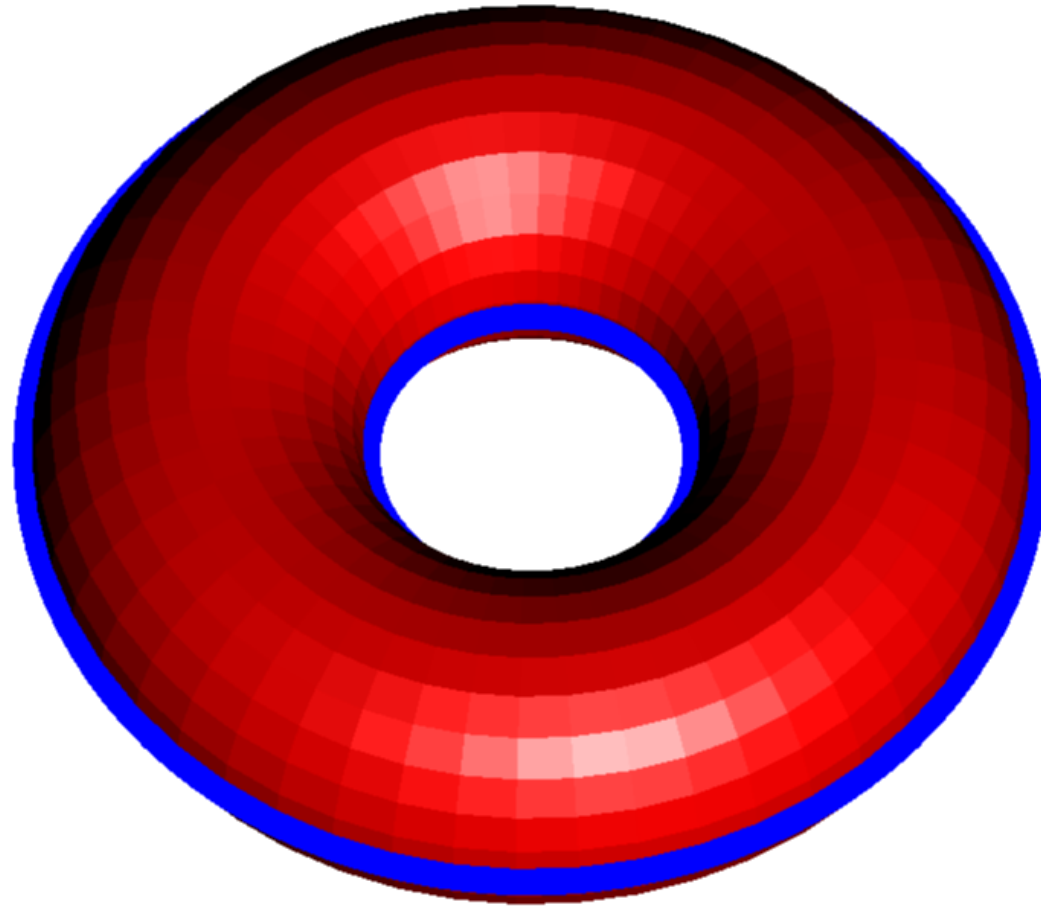
**New challenges:** topological informations such as connectivity queries?

Example: torus

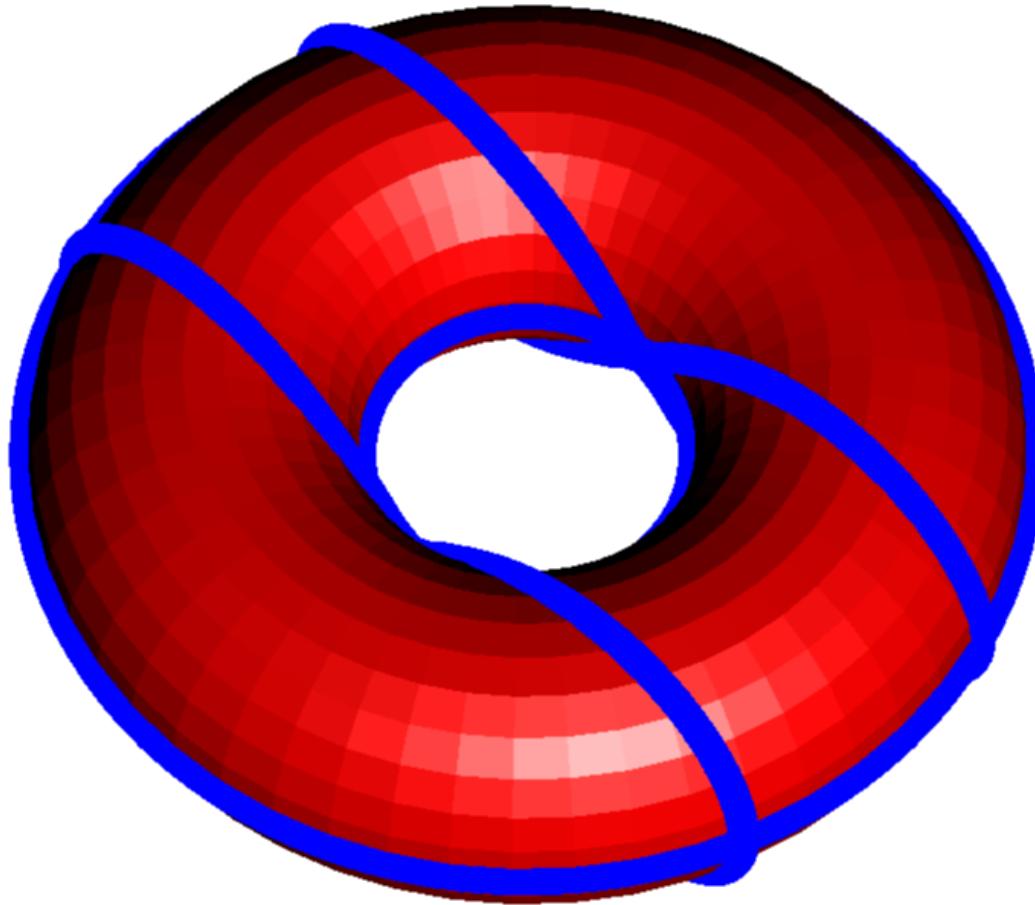




Example: torus



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Roadmap

## Complexity results for roadmaps

$D^{O(n^2)}$  (probabilistic) /  $D^{O(n^4)}$  (deterministic)

**Canny** ( $\simeq 88$ )

Further improvements (Grigoriev/Vorobjov, Gourney/Risler, Heintz/Roy/Solerno)

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**Basu/Pollack/Roy**

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**A landmark result: Basu/Roy 2014**  $(nD)^{\tilde{O}(n)}$  deterministic, no hyp.

**BUT**  $(n^{\log(n)} D)^{O(n \log^2(n))}$  and **Output size:**  $(n^{\log_2(n)} D)^{n \log_2(n)}$

$$n \leq \log_2^2(n) \quad \text{for } 4 \leq n \leq 16,$$

$$\sqrt{n} \leq \log_2^2 n \quad \text{for } 4 \leq n \leq 2^{16} = 65536$$

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**Input:** smoothness and compactness hyp.  $\mathbf{f} = (f_1, \dots, f_p)$  red. reg. sequence

$$O\left(E(4n\lambda D)^{6(\lambda+3)(n+3\lambda)}\right)$$

with  $\lambda = \log_2(n-p)$  and  $E = \text{EvalComplexity}(\mathbf{f})$

**Output:**  $(nD)^{2(\lambda+3)(n+3\lambda)}$

## Input / output

- input: a “nice” system  $\mathbf{f} = f_1, \dots, f_p$  defining  $V = V(\mathbf{f})$  ( $d = \dim(V)$ )
- output: a roadmap of  $V(\mathbf{f})$

**Main idea:** for a suitable  $i \leq d$

- **recursive call on  $W_i$**

→ we need  $W_i$  to satisfy the input assumptions.

- **recursive call on finitely many fibers of  $\pi_{i-1}$  (about  $D^n$ )**

→ we need to perform computations over “base points”.

Done by revisiting Lecerf's geometric resolution algorithm

- **merge the results**

Expectedly, running time about  $D^{O(\rho n)}$ , where  $\rho$  is the depth of the recursion.

**We want to use this recursive scheme with  $i \simeq (n - p)/2$**

$$W_i = \{\mathbf{x} \in V \mid \dim(\pi_i(T_{\mathbf{x}}V)) \leq i - 1\}$$

can be decomposed into **Thom-Boardman strata**.

$$S_{i,i-1} = \{\mathbf{x} \in V \mid \dim(\pi_i(T_{\mathbf{x}}V)) = i - 1\}$$

$$S_{i,i-2} = \{\mathbf{x} \in V \mid \dim(\pi_i(T_{\mathbf{x}}V)) = i - 2\}$$

$$\vdots$$

$$S_{i,j} = \{\mathbf{x} \in V \mid \dim(\pi_i(T_{\mathbf{x}}V)) = j\}$$

$$\vdots$$

$$S_{i,0} = \{\mathbf{x} \in V \mid \dim(\pi_i(T_{\mathbf{x}}V)) = 0\}$$

Mather, Alzati/Ottaviani, Alzati/Ottaviani

In **generic** coordinates:

- ▷ T-B strata are locally closed smooth constructible sets.
- ▷ Dimension of T-B is controlled.
- ▷ When  $i \leq \frac{\dim(V(\mathbf{f}))+3}{2}$ ,  $S_{i,j}$  has dimension  $\leq 0$   $1 \leq j \leq p - 2$ .





## First implementation

- ▷ Based on the latest Faugère's **FGb** library for computing Gröbner bases and rational parametrization.
- ▷ No assumption is checked ; routines for optimizing the choice of linear changes of variables are **not** implemented.
- ▷ Tests on **random dense** systems of quadrics and quartics (worst case).

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- ▷ Tests on **random dense** systems of quadrics and quartics (worst case).
- ▷ scales to problems of dimension 5 (case of quartics) and problems of dimension 9 (quadrics).
- ▷ new ideas behind this implementation and **careful** computation of “critical points of critical points”.
- ▷ size of the output is clearly overestimated.

## Conclusions and Perspectives

- ▷ Strong interaction between algorithm/software design and complexity
- ▷ Exact methods based on the critical point method can now solve efficiently non-trivial problems
- ▷ You should **NOT** conclude that CAD becomes useless
  - ▷ no other alternative to quantifier elimination
  - ▷ **extremely efficient** for low-dimensional problems
  - ▷ highly non-trivial (and efficient) algorithms for curve of surface topology based on CAD-like techniques
- ▷ **Diversity is good.**