

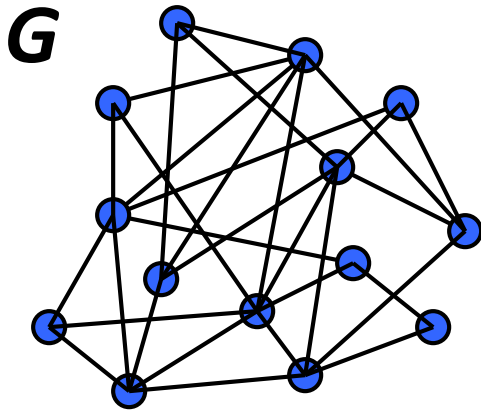
Graph Sparsification I : Effective Resistance Sampling

Nikhil Srivastava

Microsoft Research India

Simons Institute, August 26 2014

Graphs



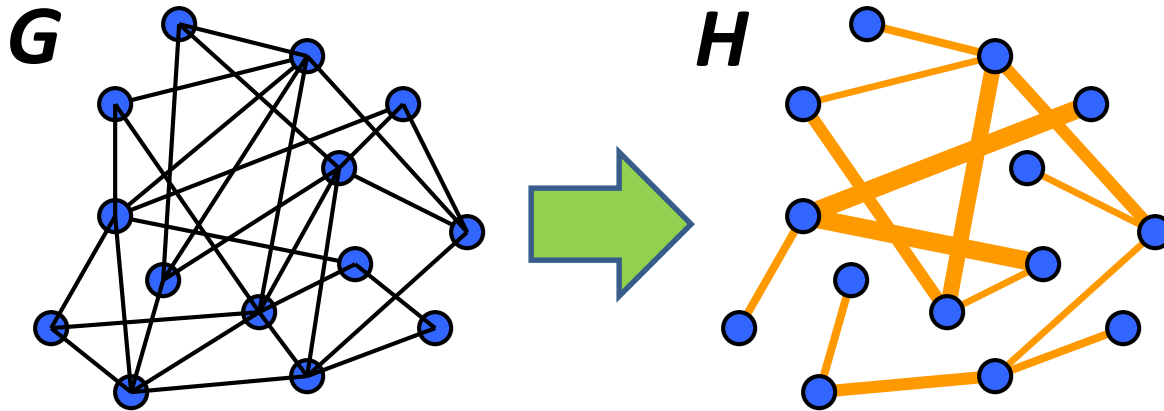
$G=(V,E,w)$ undirected

$$|V| = n$$

$$w: E \rightarrow \mathbf{R}_+$$

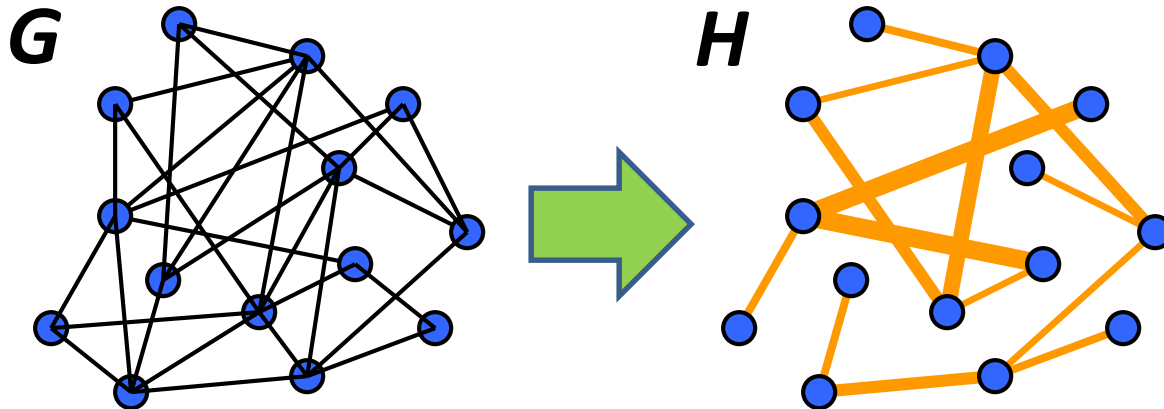
Sparsification

Approximate any graph G by a sparse graph H .



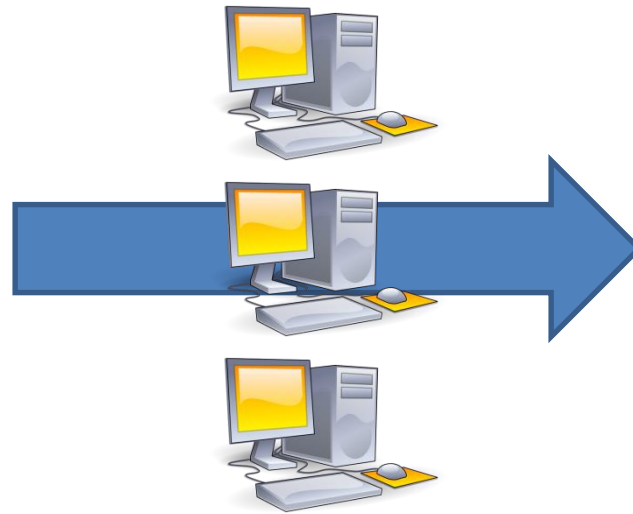
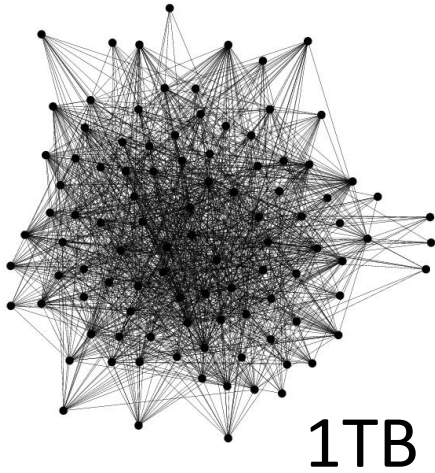
Sparsification

Approximate any graph G by a sparse graph H .



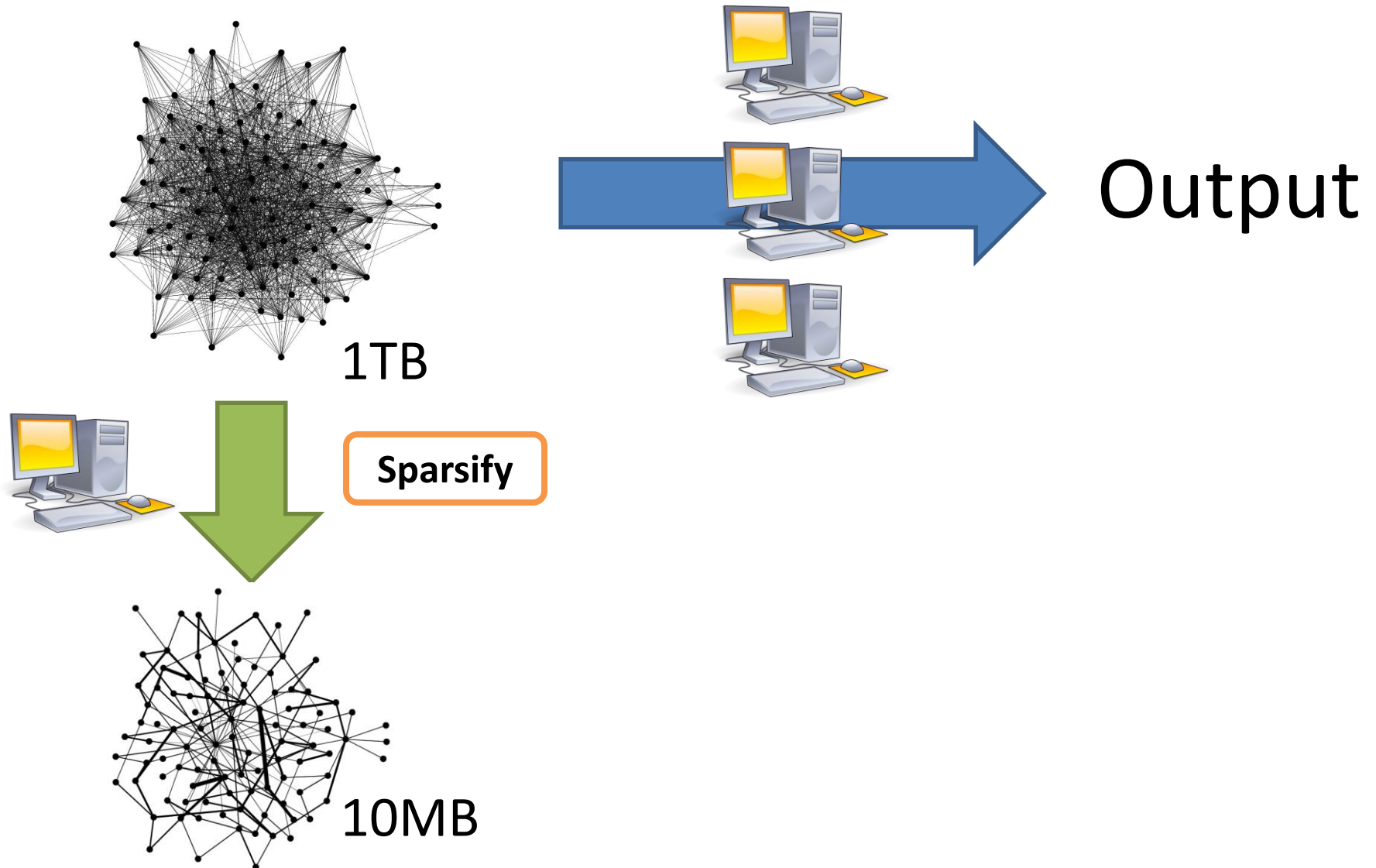
- H is faster to compute with than G
- Nontrivial statement about G

Sample Application

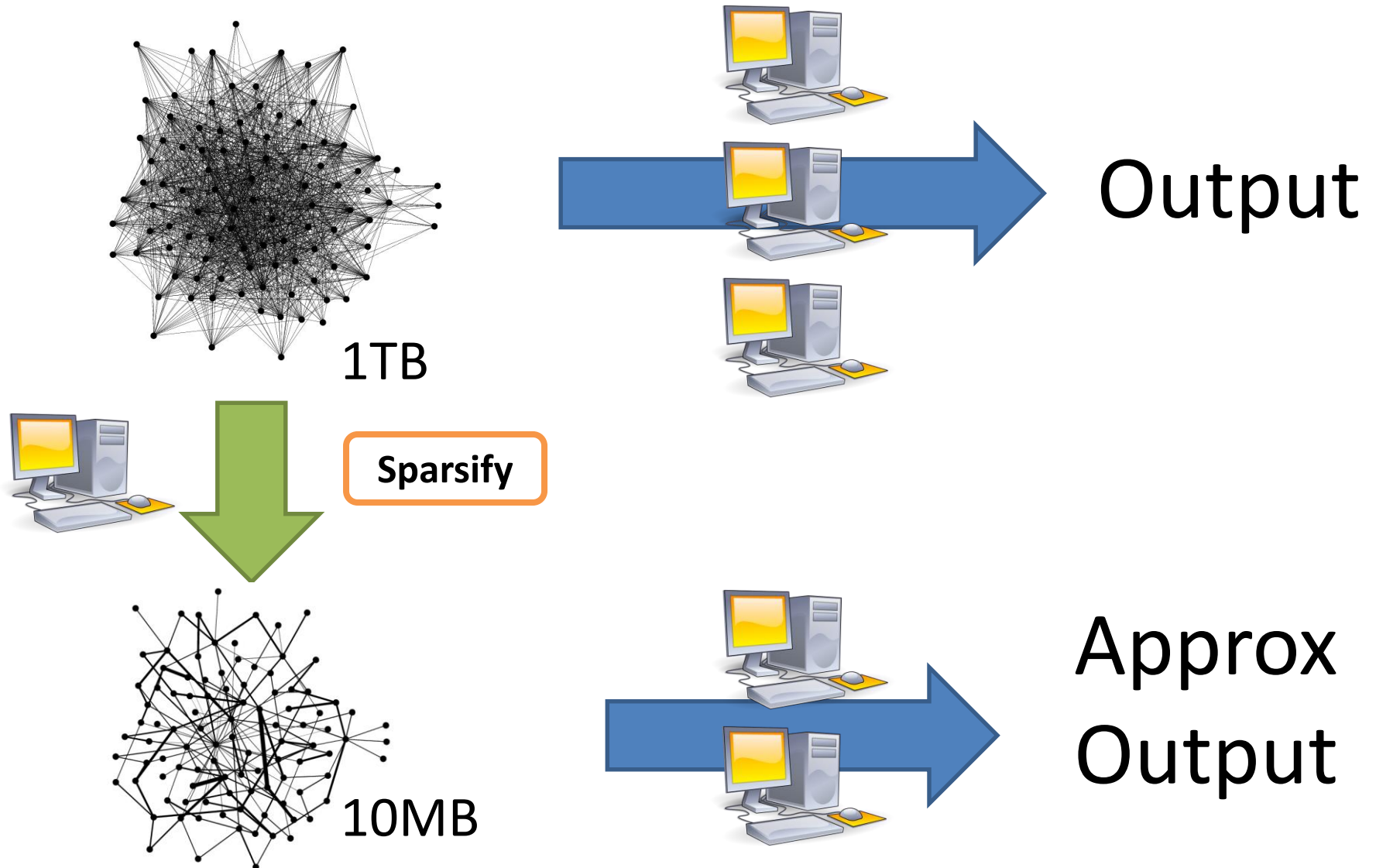


Output

Sample Application



Sample Application



Some properties of interest

Sizes of cuts

“bottlenecks”

Clusters

“communities”

Distances

Random walks

Single / multicommodity flows

Electrical flows + other physical processes

Coloring

Hamiltonian / Eulerian cycle

Subgraph counts

e.g. triangles

Some properties of interest

Sizes of cuts

“bottlenecks”

Clusters

“communities”

Distances

Random walks

Single / multicommodity flows

Electrical flows + other physical processes

Coloring

Hamiltonian / Eulerian cycle

Subgraph counts

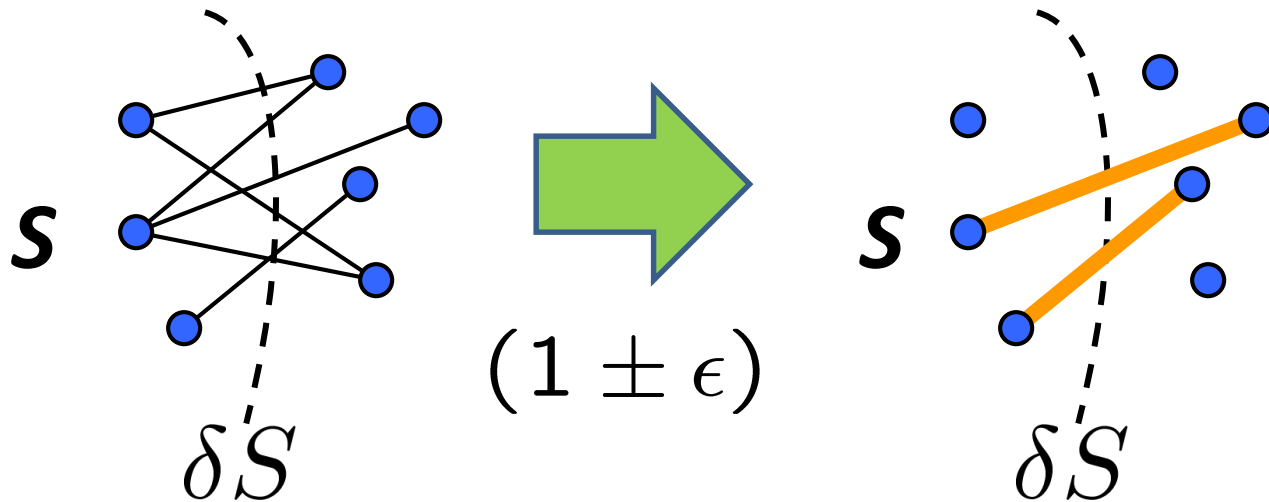
e.g. triangles

Cut Approximation [Benczur-Karger'96]

H approximates G if

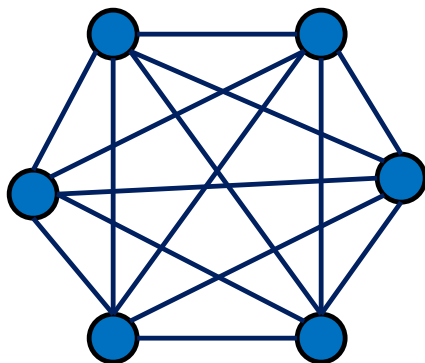
for every subset $S \subset V$

sum of weights of edges leaving S is preserved



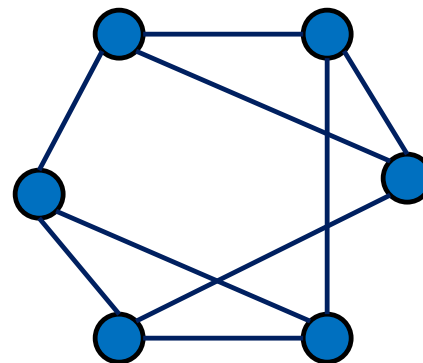
Example: The Complete Graph

$G = K_n$



$$|E_G| = O(n^2)$$

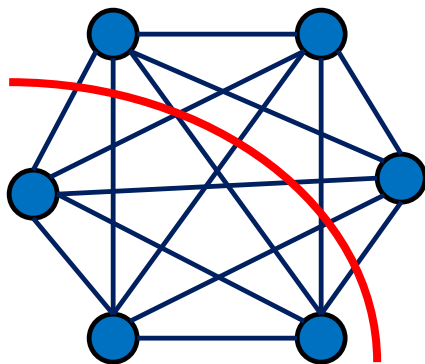
$H = \text{random } d\text{-regular}$



$$|E_H| = O(dn)$$

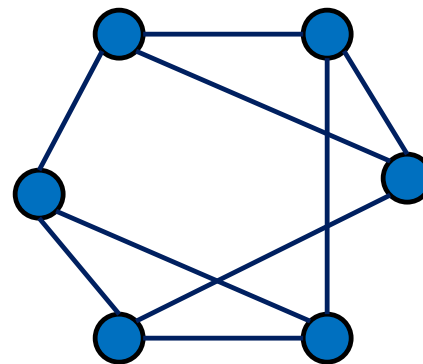
Example: The Complete Graph

$G = K_n$



$$|E_G| = O(n^2)$$

$H = \text{random } d\text{-regular}$

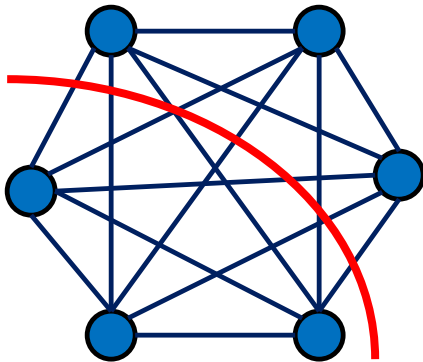


$$|E_H| = O(dn)$$

$$wt_G(\delta S) = |S| \cdot |\bar{S}|$$

Example: The Complete Graph

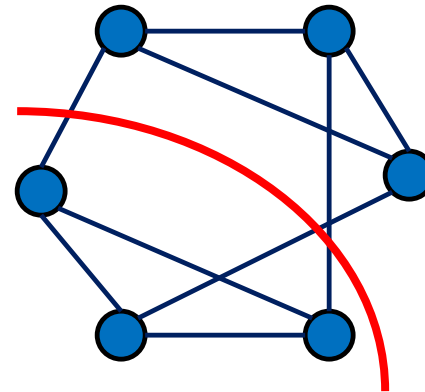
$G = K_n$



$$|E_G| = O(n^2)$$

$$wt_G(\delta S) = |S| \cdot |\bar{S}|$$

$H = \text{random } d\text{-regular}$

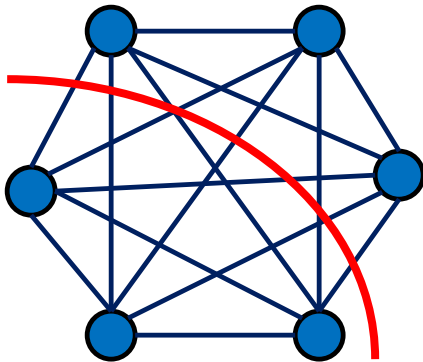


$$|E_H| = O(dn)$$

$$\mathbb{E}wt_H(\delta S) = (d/n)|S| \cdot |\bar{S}|$$

Example: The Complete Graph

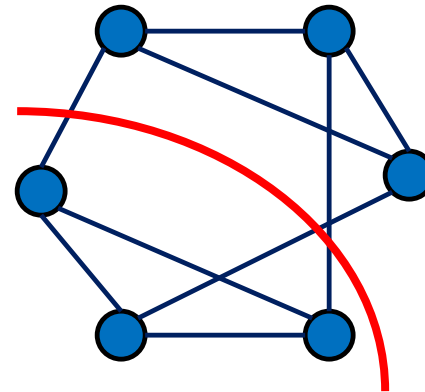
$G = K_n$



$$|E_G| = O(n^2)$$

$$wt_G(\delta S) = |S| \cdot |\bar{S}|$$

$H = \text{random } d\text{-regular}$



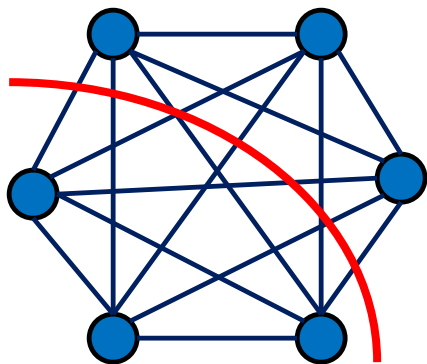
$$|E_H| = O(dn)$$

$$wt_H(\delta S) \simeq (d/n) |S| \cdot |\bar{S}|$$

with high probability

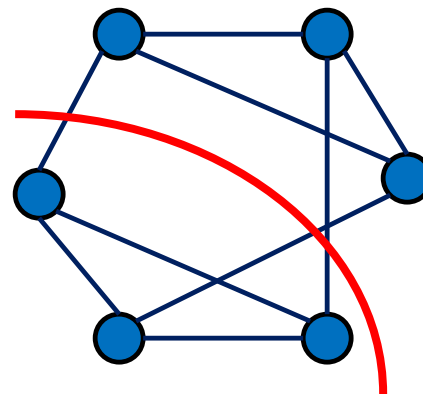
Example: The Complete Graph

$G = K_n$



$$|E_G| = O(n^2)$$

$H = \text{random } d\text{-regular}$



$$|E_H| = O(dn)$$

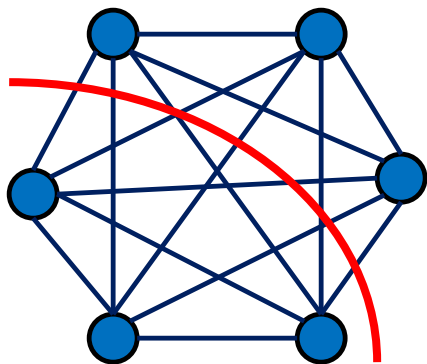
$$\forall S \subset V, \quad \frac{wt_G(\delta S)}{wt_H(\delta S)} \simeq (n/d)$$

whp

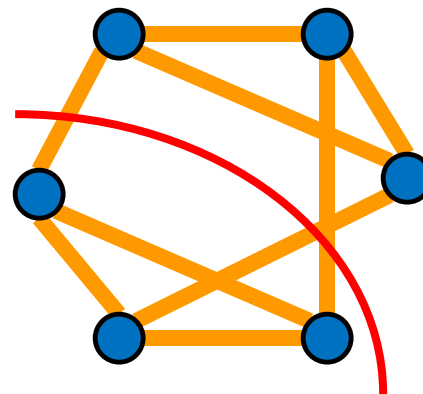
Example: The Complete Graph

$G = K_n$

$H = \text{random } d\text{-regular } \times (n/d)$



$$|E_G| = O(n^2)$$



$$|E_H| = O(dn)$$

$$\forall S \subset V, \quad \frac{wt_G(\delta S)}{wt_{(n/d)H}(\delta S)} \simeq 1$$

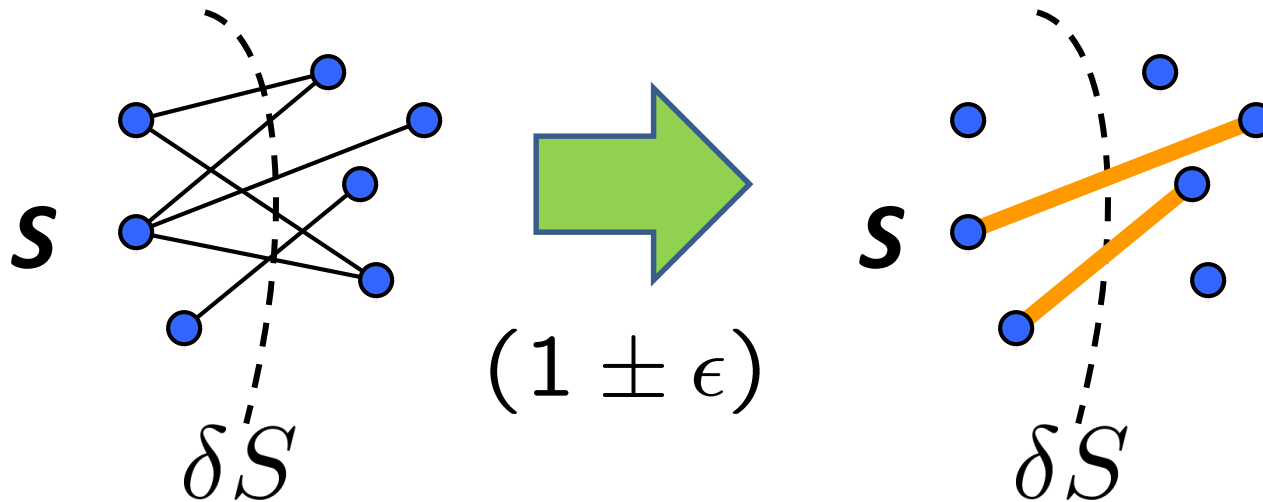
whp

Cut Approximation [Benczur-Karger'96]

H approximates G if

for every subset $S \subset V$

sum of weights of edges leaving S is preserved

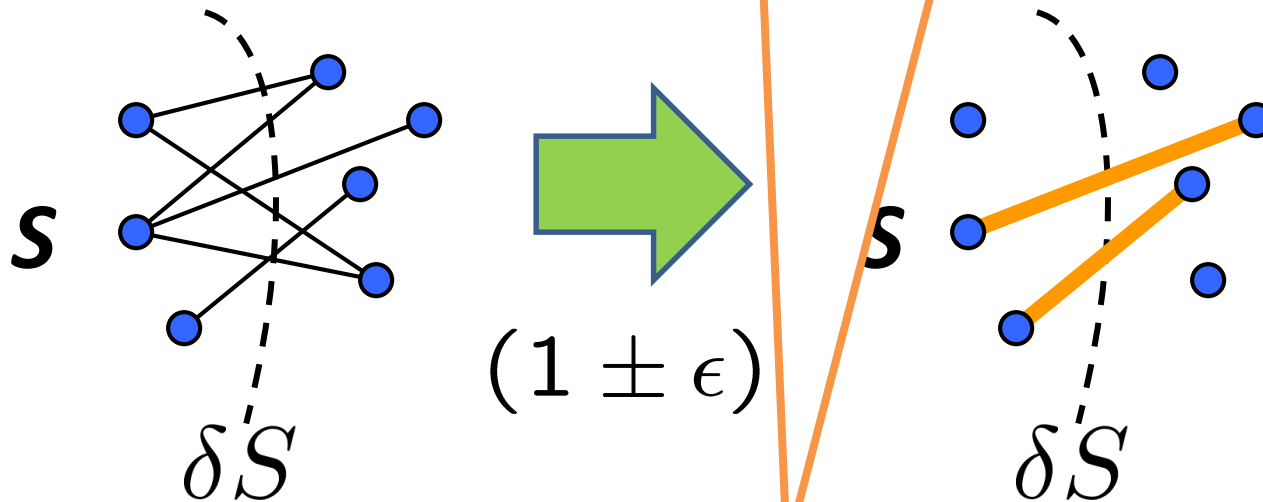


[Benczur-Karger'96]: For every G can quickly find H with $O(n \log n / \epsilon^2)$ edges.

Cut Approximation [Benczur-Karger'96]

H approximates G for every subset S of vertices. The sum of weights of edges leaving S is preserved.

G and H are essentially the same for min cut, sparsest cut, etc.



[Benczur-Karger'96]: For every G can quickly find H with $O(n \log n / \epsilon^2)$ edges.

Cut Approximation [Benczur-Karger'96]

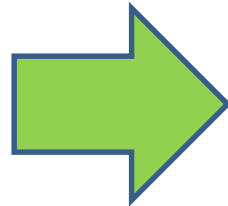
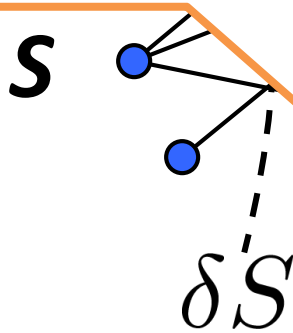
H approximates G for every subtree

G and H are essentially the same for min cut, sparsest cut, etc.

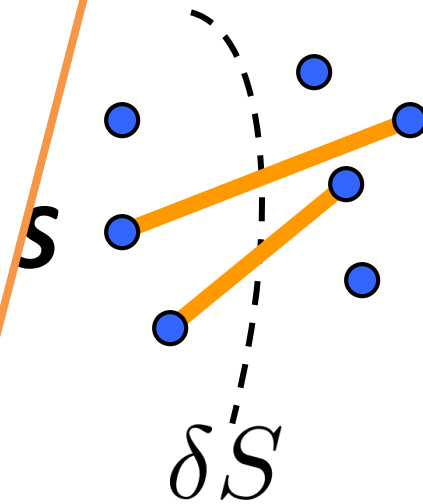
Going below $O(n)$ would disconnect the graph.

edges leave

preserved



$(1 \pm \epsilon)$



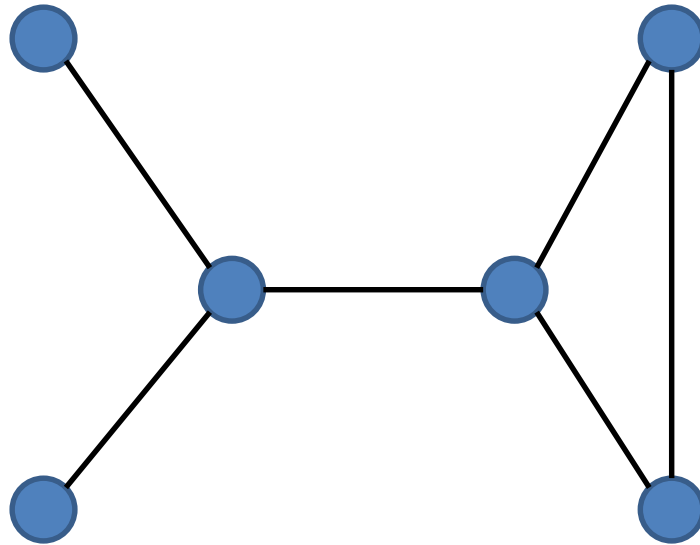
[Benczur-Karger'96]: For every G can quickly find H with $O(n \log n / \epsilon^2)$ edges.

Physical Approximation

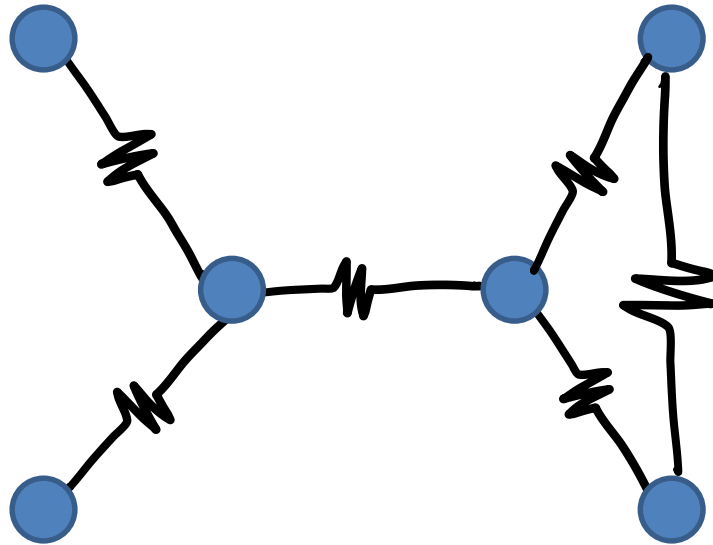
[Spielman-Teng'04]

(i.e., spectral approximation)

Resistor Network Metaphor

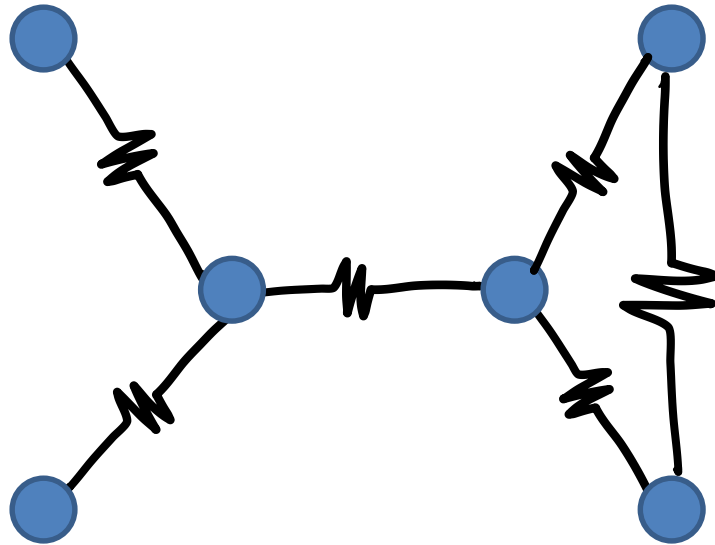


Resistor Network Metaphor



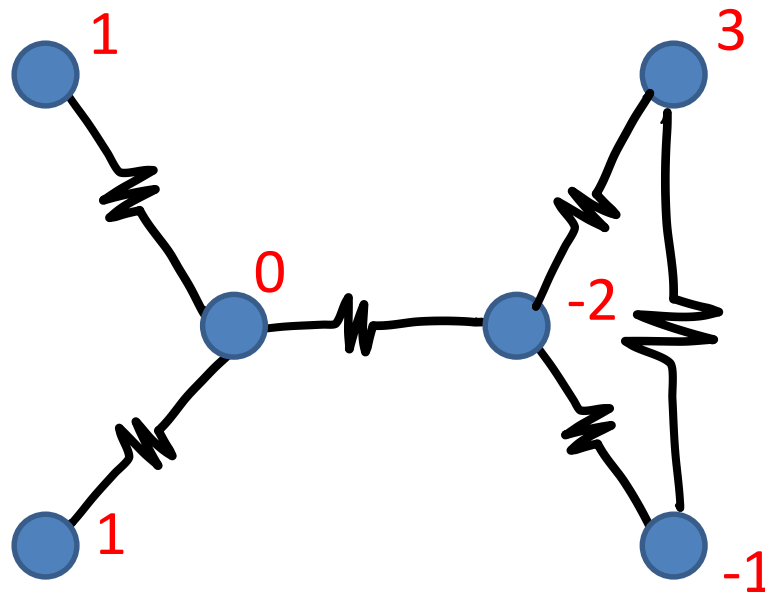
edge = 1Ω resistor

Resistor Network Metaphor



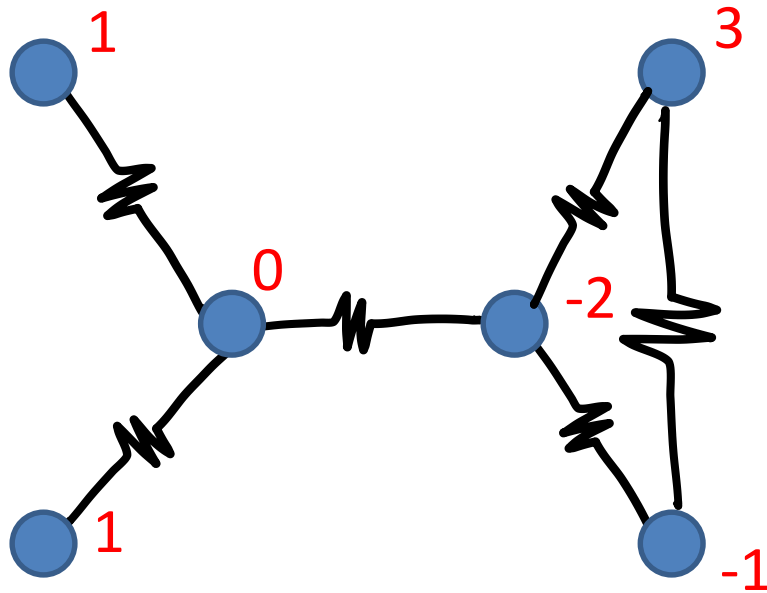
potentials $x: V \rightarrow \mathbb{R}$

Resistor Network Metaphor



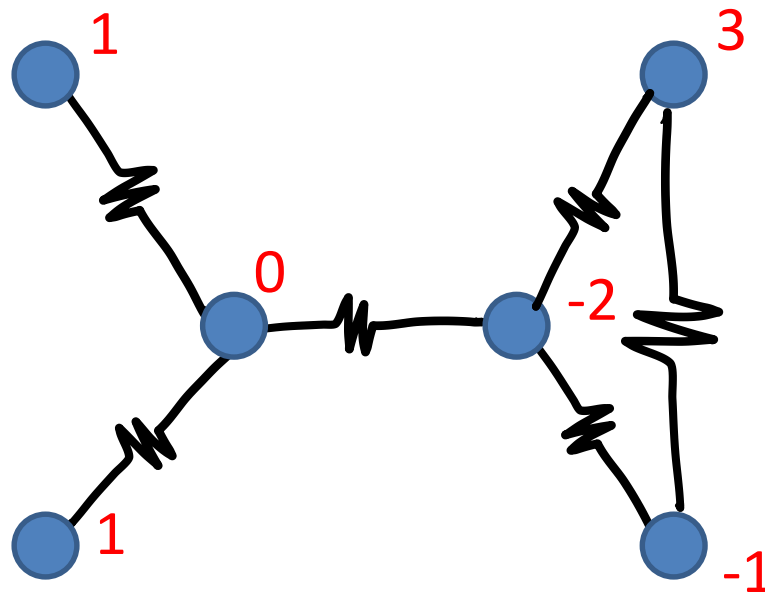
potentials $x: V \rightarrow \mathbb{R}$

Resistor Network Metaphor



$$\text{energy } \mathcal{E}_G(x) = \sum_{ij \in E} (x_i - x_j)^2$$

Resistor Network Metaphor



$$\begin{aligned} \text{energy } \mathcal{E}_G(x) &= \sum_{ij \in E} (x_i - x_j)^2 \\ &= 1^2 + 1^2 + 2^2 + 5^2 + 1^2 + 2^2 = 36 \end{aligned}$$

Physical Approximation [ST'04]

Definition. $H = (V, F, u)$ is a κ –approximation of $G = (V, E, w)$ if for all potentials $x: V \rightarrow \mathbb{R}$:

$$\mathcal{E}_H(x) \leq \mathcal{E}_G(x) \leq \kappa \cdot \mathcal{E}_H(x)$$

“Electrically Equivalent”

Physical Approximation [ST'04]

Definition. $H = (V, F, u)$ is a κ –approximation of $G = (V, E, w)$ if for all potentials $x: V \rightarrow \mathbb{R}$:

$$\sum_{ij \in F} u_{ij} (x_i - x_j)^2 \leq \sum_{ij \in E} w_{ij} (x_i - x_j)^2 \leq \kappa \cdot \sum_{ij \in F} u_{ij} (x_i - x_j)^2$$

“Electrically Equivalent”

Physical Approximation [ST'04]

Definition. $H = (V, F, u)$ is a κ –approximation of $G = (V, E, w)$ if for all potentials $x: V \rightarrow \mathbb{R}$:

$$\sum_{ij \in F} u_{ij} (x_i - x_j)^2 \leq \sum_{ij \in E} w_{ij} (x_i - x_j)^2 \leq \kappa \cdot \sum_{ij \in F} u_{ij} (x_i - x_j)^2$$

Laplacian matrix

$$x^T L_G x$$

$$x^T L_H x$$

Physical Approximation [ST'04]

Definition. $H = (V, F, u)$ is a κ –approximation of $G = (V, E, w)$ if for all potentials $x: V \rightarrow \mathbb{R}$:

$$x^T L_H x \leq x^T L_G x \leq \kappa \cdot x^T L_H x$$

where $L_G = \sum_{ij} w_{ij} (\delta_i - \delta_j)(\delta_i - \delta_j)^T$

is the **Laplacian** matrix of **G**.

Physical Approximation [ST'04]

Definition. $H = (V, F, u)$ is a κ –approximation of $G = (V, E, w)$ if for all potentials $x: V \rightarrow \mathbb{R}$:

$$x^T L_H x \leq x^T L_G x \leq \kappa \cdot x^T L_H x$$

where $L_G = \sum_{ij} w_{ij} (\delta_i - \delta_j) (\delta_i - \delta_j)^T$

is the **Laplacian** matrix of **G**.

$$\begin{matrix} i & \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} \\ j & \begin{matrix} i & j \end{matrix} \end{matrix}$$

Properties of the Laplacian

$$L_G = \sum_{ij \in E} w_{ij} (\delta_i - \delta_j)(\delta_i - \delta_j)^T = \sum_{ij \in E} w_{ij} L_{ij}$$

$x^T L_G x \geq 0$ so **positive semidefinite** $L_G \succcurlyeq 0$.

$A \succcurlyeq B$ means $x^T A x \geq x^T B x$

Properties of the Laplacian

$$L_G = \sum_{ij \in E} w_{ij} (\delta_i - \delta_j)(\delta_i - \delta_j)^T = \sum_{ij \in E} w_{ij} L_{ij}$$

$x^T L_G x \geq 0$ so **positive semidefinite** $L_G \succcurlyeq 0$.

nullspace = $\text{span}\{(1, 1, \dots, 1)\}$ for connected G .


$$\sum_{ij \in E} w_{ij} (x_i - x_j)^2 = 0 \text{ iff } x_i = x_j \text{ for every } ij \in E$$

Properties of the Laplacian

$$L_G = \sum_{ij \in E} w_{ij} (\delta_i - \delta_j)(\delta_i - \delta_j)^T = \sum_{ij \in E} w_{ij} L_{ij}$$

$x^T L_G x \geq 0$ so **positive semidefinite** $L_G \succcurlyeq 0$.

nullspace = $\text{span}\{(1, 1, \dots, 1)\}$ for connected G .

Will talk about **inverse** $L_G^{-1} \succcurlyeq 0$ orthogonal to nullspace.

Properties of the Laplacian

$$L_G = \sum_{ij \in E} w_{ij} (\delta_i - \delta_j)(\delta_i - \delta_j)^T = \sum_{ij \in E} w_{ij} L_{ij}$$

$x^T L_G x \geq 0$ so **positive semidefinite** $L_G \succcurlyeq 0$.

nullspace = $\text{span}\{(1, 1, \dots, 1)\}$ for connected G .

Will talk about **inverse** $L_G^{-1} \succcurlyeq 0$ orthogonal to nullspace.

Can talk about **square root** $L_G^{-1/2}$ because $L_G^{-1} \succcurlyeq 0$.

Physical Approximation [ST'04]

Definition. $H = (V, F, u)$ is a κ –approximation of $G = (V, E, w)$ if:

$$L_H \preceq L_G \preceq \kappa \cdot L_H$$

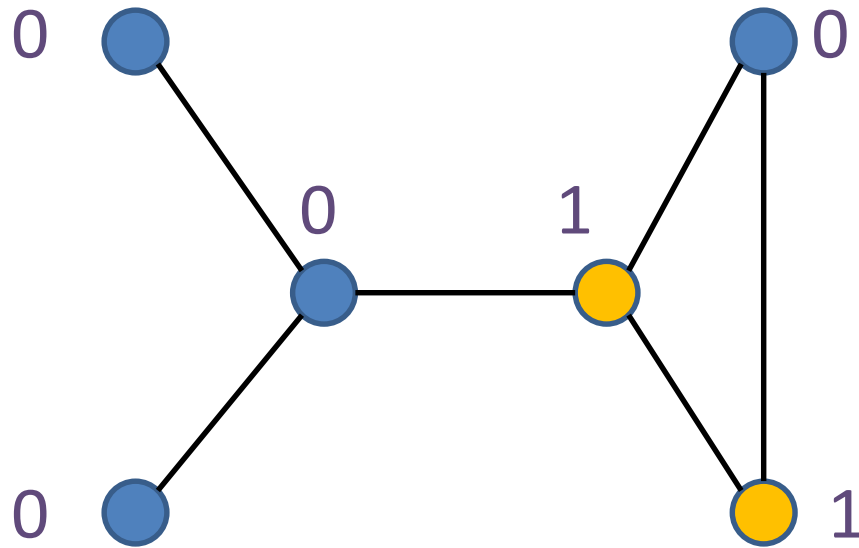
where $L_G = \sum_{ij} w_{ij} (\delta_i - \delta_j)(\delta_i - \delta_j)^T$

is the **Laplacian** matrix of **G**.

Why?

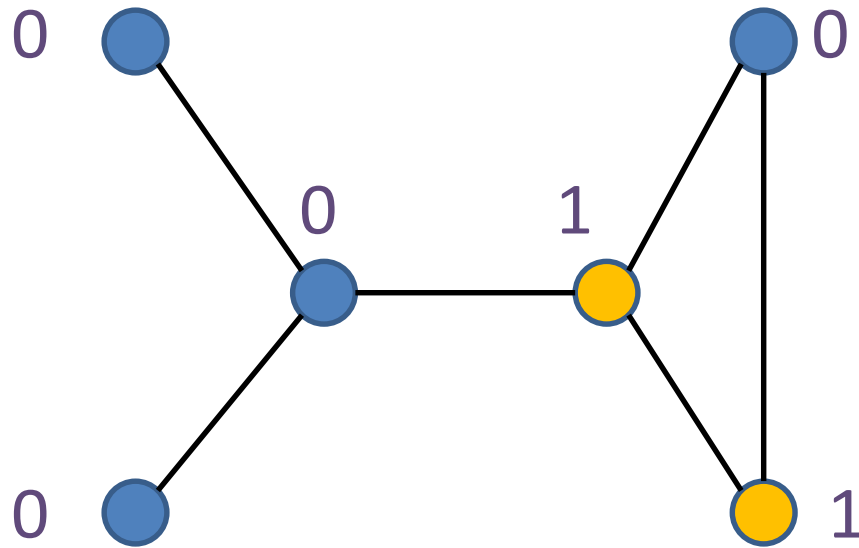
0. Energy Encodes Cuts

$$x: V \rightarrow \{0,1\}$$



0. Energy Encodes Cuts

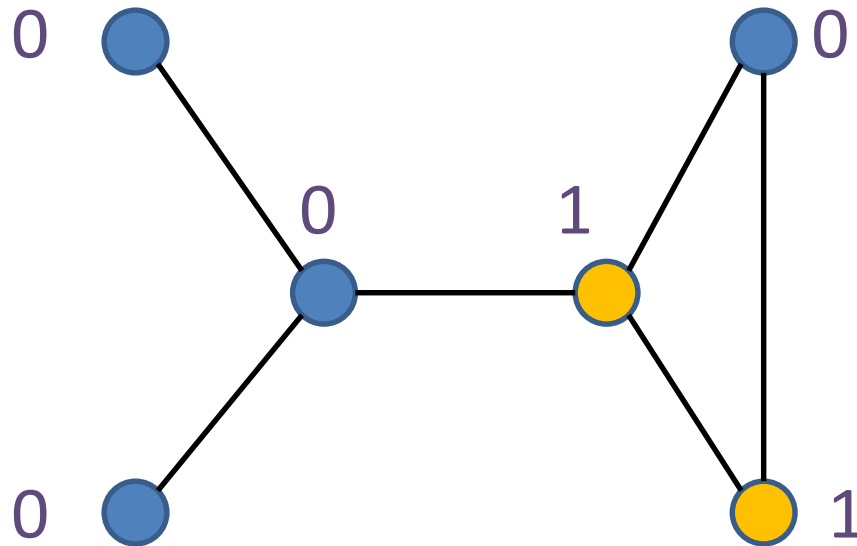
$$x: V \rightarrow \{0,1\}$$



$$\mathcal{E}_G(x) = 1^2 + 1^2 + 1^2 = 3$$

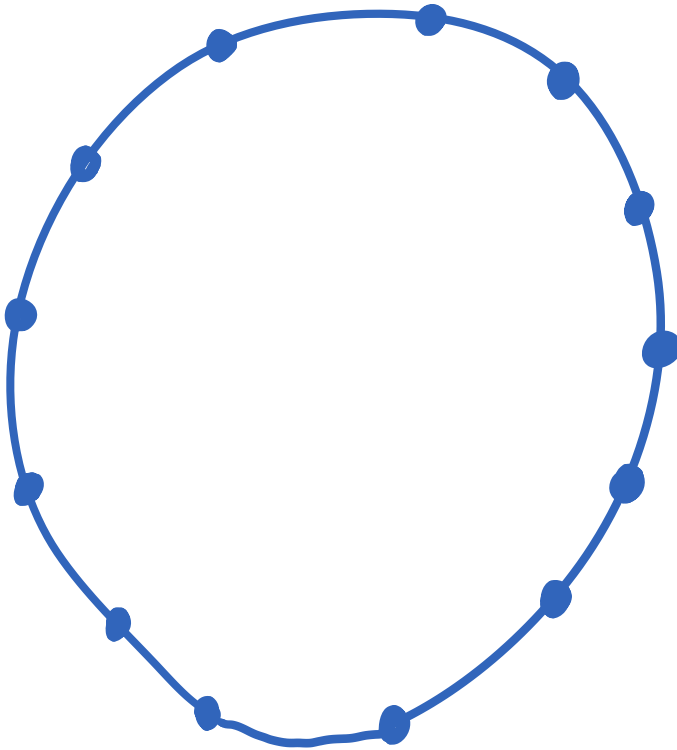
0. Energy Encodes Cuts

$$x: V \rightarrow \{0,1\}$$



Physical approx. implies cut approx.

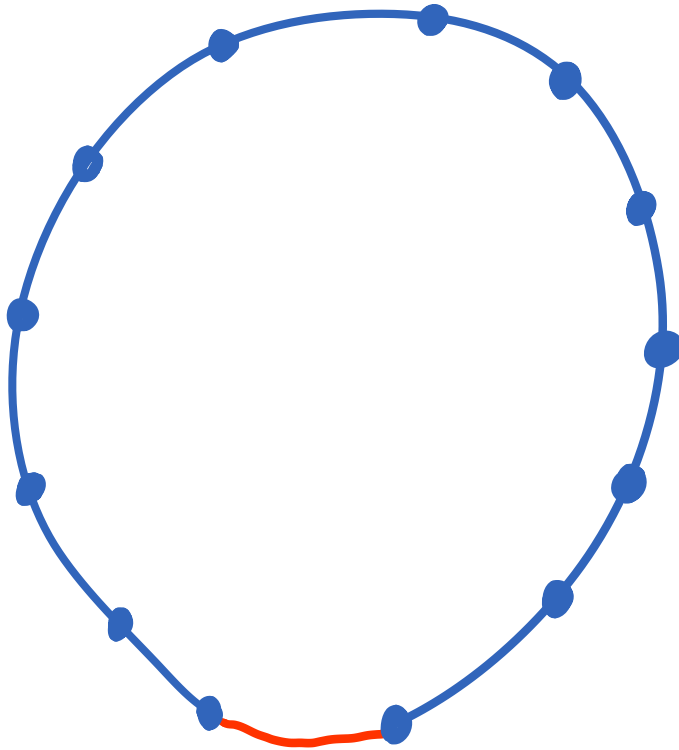
\mathcal{E} is stronger than cut approx



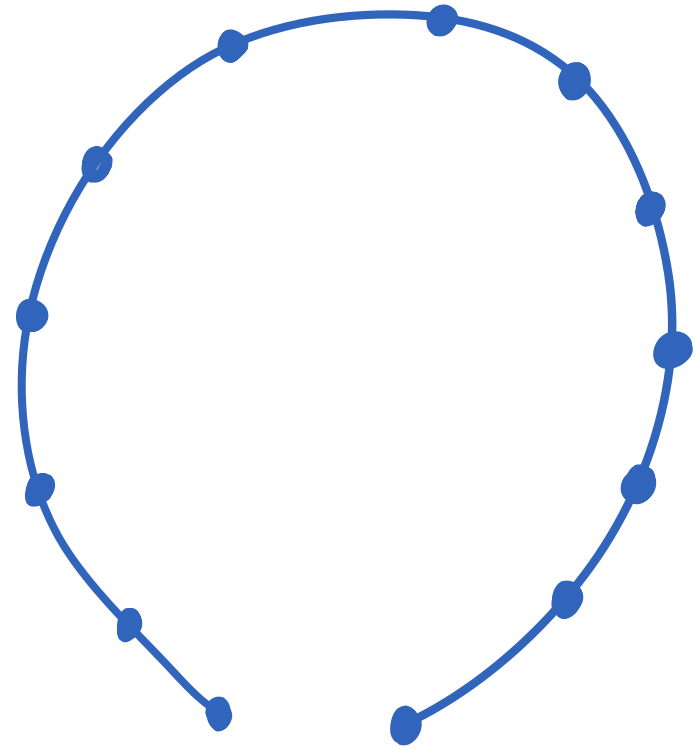
$G = \text{cycle}$

$\text{Min cut} = 2$

\mathcal{E} is stronger than cut approx

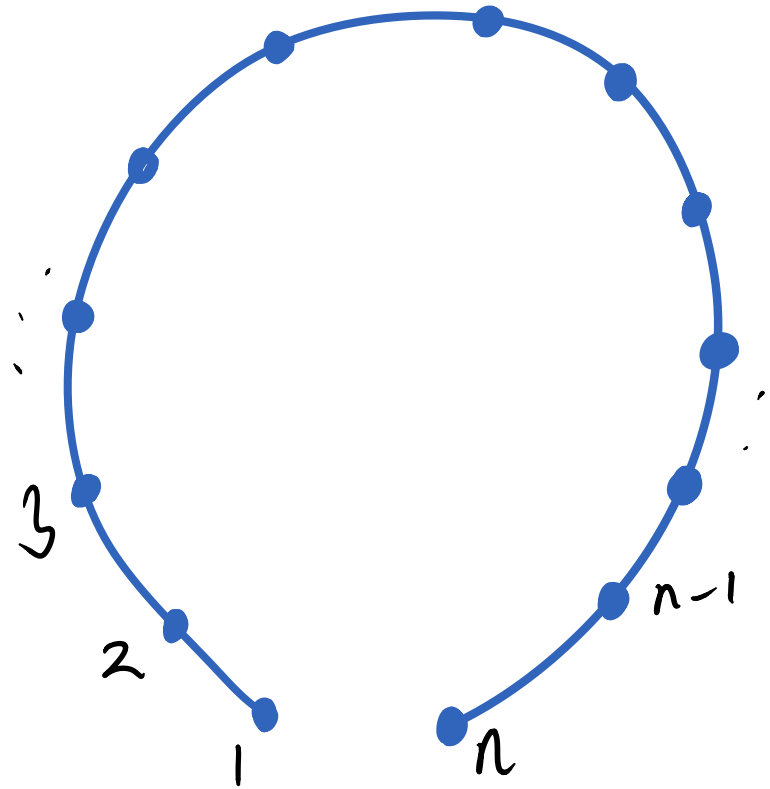
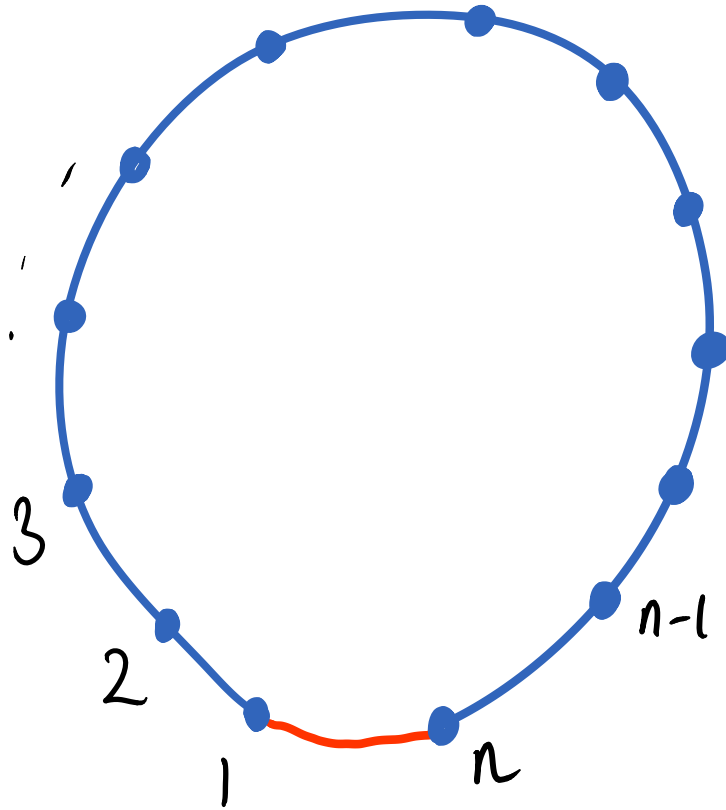


G

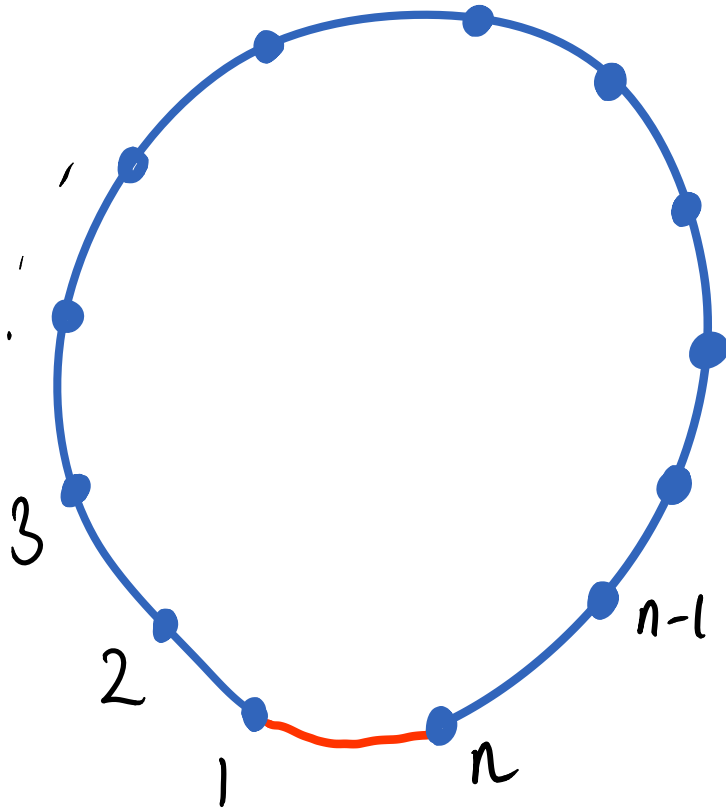


2-cut approx H

\mathcal{E} is stronger than cut approx



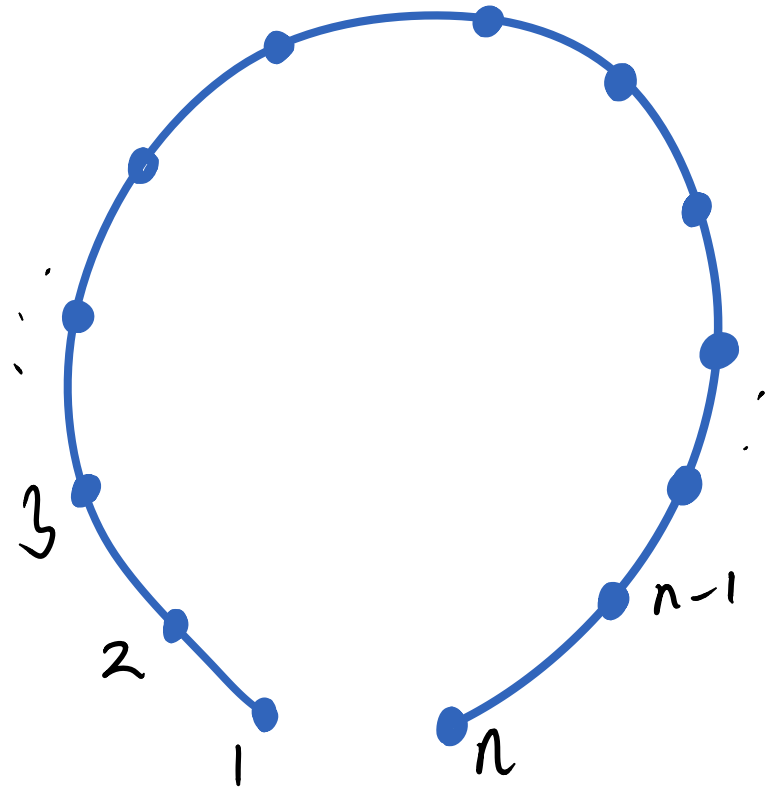
\mathcal{E} is stronger than cut approx



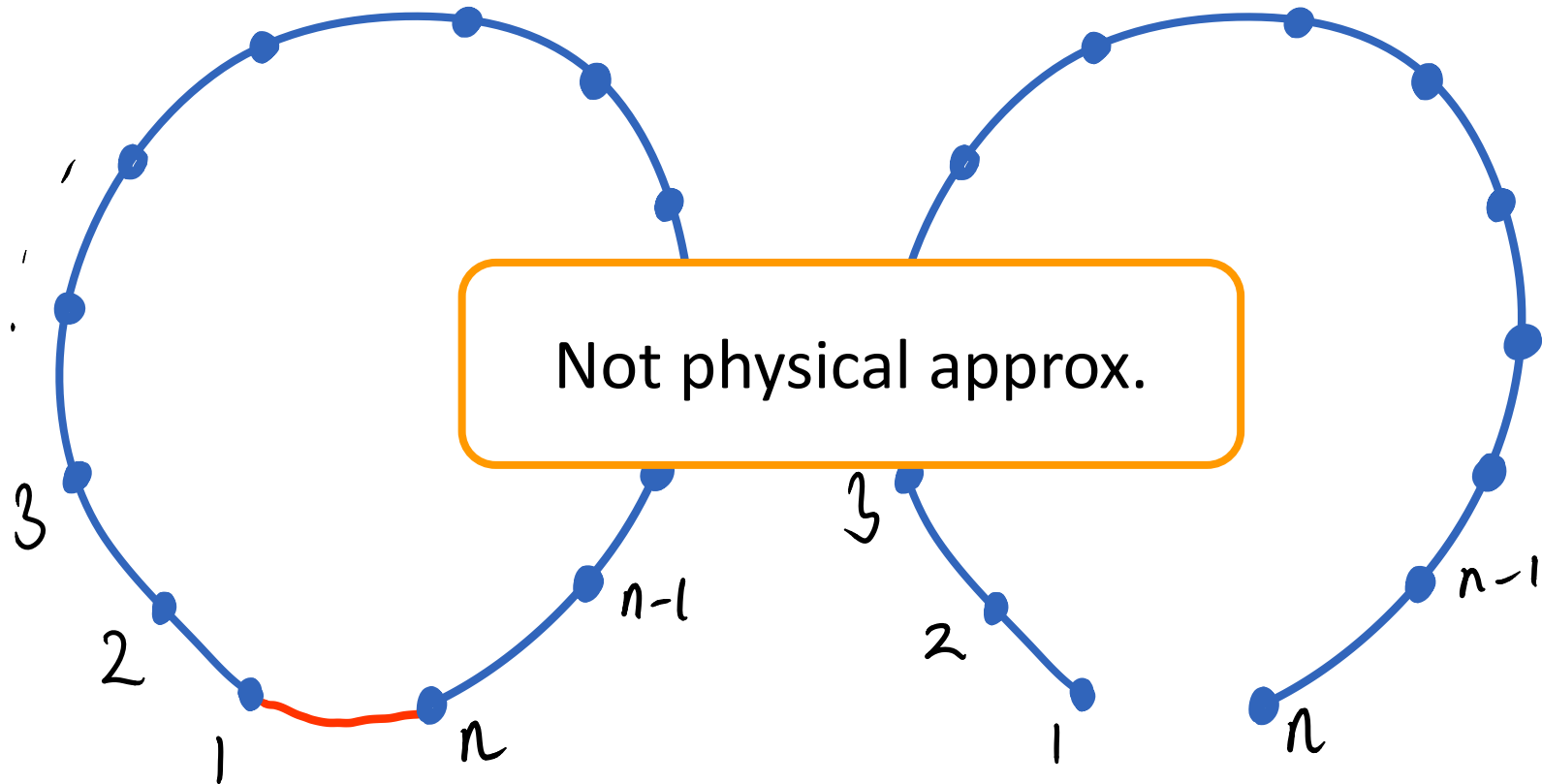
$$\mathcal{E}_q = n-1 + (n-1)^2$$

\gg

$$\mathcal{E}_H = n-1$$



\mathcal{E} is stronger than cut approx

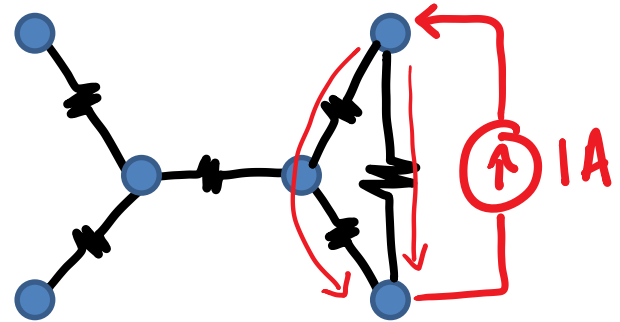


$$\mathcal{E}_q = n-1 + (n-1)^2 \gg \mathcal{E}_H = n-1$$

1. Energy controls physical processes

Electrical Flow:

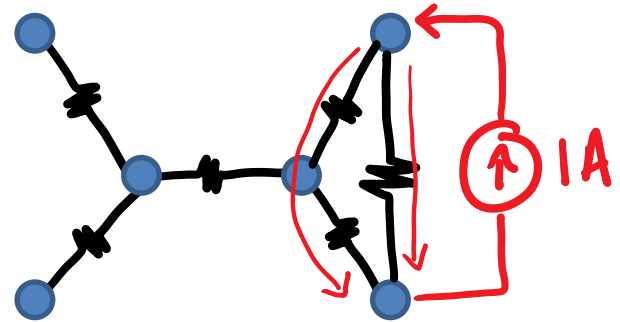
minimizes energy



1. Energy controls physical processes

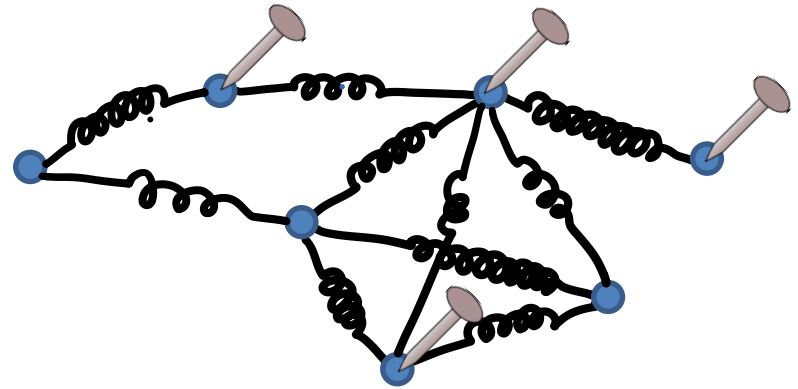
Electrical Flow:

minimizes energy



Spring Network:

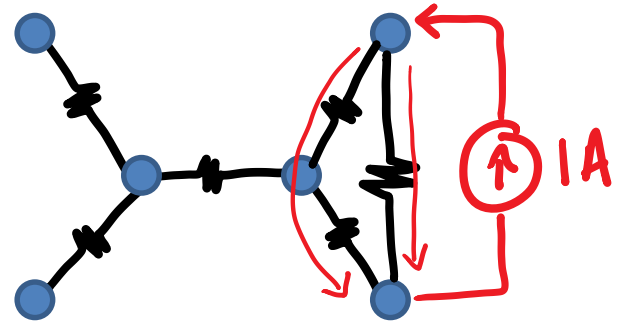
settles at min. energy



1. Energy controls physical processes

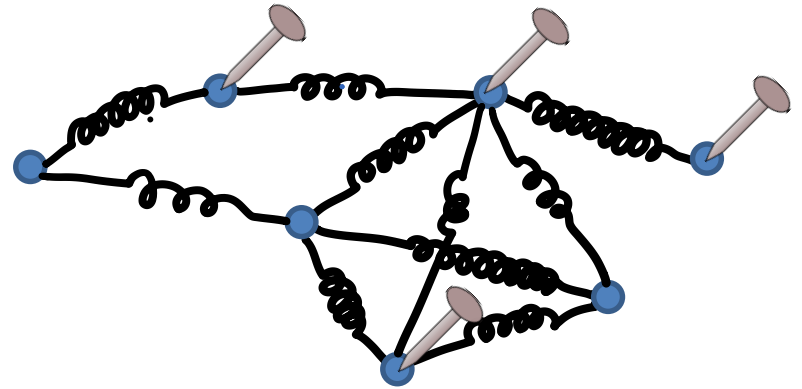
Electrical Flow:

minimizes energy

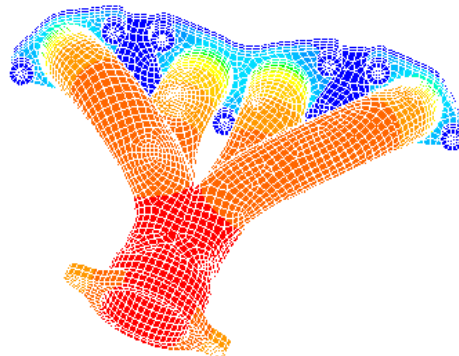


Spring Network:

settles at min. energy



Heat Flow:



1. Energy controls physical processes


Electrical Flow:

minimizes energy

Spring Network:

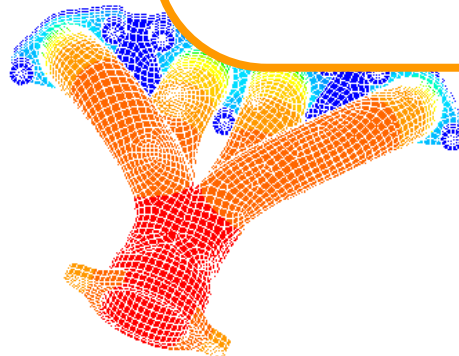
settles at minimum energy

Heat Flow:



Solving any of these reduces to solving a Laplacian linear system

$$Lx = b$$



1. Solving $Lx = b$ fast [ST'04]

$x^T L_G x \sim x^T L_H x$: can solve systems

in L_G by solving systems in L_H .

1. Solving $Lx = b$ fast [ST'04]

$x^T L_G x \sim x^T L_H x$: can solve systems

in L_G by solving systems in L_H .

Naïve:	$O(n^3)$
FMM, Williams'11:	$O(n^{2.373})$
ST'04	$O(m \log^{30} n)$
KMP'10	$O(m \log n)$

...

1. Solving $Lx = b$ fast [ST'04]

$x^T L_G x \sim x^T L_H x$: can solve systems
in L_G by solving systems in L_H .

Naïve:	$O(n^3)$
FMM, Williams'11:	$O(n^{2.373})$
ST'04	$O(m \log^{30} n)$
KMP'10	$O(m \log n)$

Thm [ST'04]

$\forall G$ can find H with
 $O(n \log^8 n)$ edges.

1. Solving $Lx = b$ fast [ST'04]

$x^T L_G x \sim x^T L_H x$: can solve systems

in L_G by solving systems in L_H .

$$Lx = b$$

Electrical Flow

Heat Flow

Spring Network

1. Solving $Lx = b$ fast [ST'04]

$x^T L_G x \sim x^T L_H x$: can solve systems

in L_G by solving systems in L_H .

$$Lx = b$$

Electrical Flow

Heat Flow

Spring Network

Max Flow [CKMST11, LRS13, M13]
Random Spanning Tree [KM08]
Resistance Distance [SS08]

Graph Partitioning [OSV11]
Regression on Graphs [ZGL03]
...

2. Spectral Graph Theory

Courant-Fischer Thm: $\mathbf{x}^T \mathbf{L}_G \mathbf{x}$ determines $\lambda_i(L_G)$

$$\lambda_{max}(L) = \max \frac{\mathbf{x}^T L \mathbf{x}}{\mathbf{x}^T \mathbf{x}} \quad \lambda_{min}(L) = \min \frac{\mathbf{x}^T L \mathbf{x}}{\mathbf{x}^T \mathbf{x}}$$

Thus for physical approx. \mathbf{H} of \mathbf{G} :

$$(1 - \epsilon) \lambda_i(G) \leq \lambda_i(H) \leq (1 + \epsilon) \lambda_i(G)$$

Now \mathbf{H} inherits many combinatorial properties:

random walks, colorings, spanning trees, etc.

3. Natural Setting

Spectral formulation more tractable:
 $\mathbf{x}^T \mathbf{L} \mathbf{x}$ better behaved over \mathbf{R}^n than $\{0,1\}^n$.

Cuts are discrete objects.

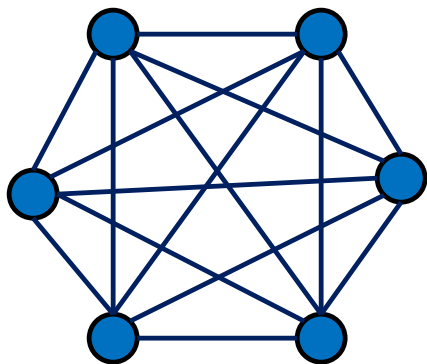
*Quadratic forms are continuous objects,
with a richer set of global transformations.*

Examples

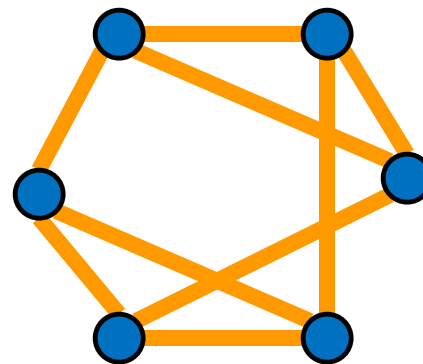
Example: The Complete Graph

$G = K_n$

$H = \text{random } d\text{-regular } \times (n/d)$



$$|E_G| = O(n^2)$$



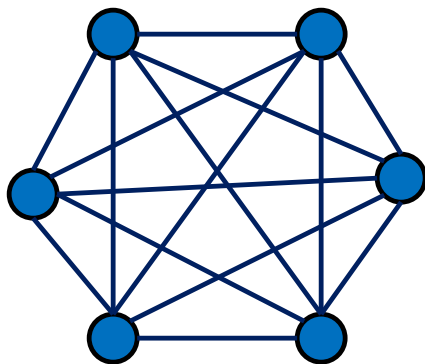
$$|E_H| = O(dn)$$

$$\forall S \subset V, \quad \frac{wt_G(\delta S)}{wt_{(n/d)H}(\delta S)} \simeq 1 \pm \epsilon$$

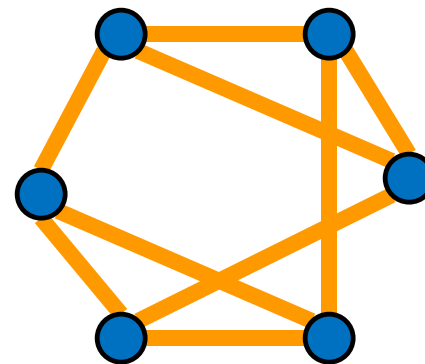
Example: The Complete Graph

$G = K_n$

$H = \text{random } d\text{-regular } \times (n/d)$



$$|E_G| = O(n^2)$$



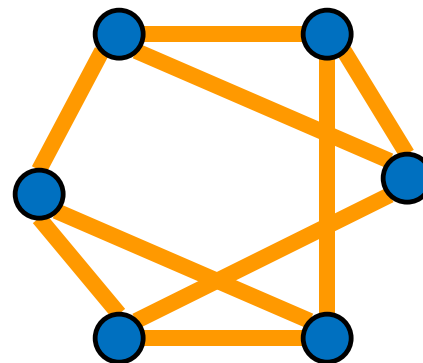
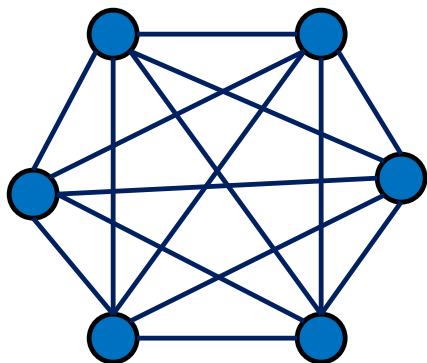
$$|E_H| = O(dn)$$

$$\forall x, \quad \frac{x^T L_G x}{x^T L_H x} \simeq 1 \pm \epsilon$$

Example: The Complete Graph

$G = K_n$

$H = \text{random } d\text{-regular } \times (n/d)$



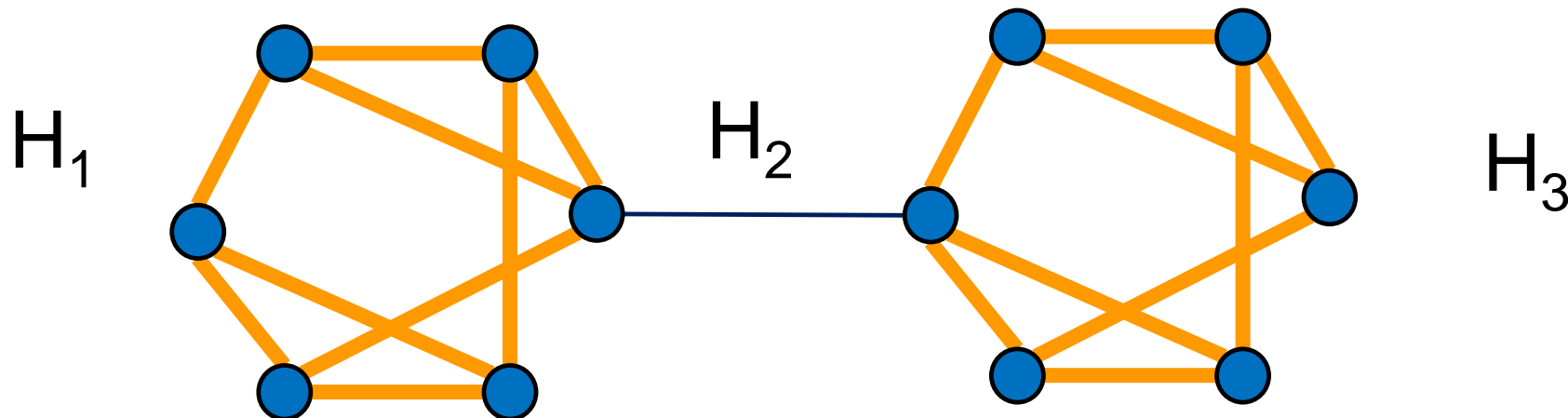
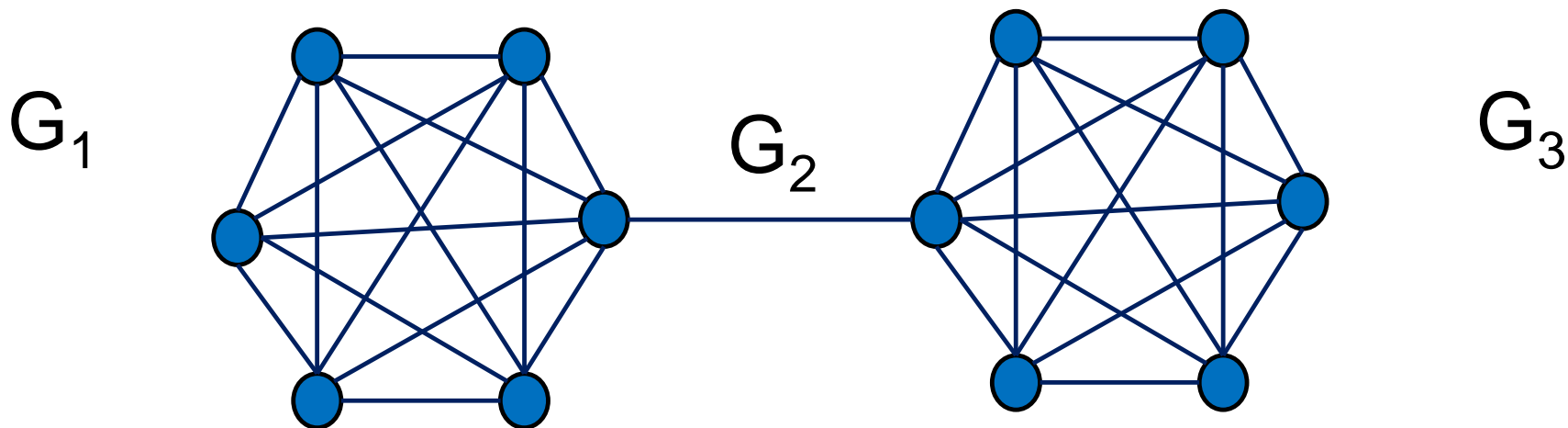
$$|E_G| = O(n^2)$$

$$|E_H| = O(dn)$$

$$\forall x, \quad \frac{x^T L_G x}{x^T L_H x} \simeq 1 \pm \epsilon$$

$$d = 2/\epsilon^2$$

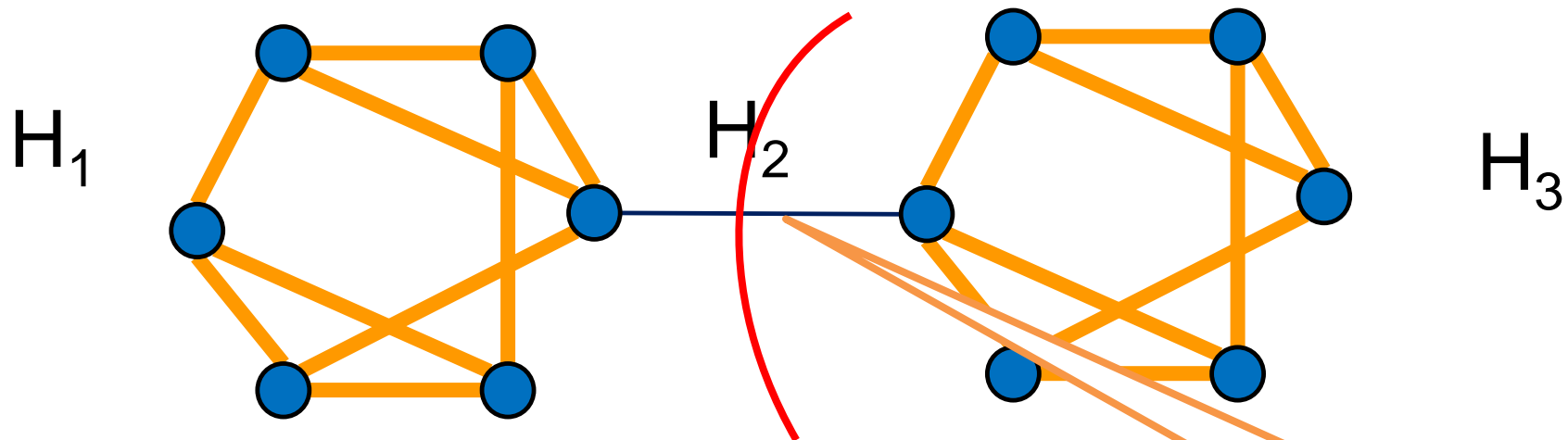
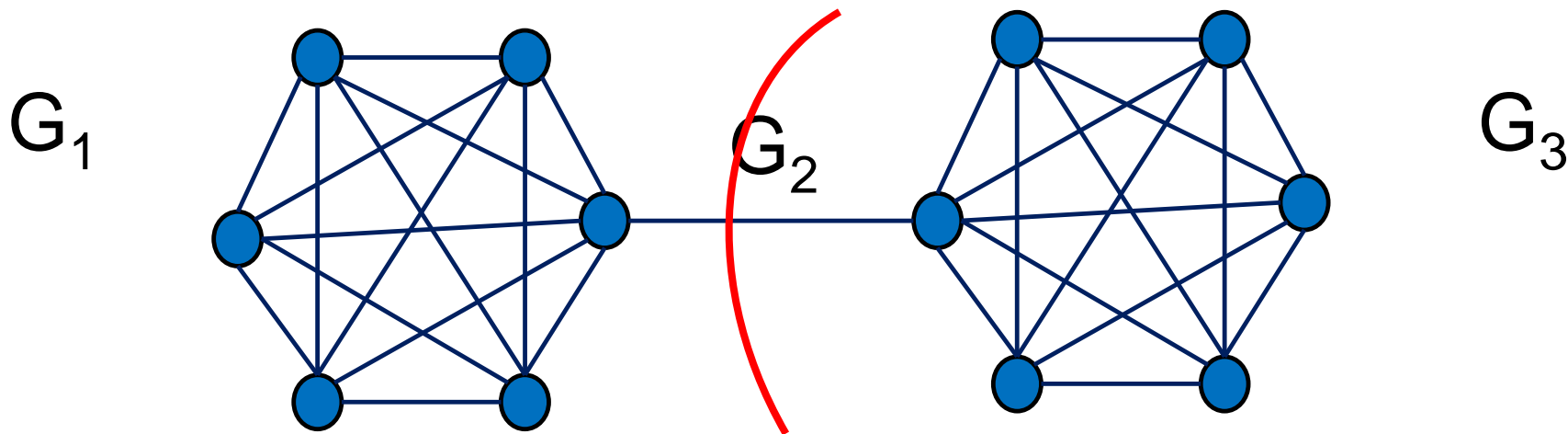
Example: Dumbbell



$$G = G_1 + G_2 + G_3$$

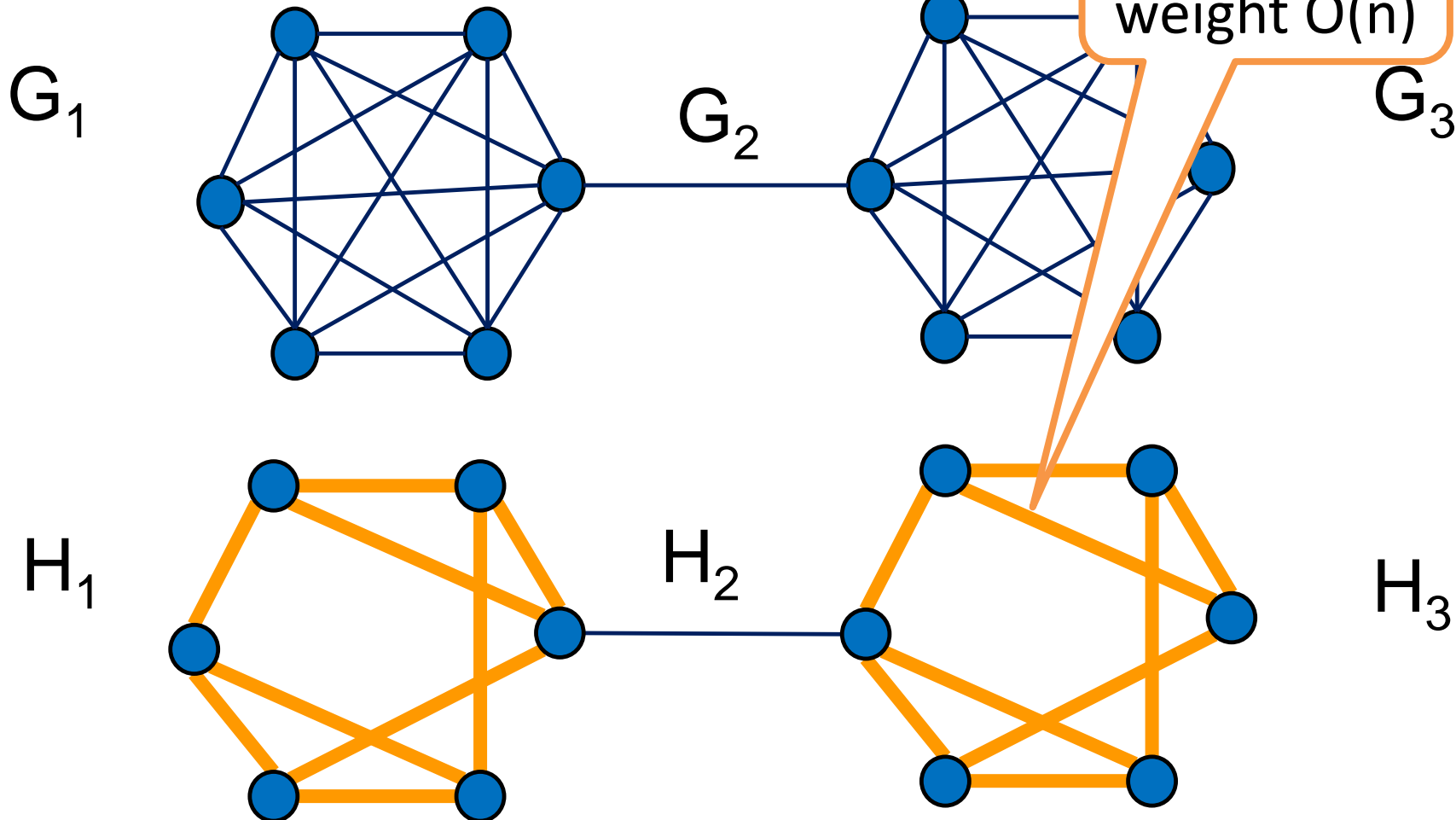
$$x^T G x = x^T G_1 x + x^T G_2 x + x^T G_3 x$$

Example: Dumbbell



must have weight 1

Example: Dumbbell



Will show how to do this
for every graph...

Theorem. Every weighted graph \mathbf{G} has a weighted subgraph \mathbf{H} with at most $9n \log n / \epsilon^2$ edges s.t.

$$L_G \preceq L_H \preceq (1 + \epsilon)L_G.$$

Moreover, H can be found in time $O^\sim(m/\epsilon^2)$.

Basic idea: **Random Sampling**

Choose each edge e with some probability p_e .

take k independent samples.

If included, add to H with weight $1/kp_e$.

$$\mathbb{E}[L_H] = \mathbb{E}[L_e] = \sum_{e \in G} p_e \cdot \frac{b_e b_e^T}{p_e} = L_G.$$

Basic idea: Random Sampling

Choose each edge e with some probability p_e .

take k independent samples.

If included, add to H with weight $1/kp_e$.

$$\mathbb{E}[L_H] = \mathbb{E}[L_e] = \sum_{e \in G} p_e \cdot \frac{b_e b_e^T}{p_e} = L_G.$$

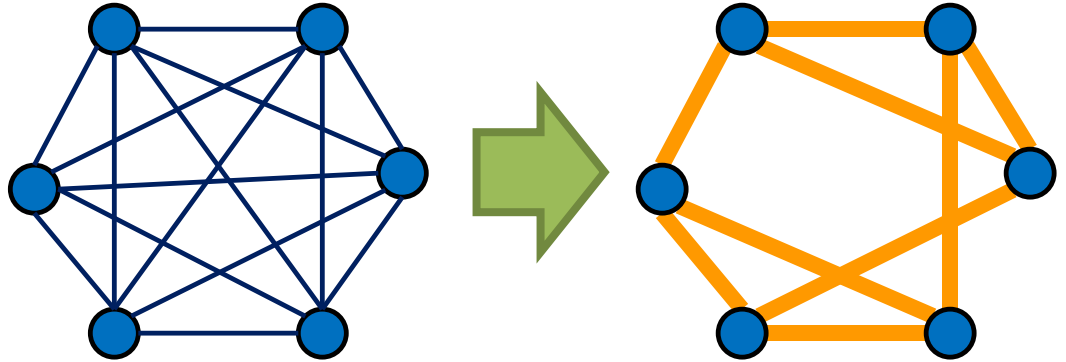
Law of large numbers: as $k \rightarrow \infty$,

$$L_H \rightarrow L_G$$

Question: how fast does this happen?

Attempt: Uniform Sampling

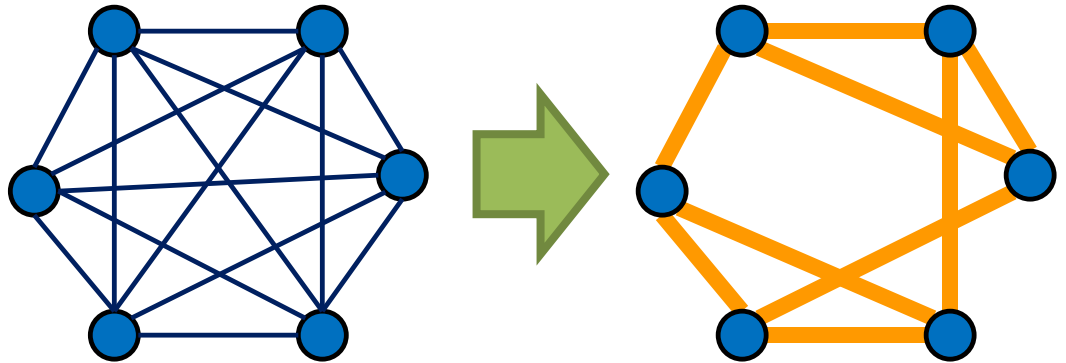
Works for K_n :



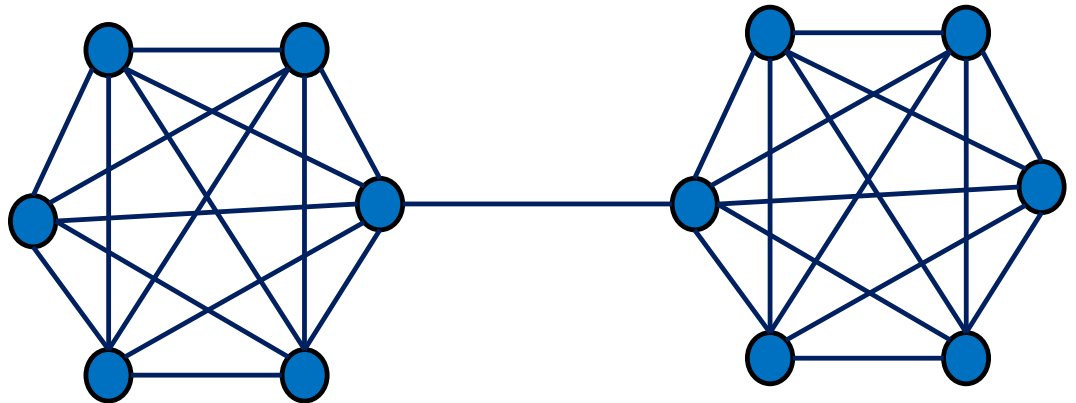
** $O(n \log n)$ samples for i.i.d. edges*

Attempt: Uniform Sampling

Works for K_n :

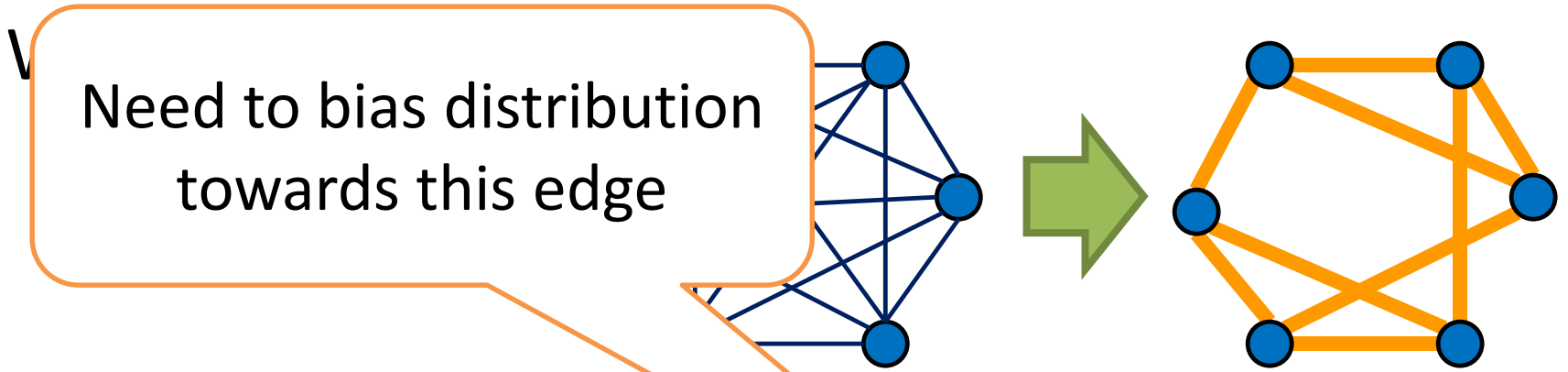


Bad for dumbbell:

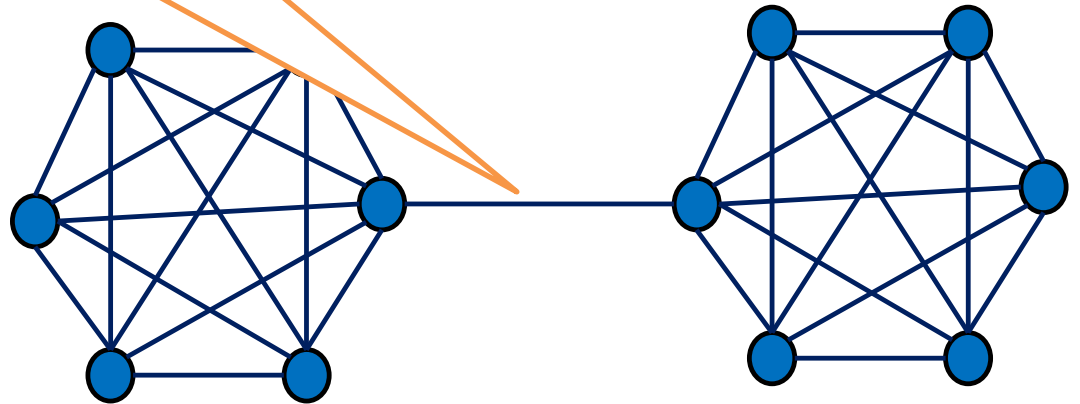


Need $\Omega(m)$ samples to catch the bridge edge.

Attempt: Uniform Sampling



Bad for dumbbell:



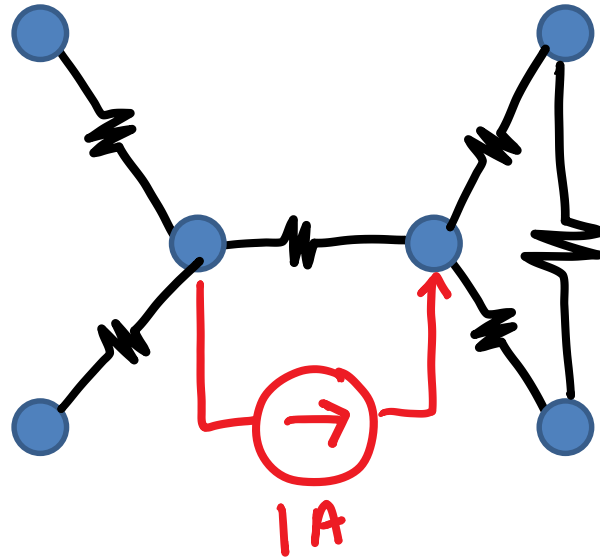
Need $\Omega(m)$ samples to catch the bridge edge.

Effective Resistance

$R_{\text{eff}}(e)$ = energy dissipation when a unit current is injected/removed across ends of e .

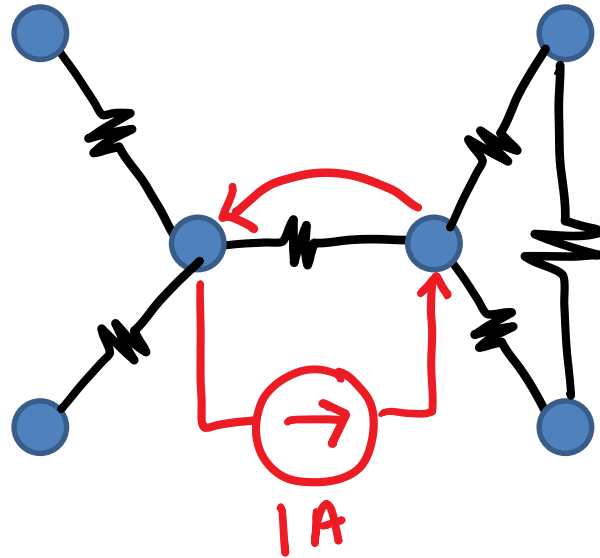
Effective Resistance

Reff(e) = energy dissipation when a unit current is injected/removed across ends of e .



Effective Resistance

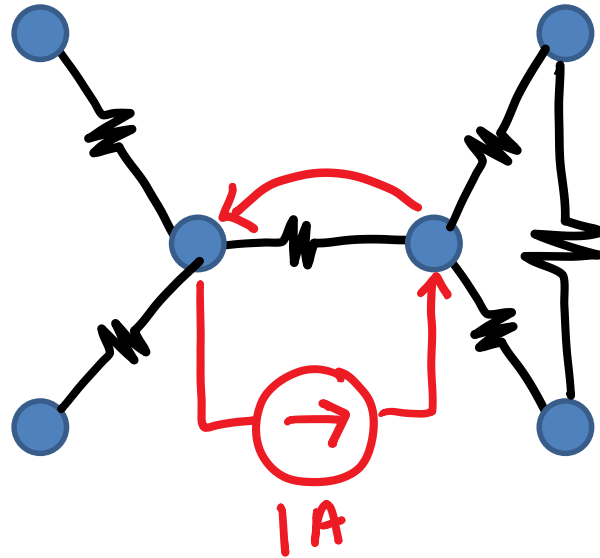
Reff(e) = energy dissipation when a unit current is injected/removed across ends of e .



electrical flow minimizes energy

Effective Resistance

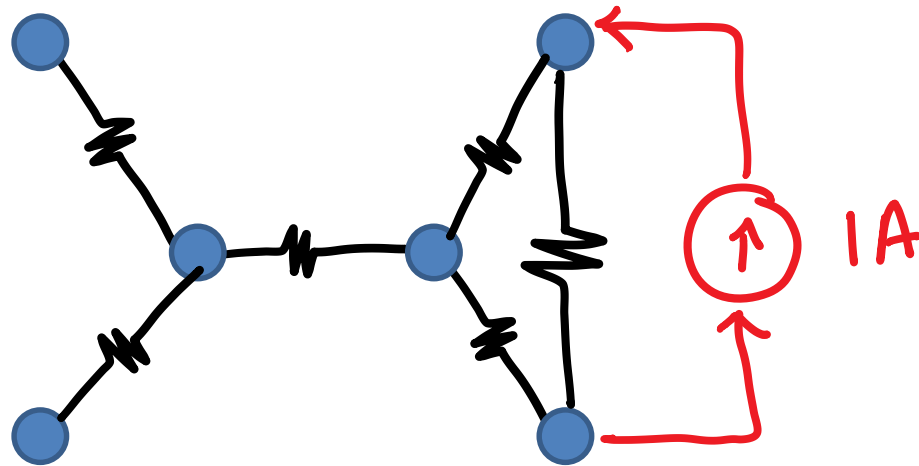
Reff(e) = energy dissipation when a unit current is injected/removed across ends of e .



$$\mathbf{Reff}(e) = 1^2 = 1$$

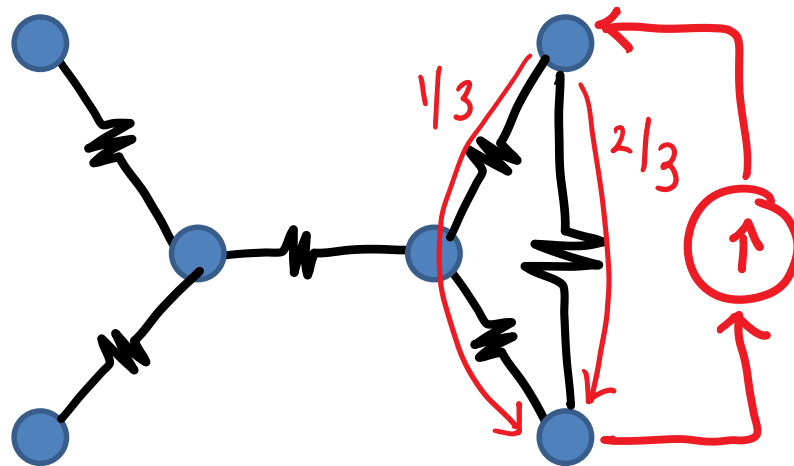
Effective Resistance

Reff(e) = energy dissipation when a unit current is injected/removed across ends of e .



Effective Resistance

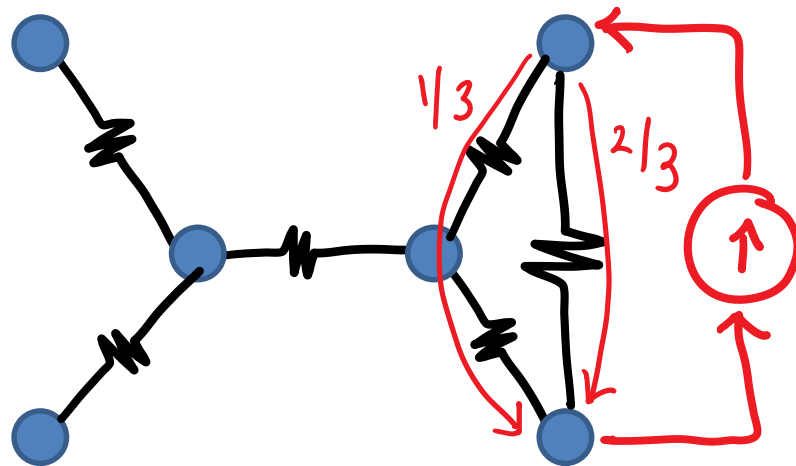
Reff(e) = energy dissipation when a unit current is injected/removed across ends of e .



$$\mathbf{Reff}(e) = (2/3)^2 + (1/3)^2 + (1/3)^2 = 2/3$$

Effective Resistance

Reff(e) = energy dissipation when a unit current is injected/removed across ends of e .



many alternate paths = lower resistance
= **electrically “redundant”**

Effective Resistance

Reff(e) = energy dissipation when a unit current is injected/removed across ends of e .

few alternate paths = high resistance
= **electrically “important”**

many alternate paths = lower resistance
= **electrically “redundant”**

Effective Resistance

$\text{Reff}(e)$ = energy dissipation when a unit current is injected/removed across ends of e .

few alternate paths = high resistance
= **electrically “important”**

many alternate paths = lower resistance
= **electrically “redundant”**

Idea: sample edges according to effective resistances.

Theorem. Every weighted graph \mathbf{G} has a weighted subgraph \mathbf{H} with at most $9n \log n / \epsilon^2$ edges s.t.

$$L_G \preceq L_H \preceq (1 + \epsilon)L_G.$$

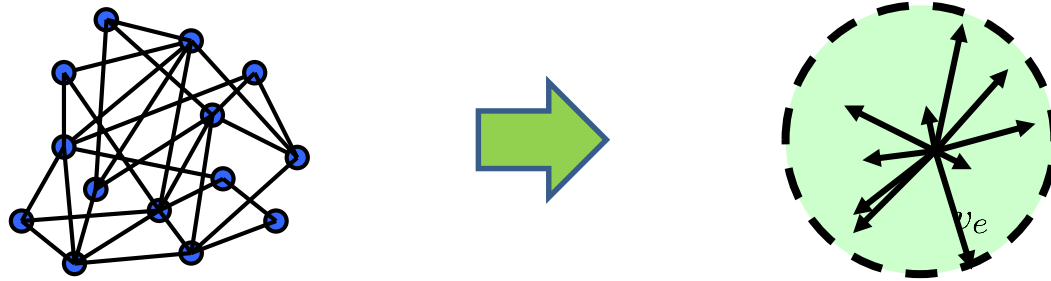
Moreover, H can be found in time $O^\sim(m/\epsilon^2)$.

Algorithm: sample $9n \log n / \epsilon^2$ edges independently according to effective resistances.

3 Step Proof

1. Reduction to a linear algebra problem
2. Solution of linear algebra problem by random matrix theory.
3. Fast computation of sampling probabilities

[Spielman-S'08]



Part 1: Reduction to Linear Algebra

Original Goal

Given G

Find sparse H

satisfying $L_G \preceq L_H \preceq \kappa \cdot L_G$

Outer Product Expansion

Recall:

$$L_G = \sum_{ij \in E} (\delta_i - \delta_j)(\delta_i - \delta_j)^T = \sum_{e \in E} b_e b_e^T.$$

Outer Product Expansion

Recall:

$$L_G = \sum_{ij \in E} (\delta_i - \delta_j)(\delta_i - \delta_j)^T = \sum_{e \in E} b_e b_e^T.$$

For a weighted subgraph \mathbf{H} :

$$L_H = \sum_{e \in E} s_e b_e b_e^T$$

where $s_e = \text{wt}(e)$ in \mathbf{H} .

Original Goal

Given G

Find sparse H

satisfying

$$L_G \preceq L_H \preceq \kappa \cdot L_G$$

Original Goal

Given $L_G = \sum_{e \in G} b_e b_e^T$ $b_{ij} = \delta_i - \delta_j$

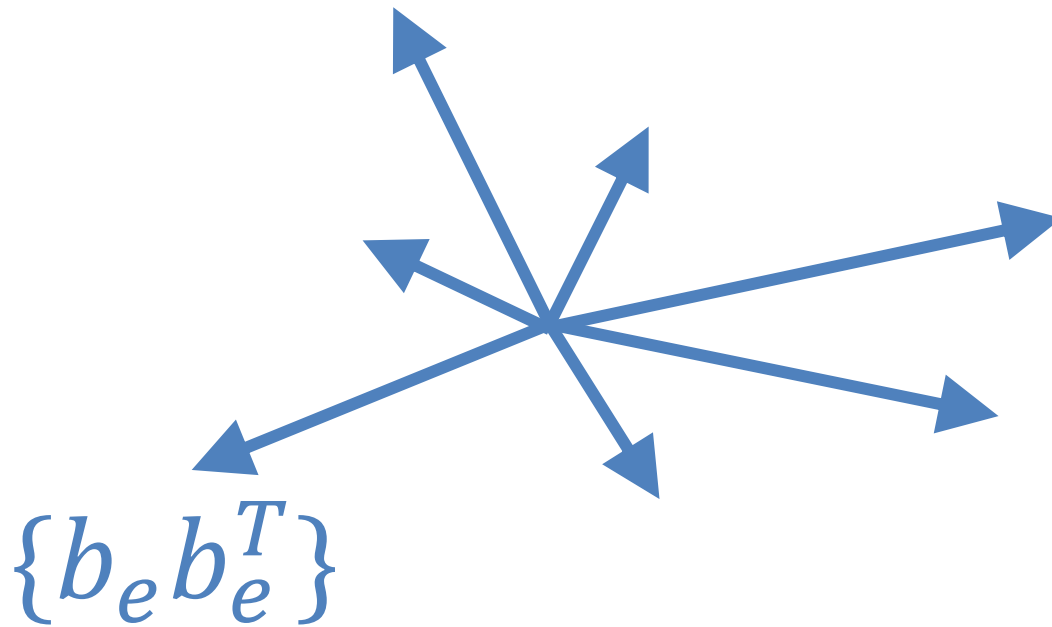
Find **sparse**

$$s_e \geq 0$$

satisfying

$$L_G \preceq L_H = \sum_{e \in G} s_e b_e b_e^T \preceq \kappa \cdot L_G$$

Quadratic Forms as Ellipsoids

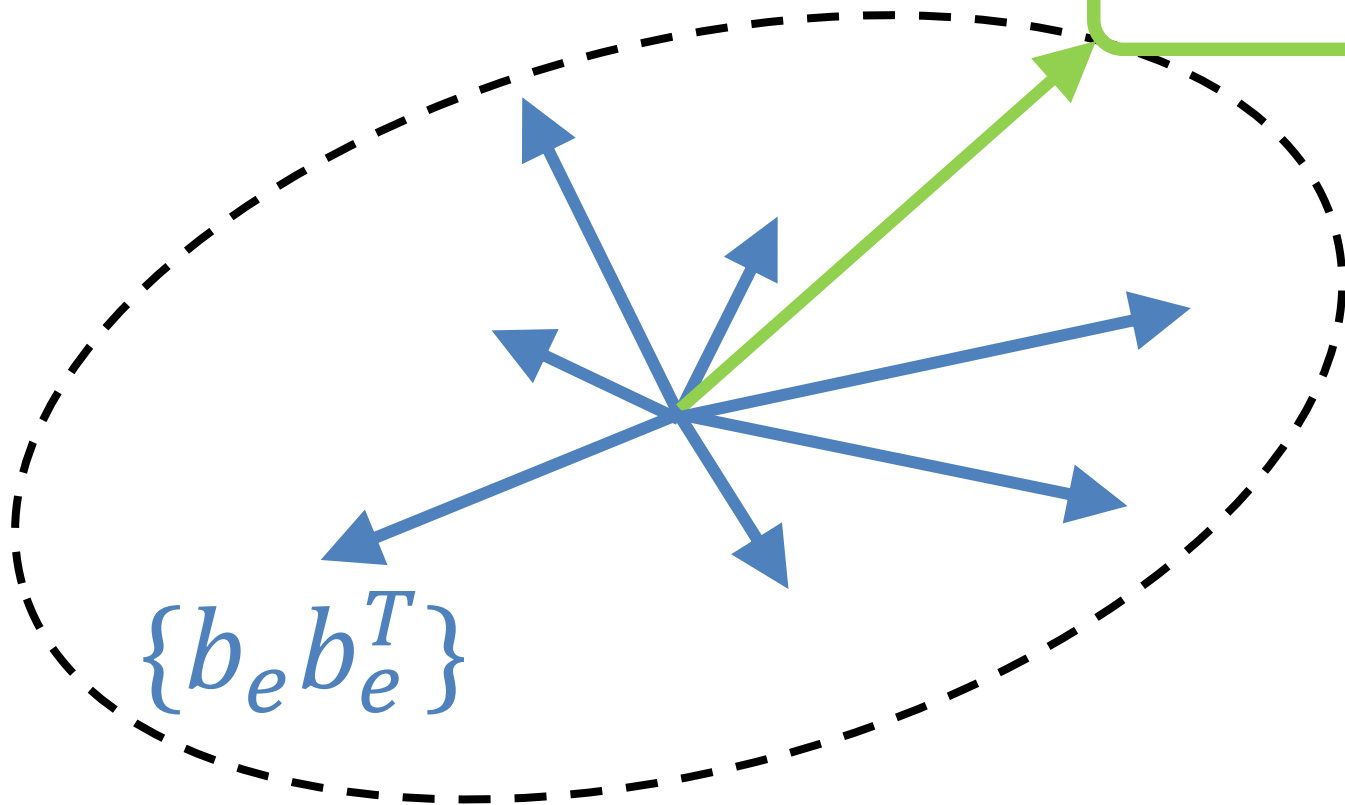


$$L_G = \sum_{e \in G} b_e b_e^T \quad b_{ij} = \delta_i - \delta_j$$

Quadratic Forms as Ellipsoids

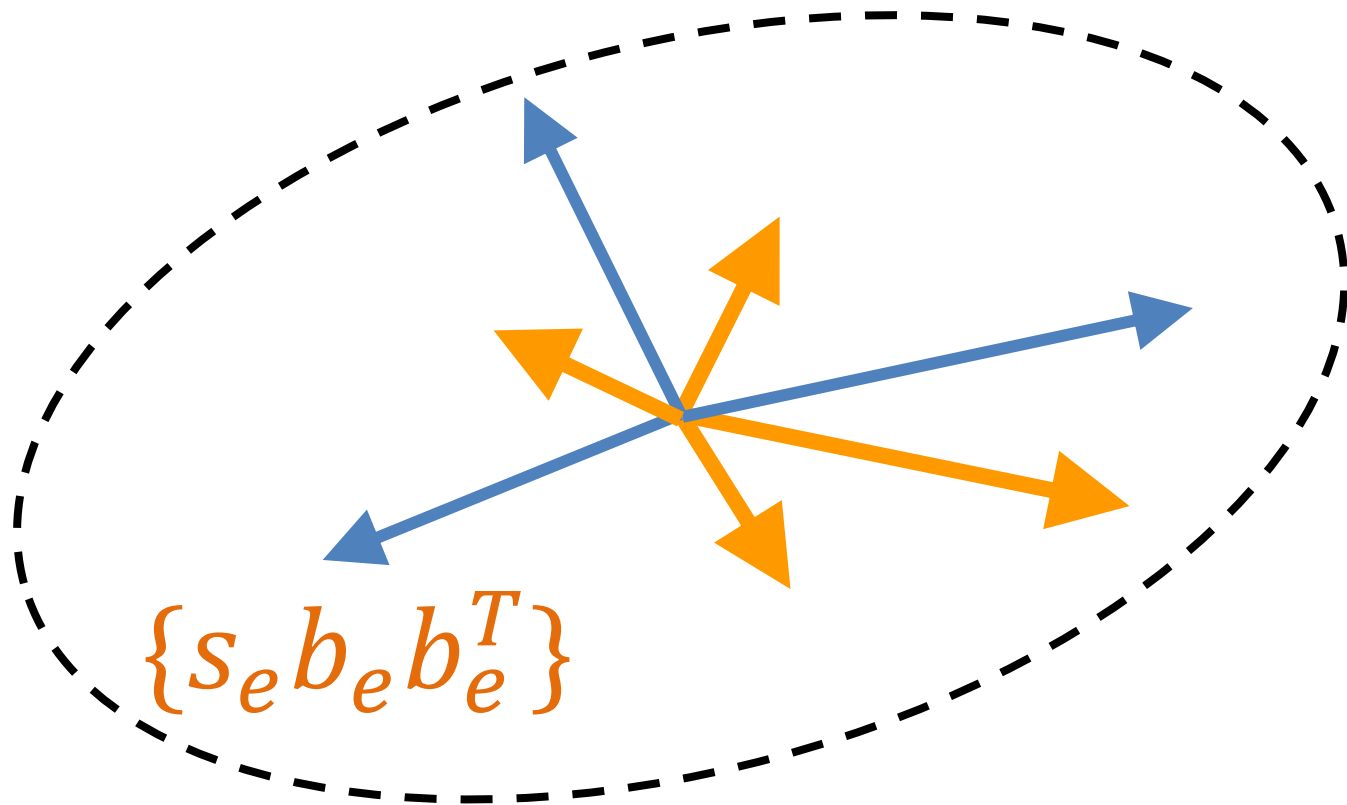
Consider level sets

$$x^T L x \leq 1$$



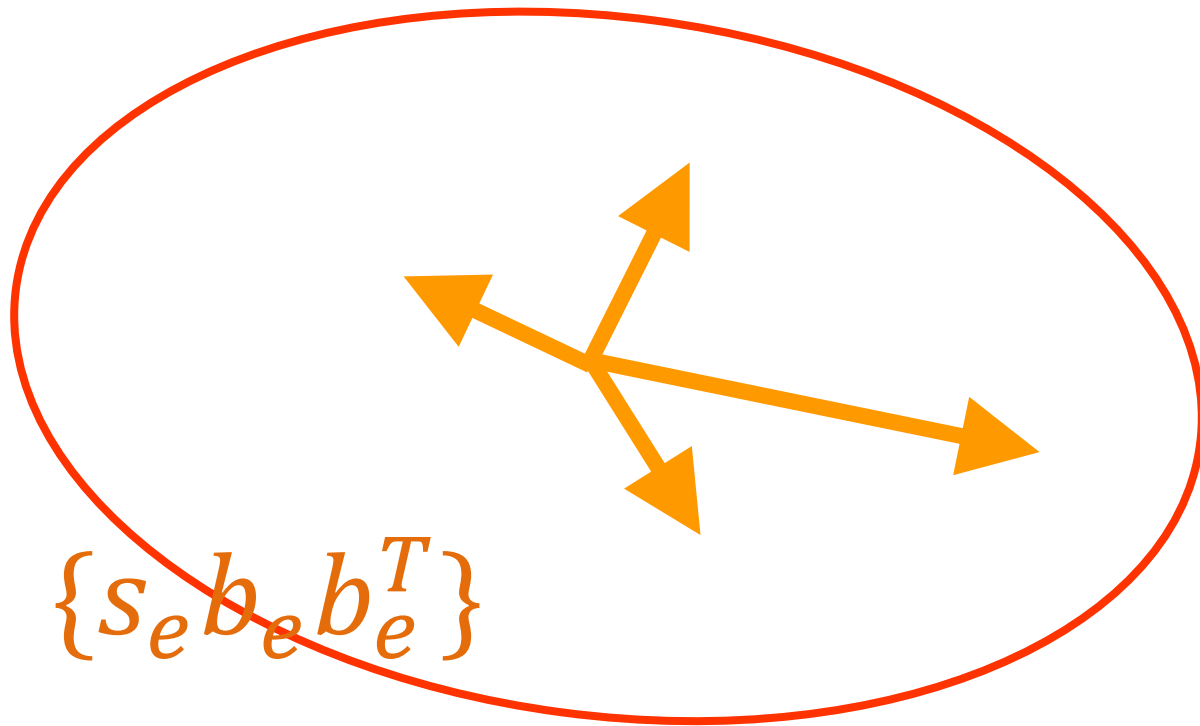
$$L_G = \sum_{e \in G} b_e b_e^T \quad b_{ij} = \delta_i - \delta_j$$

Quadratic Forms as Ellipsoids



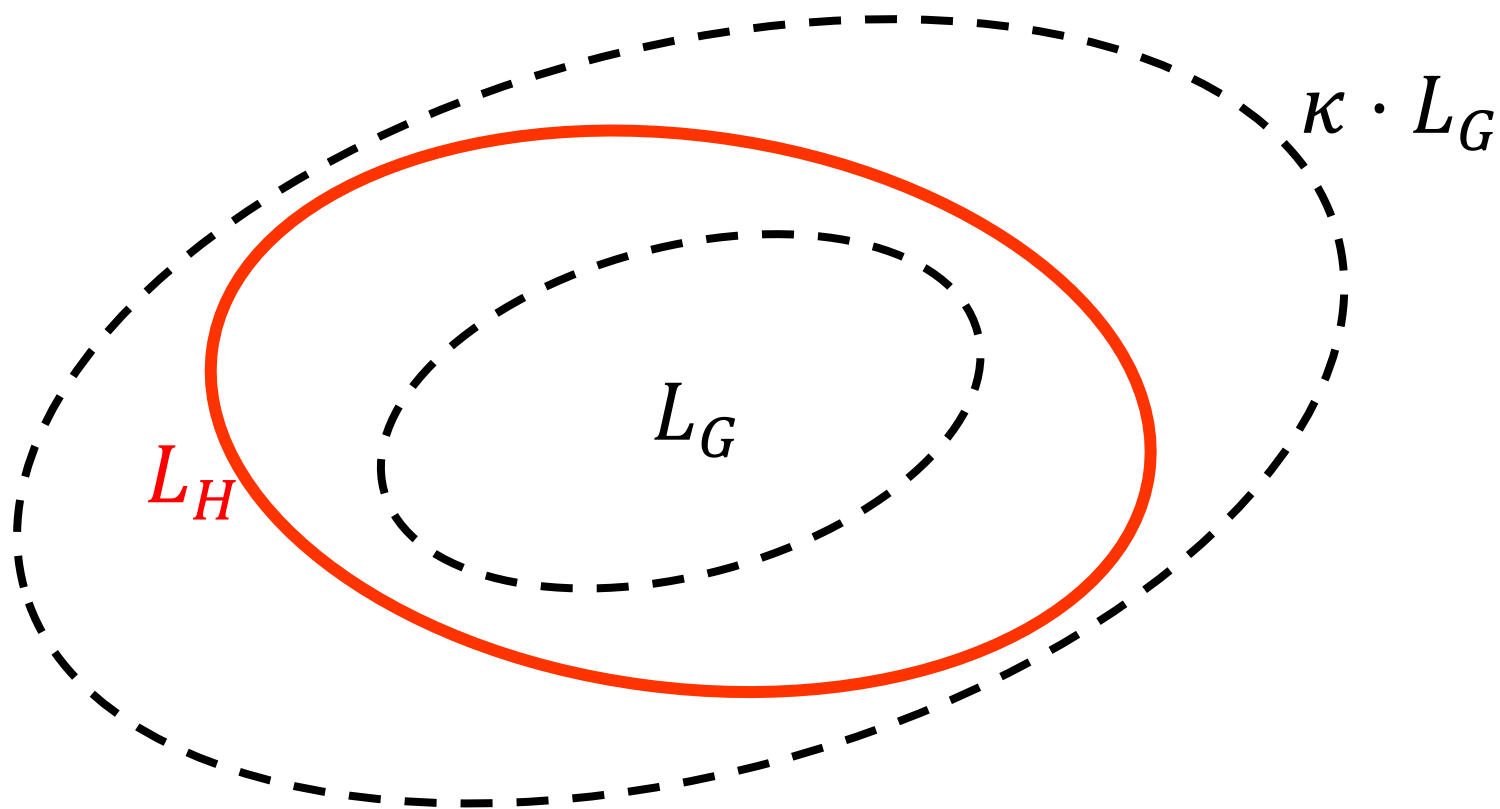
$$L_H = \sum_{e \in E} s_e b_e b_e^T$$

Quadratic Forms as Ellipsoids



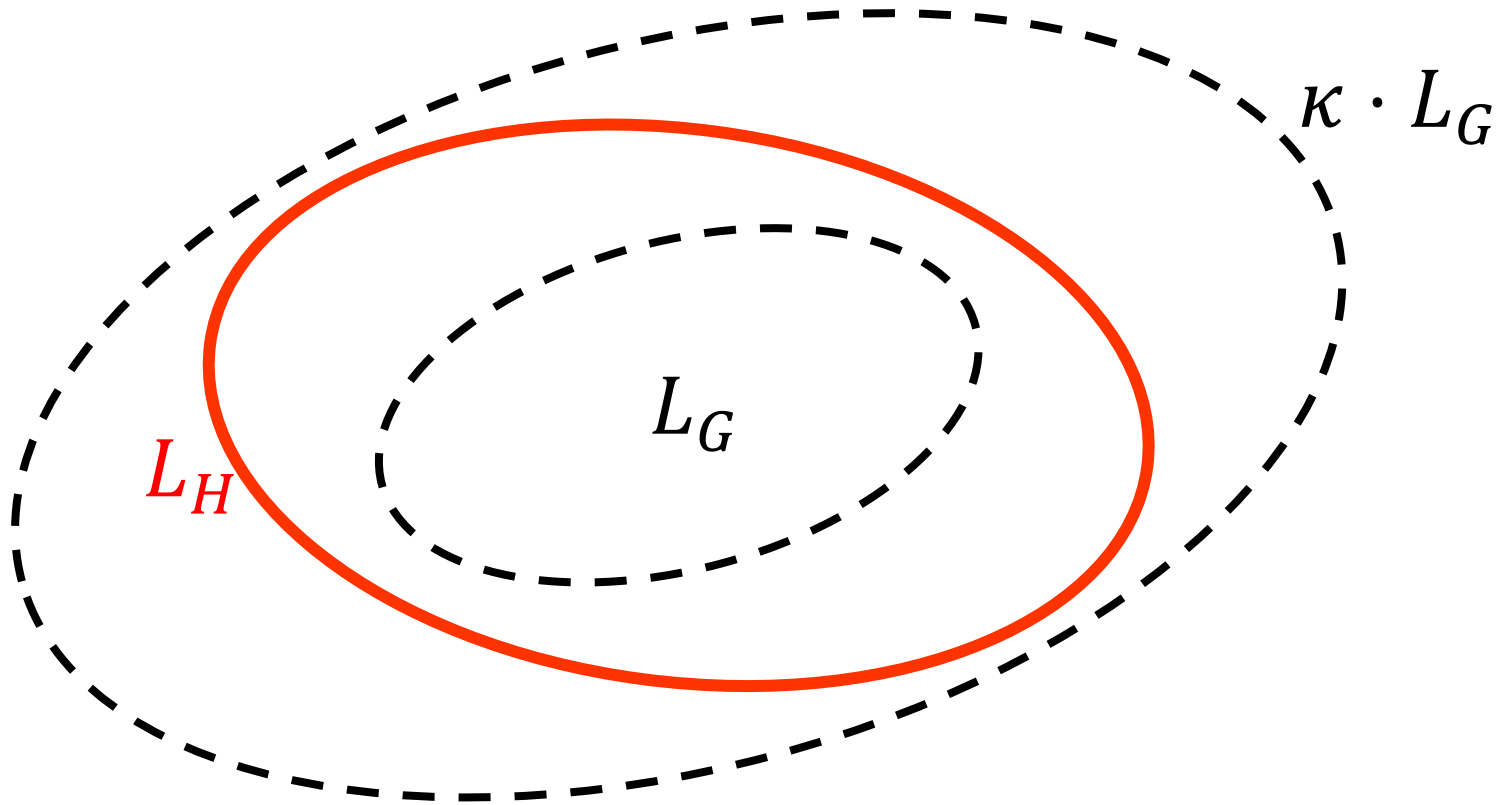
$$L_H = \sum_{e \in E} s_e b_e b_e^T$$

Containment of Ellipsoids



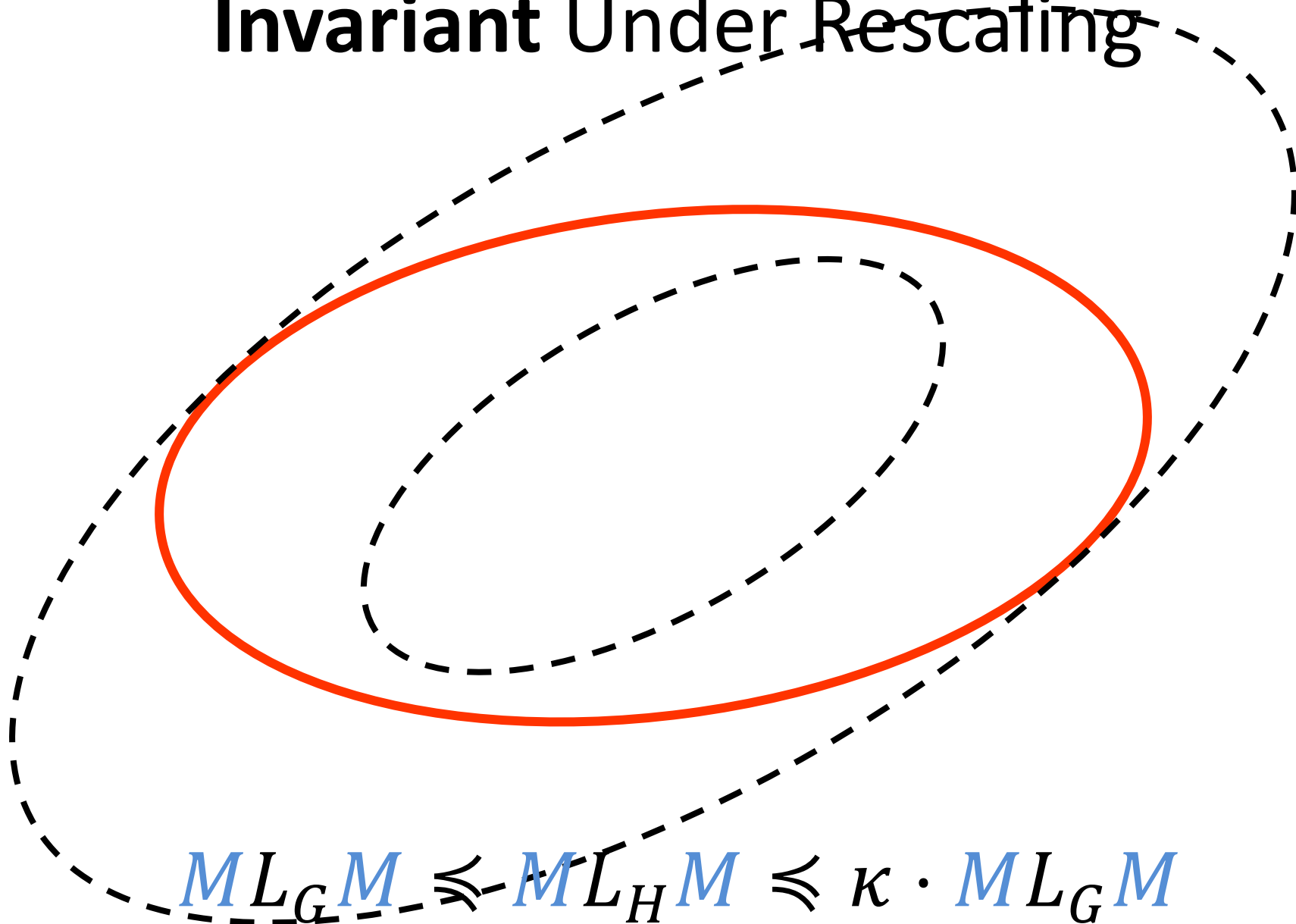
$$L_G \preceq L_H \preceq \kappa \cdot L_G$$

Invariant Under Rescaling



$$ML_G M \cong ML_H M \cong \kappa \cdot ML_G M$$

Invariant Under Rescaling

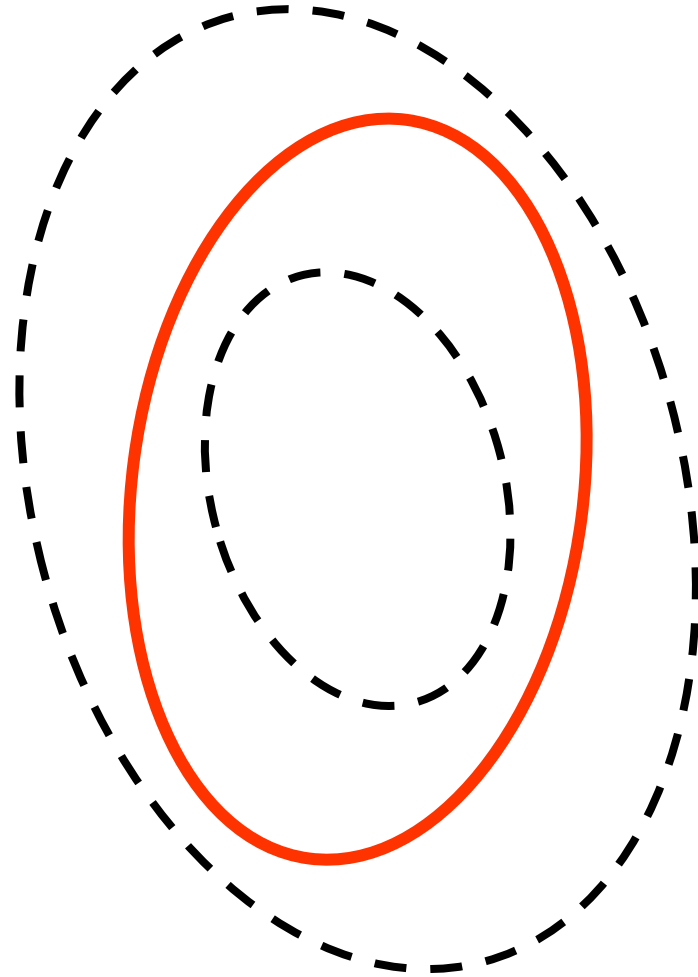


$$ML_G M \cong ML_H M \cong \kappa \cdot ML_G M$$

Invariant Under Rescaling

$$ML_G M \cong ML_H M \cong \kappa \cdot ML_G M$$

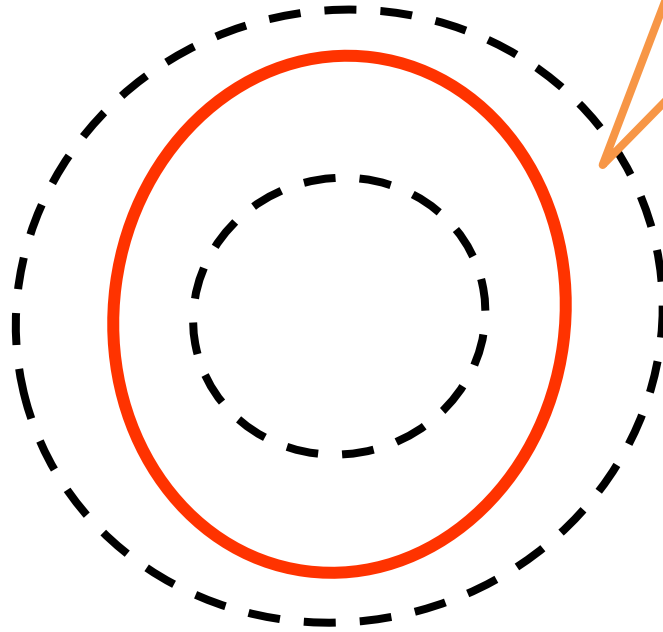
Invariant Under Rescaling



$$ML_G M \cong ML_H M \cong \kappa \cdot ML_G M$$

Invariant Under Re

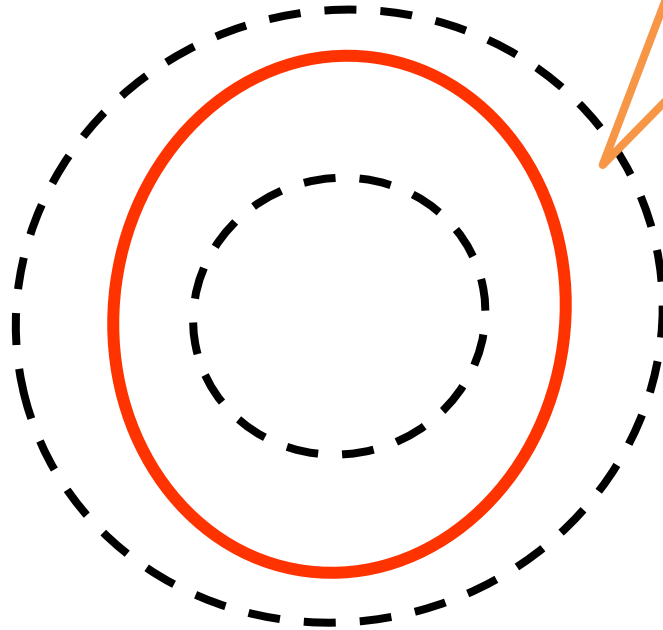
Choose $M = L_G^{-1/2}$



$$L_G^{-1/2} L_G L_G^{-1/2} \preccurlyeq L_G^{-1/2} L_H L_G^{-1/2} \preccurlyeq \kappa \cdot L_G^{-1/2} L_G L_G^{-1/2}$$

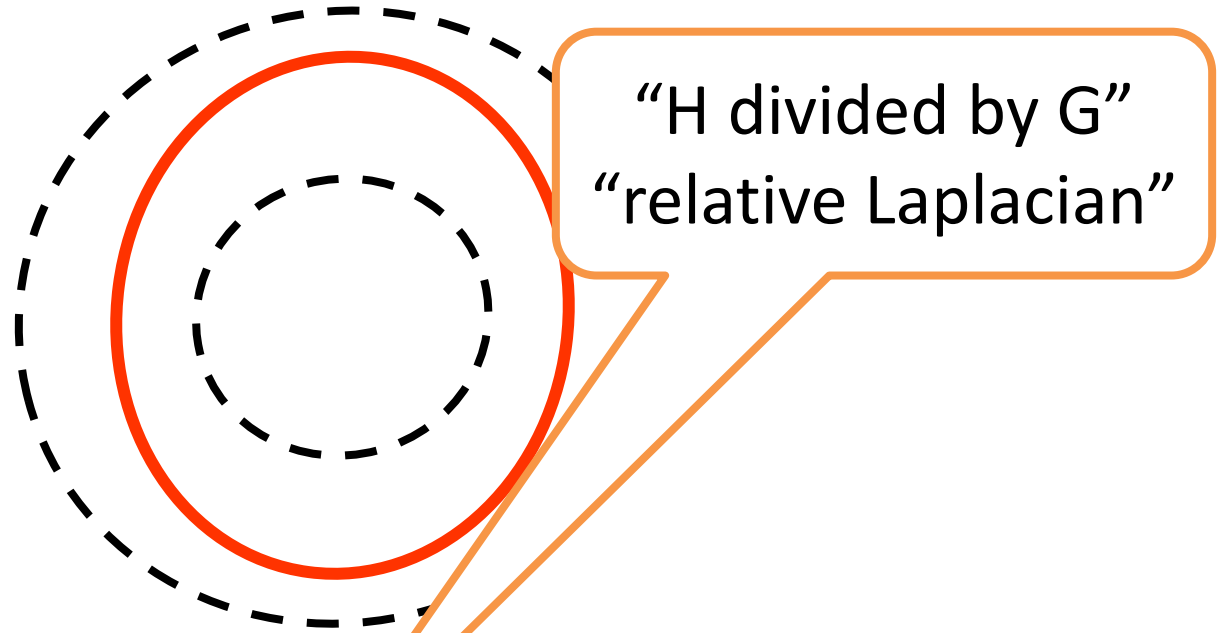
Invariant Under Re

Choose $M = L_G^{-1/2}$



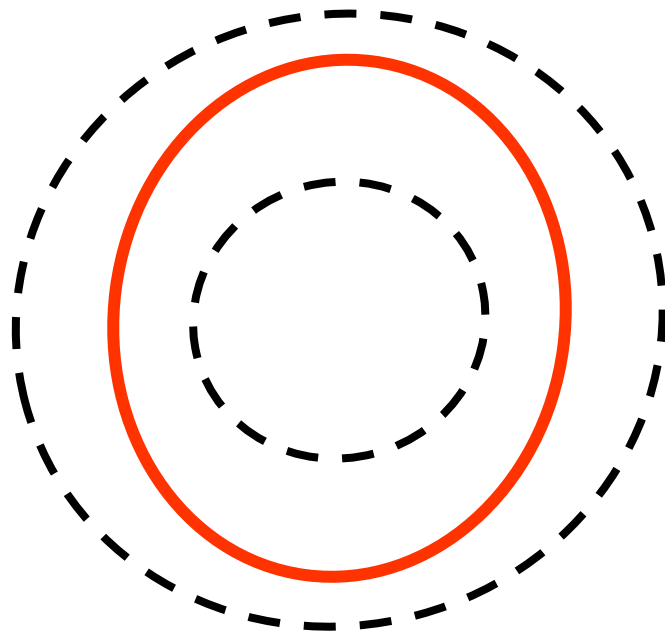
$$I \preceq L_G^{-1/2} L_H L_G^{-1/2} \preceq \kappa \cdot I$$

Invariant Under Rescaling



$$I \preceq L_G^{-1/2} L_H L_G^{-1/2} \preceq \kappa \cdot I$$

Invariant Under Rescaling

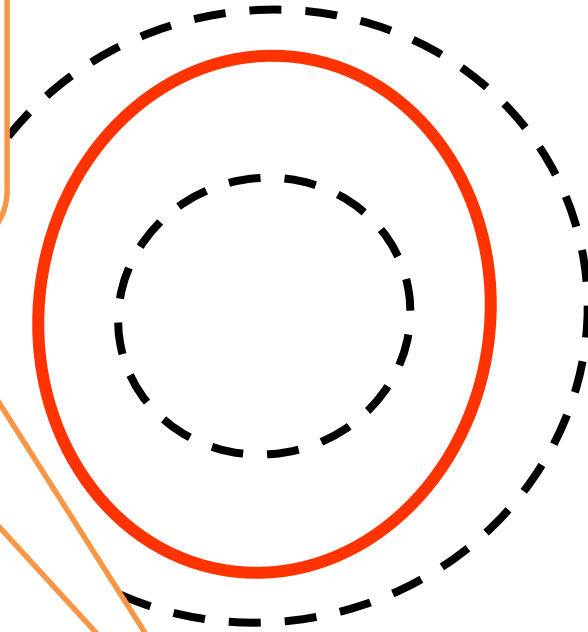


$$I \preceq \sum_e s_e L_G^{-1/2} b_e b_e^T L_G^{-1/2} \preceq \kappa \cdot I$$

Invariant Under Rescaling

Rescaled
incidence vector

$$v_e := L_G^{-1/2} b_e$$



$$I \preceq \sum_e s_e v_e v_e^T \preceq \kappa \cdot I$$

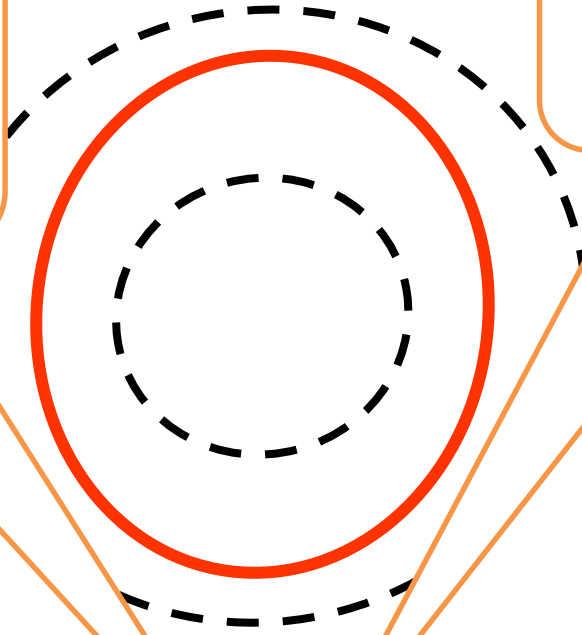
Invariant Under Rescaling

Rescaled
incidence vector

$$v_e := L_G^{-1/2} b_e$$

$$\sum_e v_e v_e^T = I$$

$$I \preceq \sum_e s_e v_e v_e^T \preceq \kappa \cdot I$$



Equivalent Problem

Given $I = \sum_e v_e v_e^T$

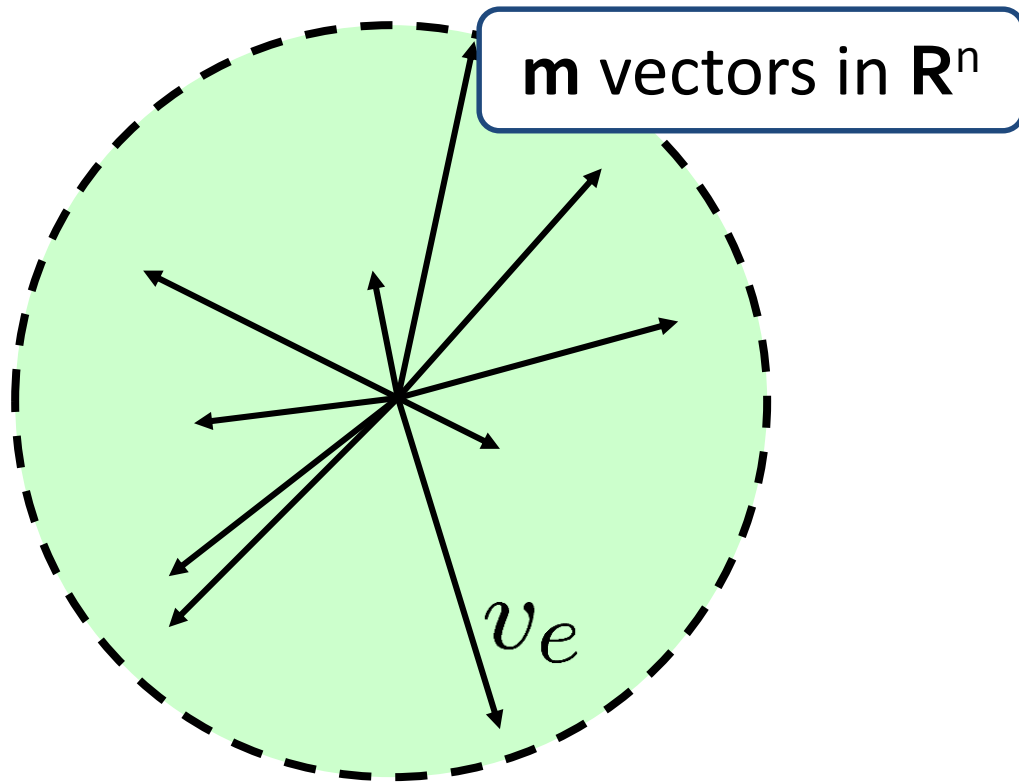
Find **sparse**

$$s_e \geq 0$$

satisfying

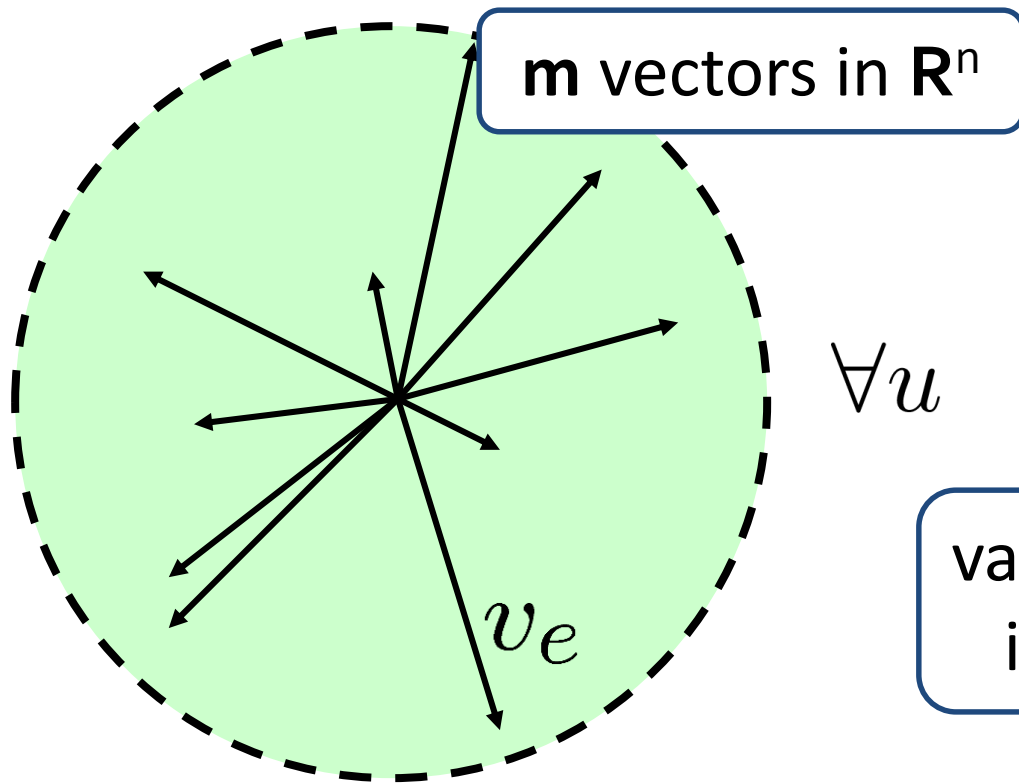
$$I \preceq \sum_{e \in G} s_e v_e v_e^T \preceq \kappa \cdot I$$

Core Problem



$$I = \sum_e v_e v_e^T$$

Core Problem

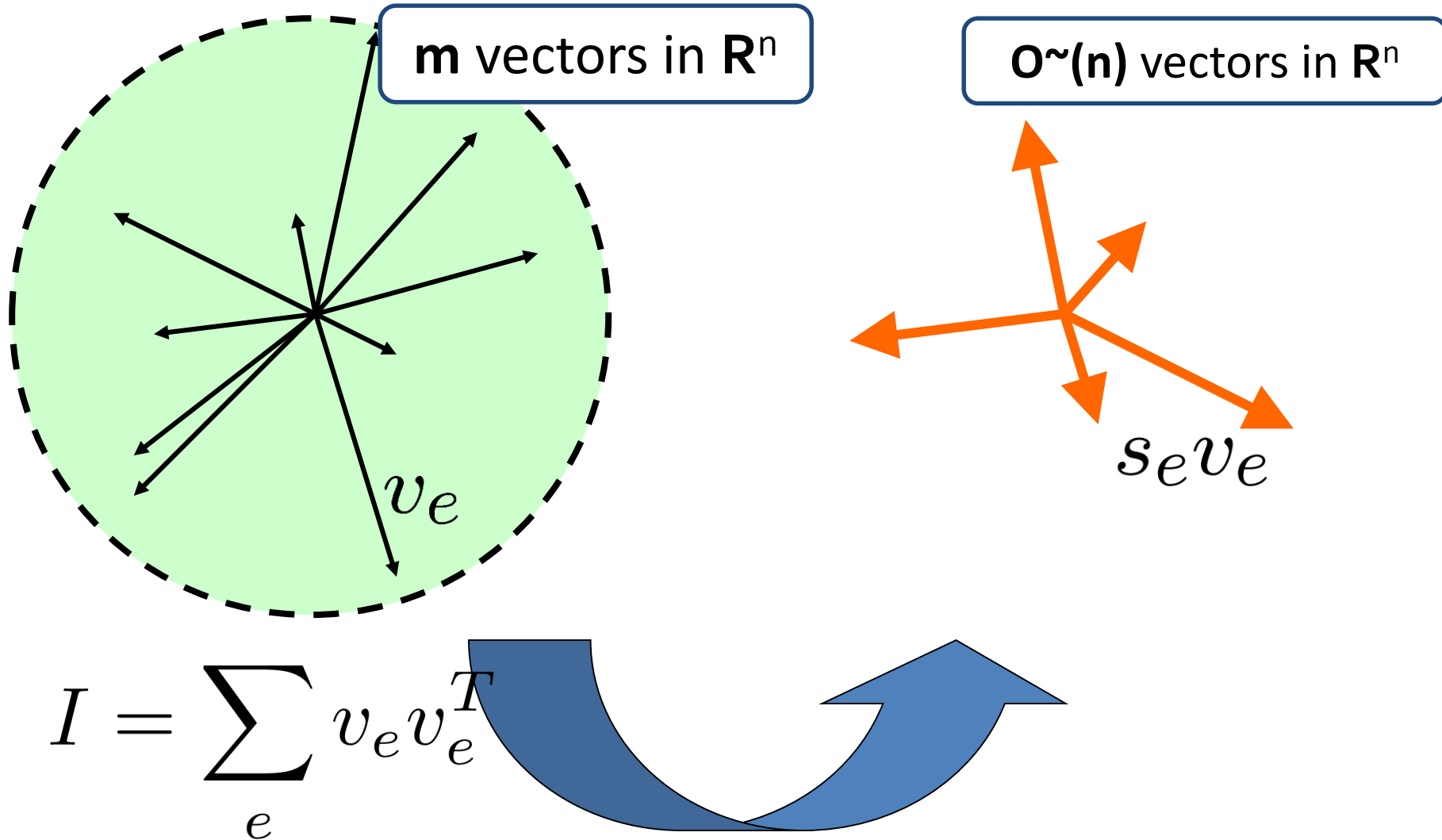


$$\forall u \quad \sum_e \langle u, v_e \rangle^2 = 1$$

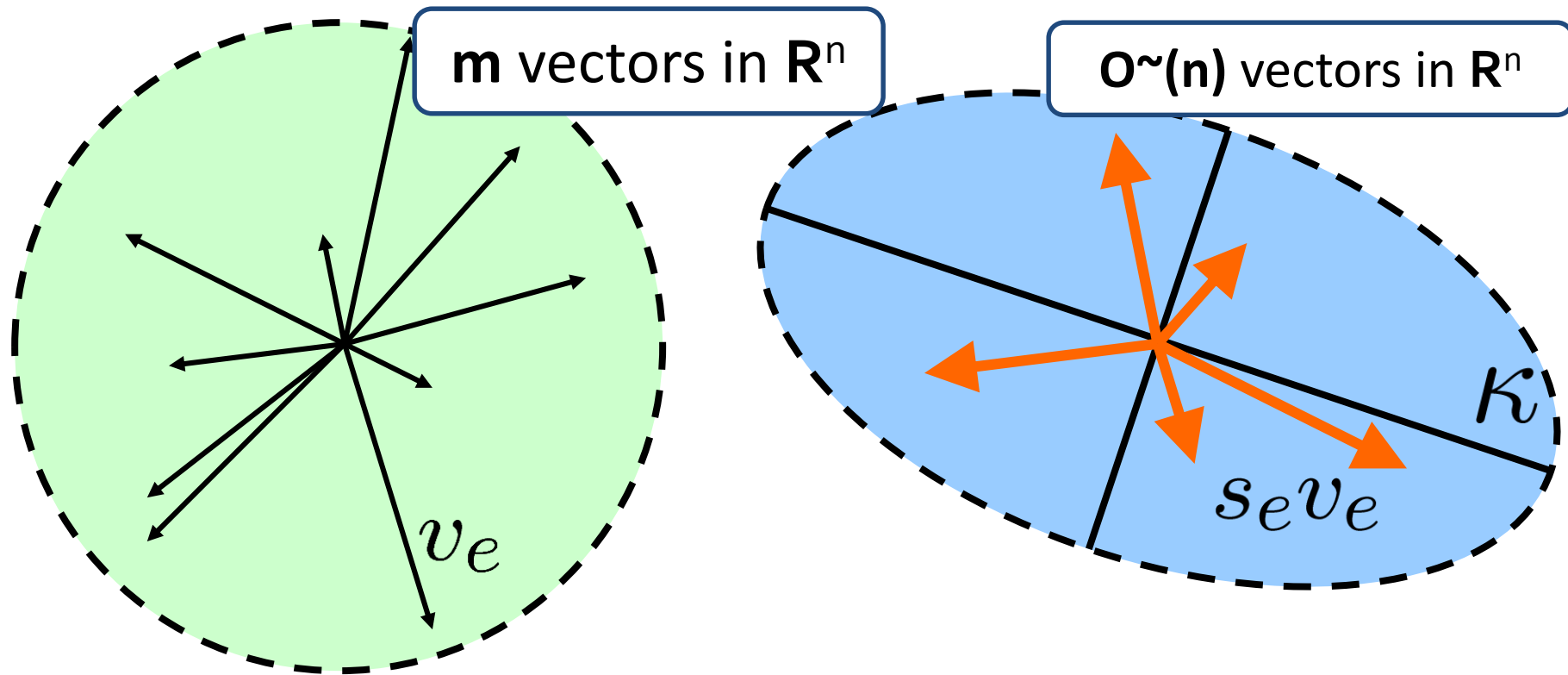
variance is the same
in every direction

$$I = \sum_e v_e v_e^T$$

Core Problem



Core Problem



$$I = \sum_e v_e v_e^T$$

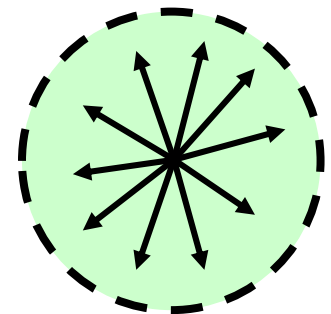
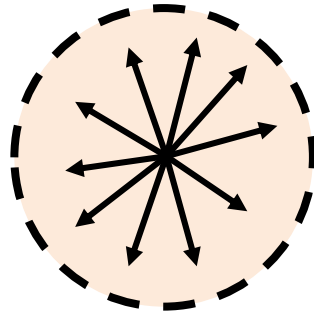
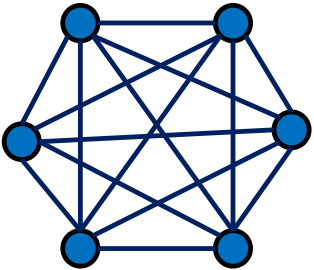
$$I \preceq \sum_e s_e v_e v_e^T \preceq \kappa I$$

Examples of the Reduction

Graph

$$L_G = \sum_e b_e b_e^T$$

$$I = \sum_e v_e v_e^T$$



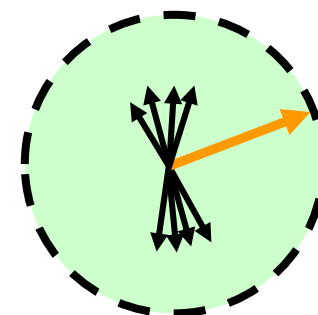
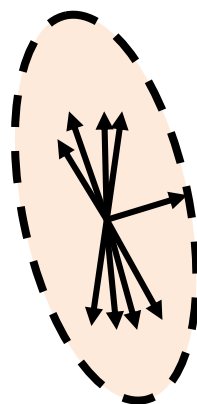
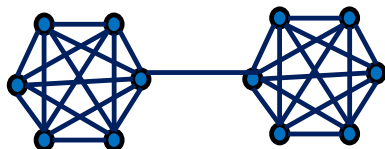
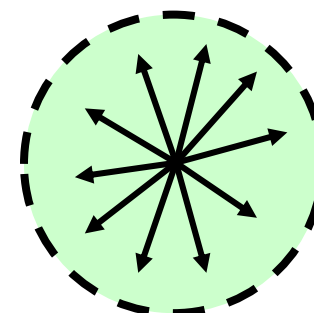
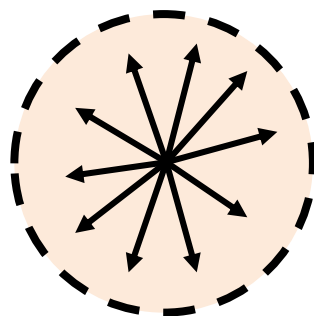
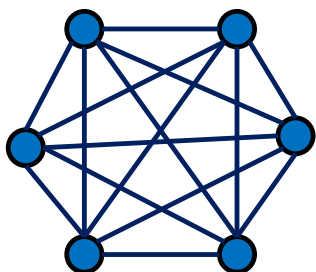
$$v_e = L_G^{-1/2} b_e$$

Examples of the Reduction

Graph

$$L_G = \sum_e b_e b_e^T$$

$$I = \sum_e v_e v_e^T$$



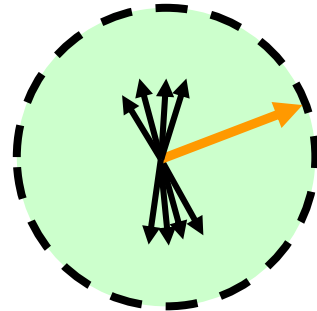
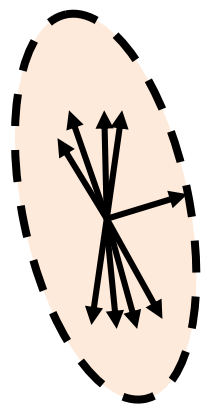
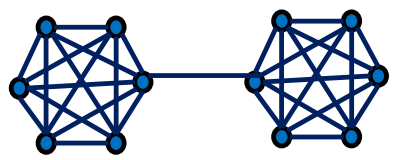
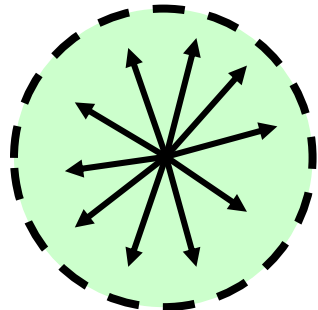
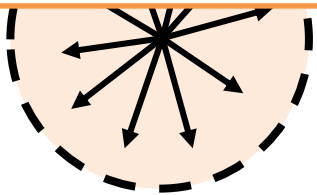
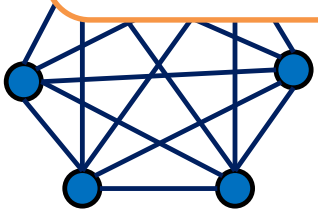
$$v_e = L_G^{-1/2} b_e$$

Examples of the Reduction

$$G^{-1} = \sum_e v_e v_e^T$$

Q: Why rescale to identity?

A: All test directions are equally important in multiplicative approximation.



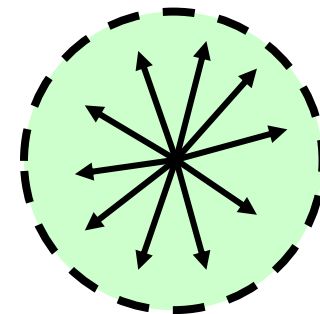
$$v_e = L_G^{-1/2} b_e$$

Examples of the Reduction

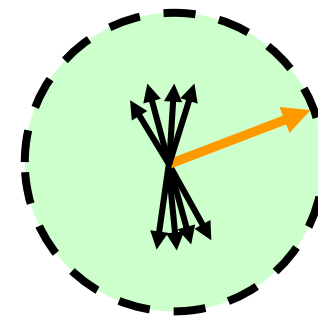
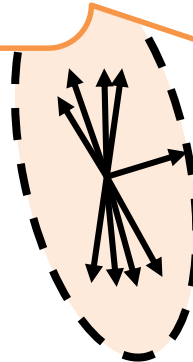
$$G^{-1} = \sum_e v_e v_e^T$$

Q: Why rescale to identity?

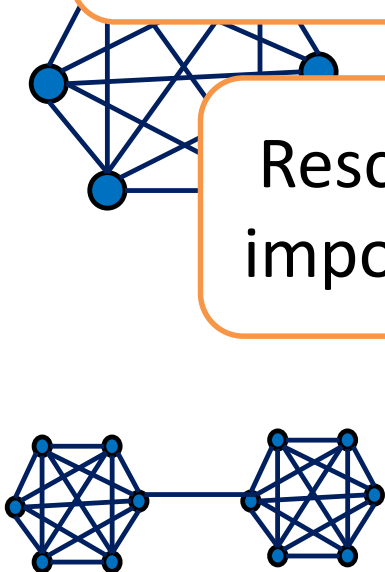
A: All test directions are equally important in multiplicative approximation.



Rescaling reveals important vectors



$$v_e = L_G^{-1/2} b_e$$



Effective Resistance View

For a graph \mathbf{G} , the vectors are $v_e = L_G^{-1/2} b_e$

Lengths of vectors are:

$$\|v_e\|^2 = \|L_G^{-1/2} b_e\|^2 = b_e^T L_G^{-1} b_e$$

Effective Resistance View

For a graph \mathbf{G} , the vectors are $v_e = L_G^{-1/2} b_e$

Lengths of vectors are:

$$\|v_e\|^2 = \|L_G^{-1/2} b_e\|^2 = b_e^T L_G^{-1} b_e$$

Electrical Flow minimizes energy:

$$\begin{array}{ll} \text{minimize} & \frac{1}{2} x^T L_G x - (x_i - x_j) \\ \text{Subject to} & x \perp 1 \end{array}$$

Effective Resistance View

For a graph \mathbf{G} , the vectors are $v_e = L_G^{-1/2} b_e$

Lengths of vectors are:

$$\|v_e\|^2 = \|L_G^{-1/2} b_e\|^2 = b_e^T L_G^{-1} b_e$$

Electrical Flow minimizes energy:

$$\begin{array}{ll} \text{minimize} & \frac{1}{2} x^T L_G x - (x_i - x_j) \\ \text{Subject to} & x \perp 1 \end{array}$$

$$\begin{array}{ll} \text{Optimality conditions:} & L_G x = (\delta_i - \delta_j) = b_{ij} \\ \text{Optimal energy:} & b_{ij}^T L_G^{-1} b_{ij} \end{array}$$

Effective Resistance View

For a graph \mathbf{G} , the vectors are $v_e = L_G^{-1/2} b_e$

Lengths of vectors are:

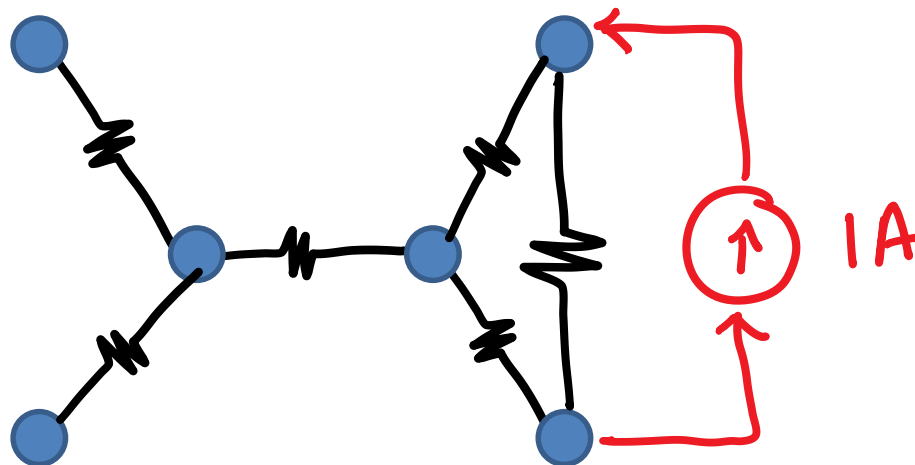
$$\|v_e\|^2 = \|L_G^{-1/2} b_e\|^2 = b_e^T L_G^{-1} b_e = \mathbf{Reff}_G(e)$$

Effective Resistance View

For a graph \mathbf{G} , the vectors are $v_e = L_G^{-1/2} b_e$

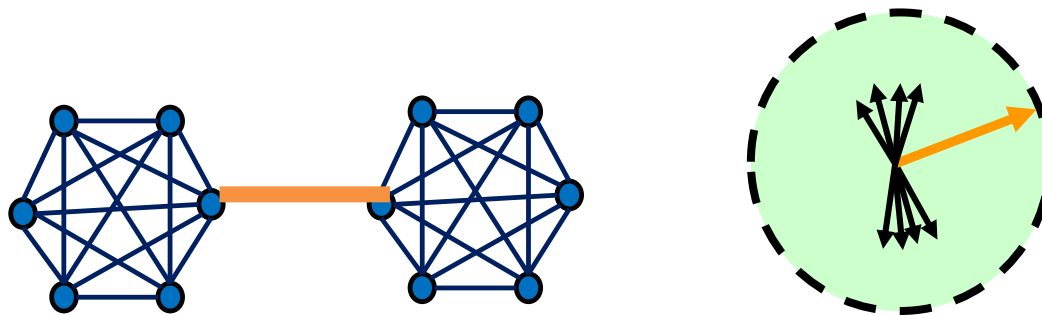
Lengths of vectors are:

$$\|v_e\|^2 = \|L_G^{-1/2} b_e\|^2 = b_e^T L_G^{-1} b_e = \mathbf{Reff}_G(e)$$



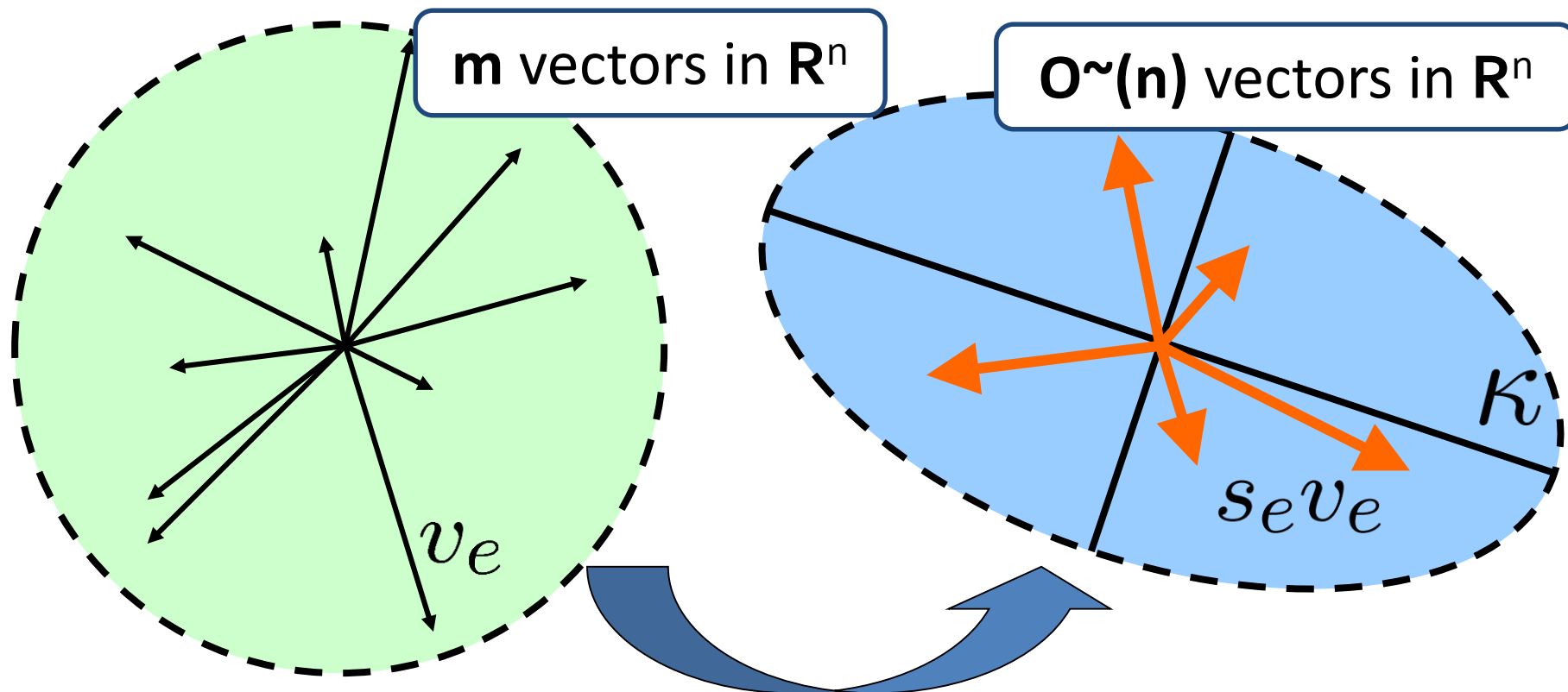
Confirmation of Electrical Intuition

- Want \mathbf{G} an \mathbf{H} to be electrically equivalent
- Edges with higher \mathbf{Reff} are more electrically significant = have higher norm after rescaling



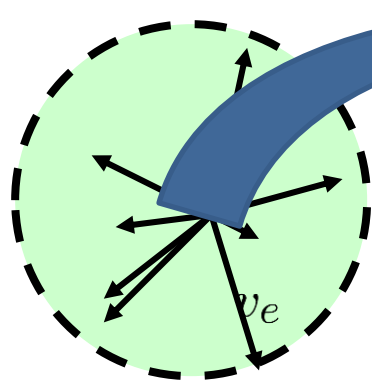
$$v_e = L_G^{-1/2} b_e$$

Core Problem



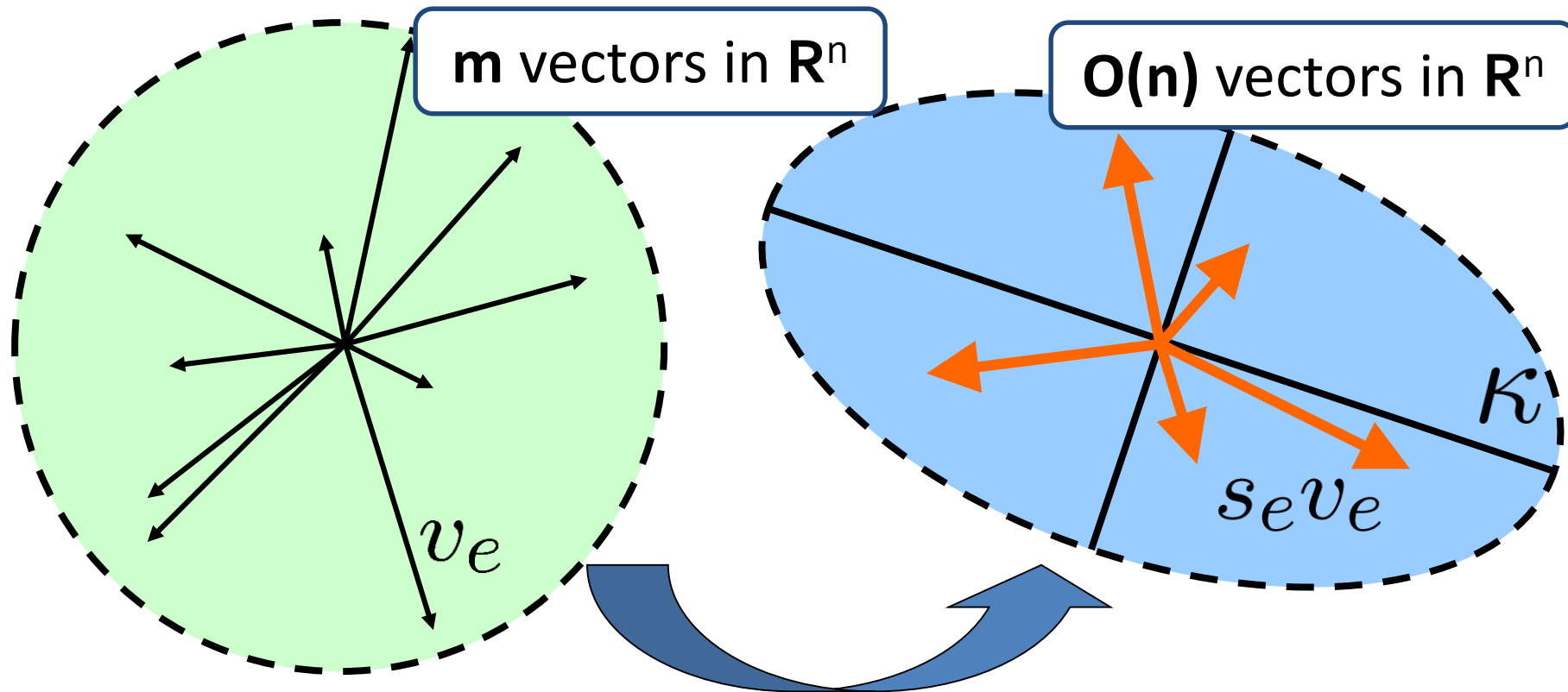
$$I = \sum_{i \leq m} v_i v_i^T$$

$$I \preceq \sum_i s_i v_i v_i^T \preceq \kappa I$$



Part 2: Randomized solution of linear algebra problem

Core Problem



$$I = \sum_{i \leq m} v_i v_i^T$$

$$I \preceq \sum_i s_i v_i v_i^T \preceq \kappa I$$

Approximating the Identity

Given $\sum_i v_i v_i^T = I$, consider the random matrix

$$X = \frac{v_i v_i^T}{p_i} \quad \text{with probability } p_i$$

Then $\mathbb{E}X = \sum_i v_i v_i^T = I$.

Take k i.i.d. samples X_1, \dots, X_k . Would like

$$(1 - \epsilon)I \preceq \frac{1}{k} \sum_i X_i \preceq (1 + \epsilon)I$$

The Chernoff Bound

Suppose X_1, \dots, X_k are i.i.d. random variables with

$$0 \leq X_i \leq M \quad \text{and} \quad \mathbb{E}X_i = 1.$$

Then

$$\mathbb{P} \left[\left| \frac{1}{k} \sum_i X_i - 1 \right| \geq \epsilon \right] \leq 2 \exp \left(-\frac{k\epsilon^2}{4M} \right)$$

The Chernoff Bound

$k = 4M/\epsilon^2$ samples give

$$\frac{1}{k} \sum_i X_i \approx_{\epsilon} 1$$

with constant probability.

dom variables with

$$\mathbb{E}X_i = 1.$$

Then

$$\mathbb{P} \left[\left| \frac{1}{k} \sum_i X_i - 1 \right| \geq \epsilon \right] \leq 2 \exp \left(-\frac{k\epsilon^2}{4M} \right)$$

The Chernoff Bound

Suppose X_1, \dots, X_k are i.i.d. random variables with

$$0 \leq X_i \leq M \quad \text{and} \quad \mathbb{E}X_i = 1.$$

Then

$$\mathbb{P} \left[\left| \frac{1}{k} \sum_i X_i - 1 \right| \geq \epsilon \right] \leq 2 \exp \left(-\frac{k\epsilon^2}{4M} \right)$$

The **Matrix** Chernoff Bound

[Rudelson'99, AW'02, Tropp'11]

Suppose X_1, \dots, X_k are i.i.d. random $d \times d$ **matrices** with

$$0 \preceq X_i \preceq M \cdot I \quad \text{and} \quad \mathbb{E}X_i = I.$$

Then

$$\mathbb{P} \left[\left\| \frac{1}{k} \sum_i X_i - I \right\| \geq \epsilon \right] \leq 2d \exp \left(-\frac{k\epsilon^2}{4M} \right)$$

The Matrix Chernoff Bound

[Rudelson'99, AW'02, Tropp'11]

$k = 4M \log d / \epsilon^2$ samples give

$$\frac{1}{k} \sum_i X_i \approx_{\epsilon} I$$

with constant probability.

dom $d \times d$

$$\mathbb{E}X_i = I.$$

Then

$$\mathbb{P} \left[\left\| \frac{1}{k} \sum_i X_i - I \right\| \geq \epsilon \right] \leq 2d \exp \left(-\frac{k\epsilon^2}{4M} \right)$$

The **Matrix** Chernoff Bound

[Rudelson'99, AW'02, Tropp'11]

Suppose X_1, \dots, X_k are i.i.d. random $d \times d$ **matrices** with

$$0 \preceq X_i \preceq M \cdot I \quad \text{and} \quad \mathbb{E}X_i = I.$$

Then

$$\mathbb{P} \left[\left\| \frac{1}{k} \sum_i X_i - I \right\| \geq \epsilon \right] \leq 2d \exp \left(-\frac{k\epsilon^2}{4M} \right)$$

In our case

$$X = \frac{v_i v_i^T}{p_i} \quad \text{with prob. } p_i, \quad \mathbb{E}X = I.$$

Want to minimize $M = \max_i \left\| \frac{v_i v_i^T}{p_i} \right\| = \max_i \frac{\|v_i\|^2}{p_i}$

To make this tight for all v_i set $p_i = \frac{\|v_i\|^2}{M}$.

In our case

$$X = \frac{v_i v_i^T}{p_i} \quad \text{with prob. } p_i, \quad \mathbb{E}X = I.$$

Want to minimize $M = \max_i \left\| \frac{v_i v_i^T}{p_i} \right\| = \max_i \frac{\|v_i\|^2}{p_i}$

To make this tight for all v_i set $p_i = \frac{\|v_i\|^2}{M}$.

$$\text{But } \sum_i p_i = \sum_i \frac{\|v_i\|^2}{M}$$

In our case

$$X = \frac{v_i v_i^T}{p_i} \quad \text{with prob. } p_i, \quad \mathbb{E}X = I.$$

Want to minimize $M = \max_i \left\| \frac{v_i v_i^T}{p_i} \right\| = \max_i \frac{\|v_i\|^2}{p_i}$

To make this tight for all v_i set $p_i = \frac{\|v_i\|^2}{M}$.

$$\text{But } \sum_i p_i = \sum_i \frac{\|v_i\|^2}{M} = \sum_i \frac{\text{Tr}(v_i v_i^T)}{M}$$

In our case

$$X = \frac{v_i v_i^T}{p_i} \quad \text{with prob. } p_i, \quad \mathbb{E}X = I.$$

Want to minimize $M = \max_i \left\| \frac{v_i v_i^T}{p_i} \right\| = \max_i \frac{\|v_i\|^2}{p_i}$

To make this tight for all v_i set $p_i = \frac{\|v_i\|^2}{M}$.

$$\text{But } \sum_i p_i = \sum_i \frac{\|v_i\|^2}{M} = \sum_i \frac{\text{Tr}(v_i v_i^T)}{M} = \frac{\text{Tr}(\sum_i v_i v_i^T)}{M}$$

In our case

$$X = \frac{v_i v_i^T}{p_i} \quad \text{with prob. } p_i, \quad \mathbb{E}X = I.$$

Want to minimize $M = \max_i \left\| \frac{v_i v_i^T}{p_i} \right\| = \max_i \frac{\|v_i\|^2}{p_i}$

To make this tight for all v_i set $p_i = \frac{\|v_i\|^2}{M}$.

$$\text{But } \sum_i p_i = \sum_i \frac{\|v_i\|^2}{M} = \sum_i \frac{\text{Tr}(v_i v_i^T)}{M} = \frac{\text{Tr}(\sum_i v_i v_i^T)}{M} = \frac{n}{M}$$

In our case

$$X = \frac{v_i v_i^T}{p_i} \quad \text{with prob. } p_i, \quad \mathbb{E}X = I.$$

Must have $M = n$

Thm: $4n \log n / \epsilon^2$ samples suffice.

$$\|X\| = \max_i \frac{\|v_i\|^2}{p_i}$$

TO MAKE THIS THIS RIGHT. v_i set $p_i = \frac{\|v_i\|^2}{M}$.

$$\text{But } \sum_i p_i = \sum_i \frac{\|v_i\|^2}{M} = \sum_i \frac{\text{Tr}(v_i v_i^T)}{M} = \frac{\text{Tr}(\sum_i v_i v_i^T)}{M} = \frac{n}{M}$$

How to Approximate the Identity

Given $\sum_i v_i v_i^T = I$

Sample $n \log n / \epsilon^2$ vectors randomly with replacement, by $p_i \propto \|v_i\|^2$.

Set $s_i = 1/p_i$ for chosen vectors.

Rudelson'99: This works whp:

$$1 - \epsilon \preceq \sum_i s_i v_i v_i^T \preceq 1 + \epsilon$$

How to Approximate the Identity

Given $\sum_i v_i v_i^T = I$

For a graph, $p_e \propto \mathbf{Reff}_G(e)$

Sample $n \log n / \epsilon^2$ vectors randomly with replacement, by $p_i \propto \|v_i\|^2$.

Set $s_i = 1/p_i$ for chosen vectors.

Rudelson'99: This works whp:

$$1 - \epsilon \preceq \sum_i s_i v_i v_i^T \preceq 1 + \epsilon$$

How to Approximate any Matrix

Given $\sum_i v_i v_i^T = V$

Sample $n \log n / \epsilon^2$ vectors randomly with replacement, by $p_i \propto \|V^{-1/2} v_i\|^2$.

Set $s_i = 1/p_i$ for chosen vectors.

Rudelson'99: This works whp:

$$1 - \epsilon \preceq \sum_i s_i v_i v_i^T \preceq 1 + \epsilon$$

Theorem. Every weighted graph \mathbf{G} has a weighted subgraph \mathbf{H} with at most $4n \log n / \epsilon^2$ edges s.t.

$$L_G \preceq L_H \preceq (1 + \epsilon)L_G.$$

Algorithm: sample $4n \log n / \epsilon^2$ edges independently according to effective resistances.

Theorem. Every weighted graph \mathbf{G} has a weighted subgraph \mathbf{H} with at most $9n \log n / \epsilon^2$ edges s.t.

$$L_G \preceq L_H \preceq (1 + \epsilon)L_G.$$

Moreover, H can be found in time $O^\sim(m/\epsilon^2)$.

Algorithm: sample $9n \log n / \epsilon^2$ edges independently according to **approximate** effective resistances.

[Spielman-S'08]

Part 3: Fast Calculation of Sampling Probabilities

Resistances are Distances

Outer product expansion:

$$L_G = \sum_e b_e b_e^T = B^T B \quad \text{for rows}(B) = \{b_e^T\}$$

$$B = \begin{pmatrix} 1 & 0 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 & 1 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & 0 & -1 & 0 & 0 \end{pmatrix}$$

Signed edge-vertex
incidence matrix

Resistances are Distances

Outer product expansion:

$$L_G = \sum_e b_e b_e^T = B^T B \quad \text{for rows}(B) = \{b_e^T\}$$

Sampling probabilities:

$$\begin{aligned} \|v_e\|^2 &= b_e^T L_G^{-1} b_e \\ &= b_e^T L_G^{-1} B^T B L_G^{-1} b_e \\ &= \|B L_G^{-1} (\delta_i - \delta_j)\|^2 \quad \text{for } e = ij. \end{aligned}$$

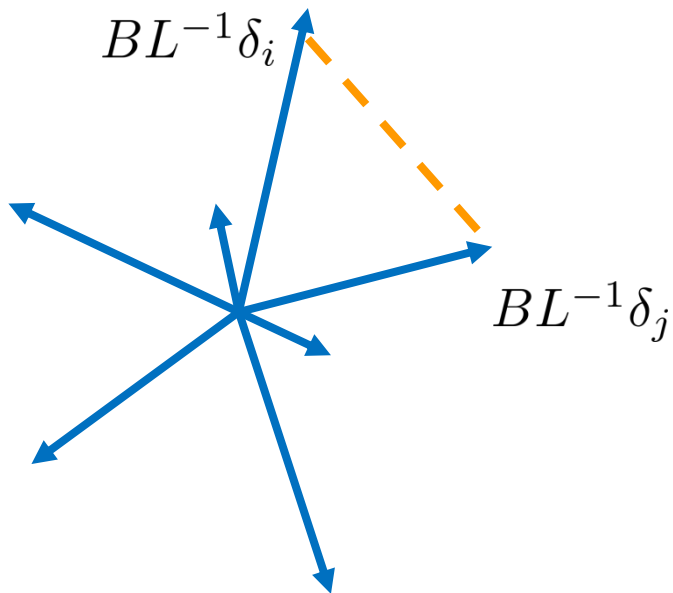
Nearly Linear Time

$$\mathbf{Reff}(ij) = \|BL^{-1}(\delta_i - \delta_j)\|^2$$

Nearly Linear Time

$$\mathbf{Reff}(ij) = \|BL^{-1}(\delta_i - \delta_j)\|^2$$

So care about distances between cols. of \mathbf{BL}^{-1}



Dimension Reduction

Johnson-Lindenstrauss Lemma [JL'84]:

Suppose x_1, \dots, x_n are points in \mathbb{R}^d .

Let $Q_{k \times n}$ be a random k –dimensional projection.

Then

$$\|Qx_i - Qx_j\|_2 = (1 \pm \epsilon) \|x_i - x_j\|_2$$

With high probability as long as

$$k \geq 10 \log n / \epsilon^2$$

Dimension Reduction

Johnson-Lindenstrauss Lemma [JL'84]:

Suppose x_1, \dots, x_n are points in \mathbb{R}^d .

Let $Q_{k \times n}$ be a random **Bernoulli matrix**.

Then

$$\|Qx_i - Qx_j\|_2 \propto (1 \pm \epsilon) \|x_i - x_j\|_2$$

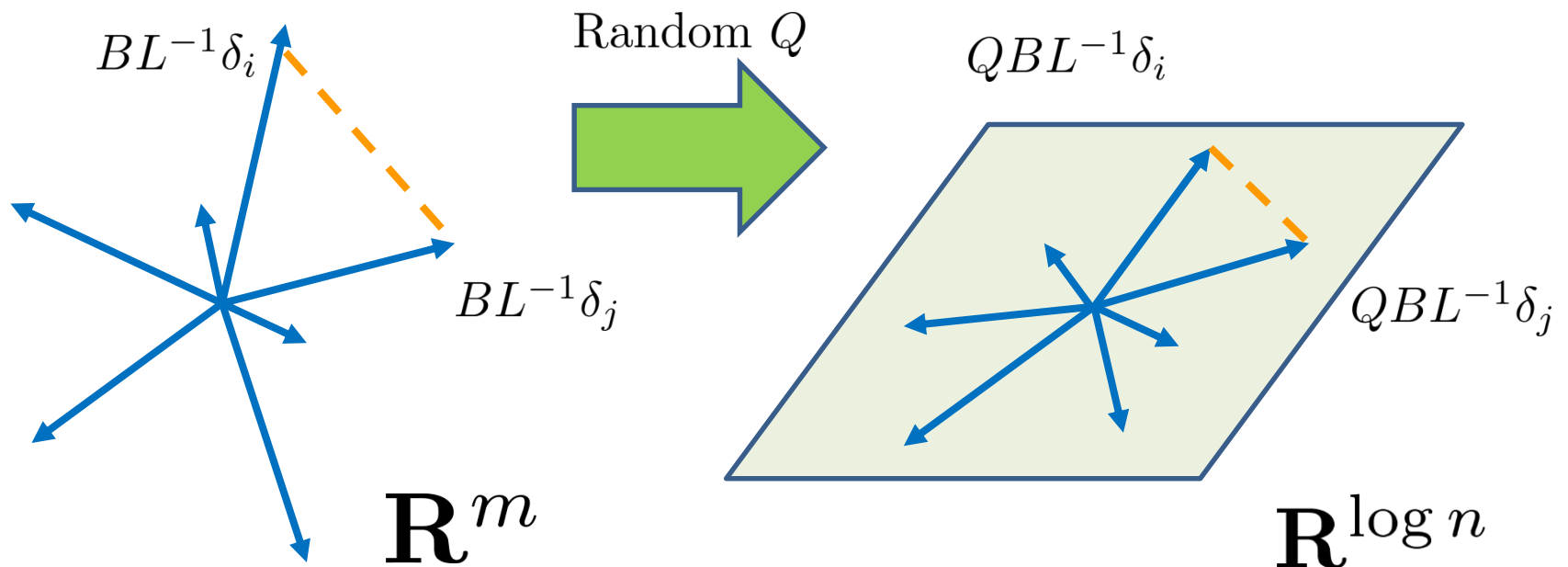
With high probability as long as

$$k \geq 10 \log n / \epsilon^2$$

Johnson-Lindenstrauss with $\epsilon = 1/2$

$$\mathbf{Reff}(ij) = \|BL^{-1}(\delta_i - \delta_j)\|^2$$

So care about distances between cols. of \mathbf{BL}^{-1}



Nearly Linear Time

$$\mathbf{Reff}(ij) = \|BL^{-1}(\delta_i - \delta_j)\|^2$$

So care about distances between cols. of BL^{-1}

Johnson-Lindenstrauss: Take random $Q_{\log n \times m}$

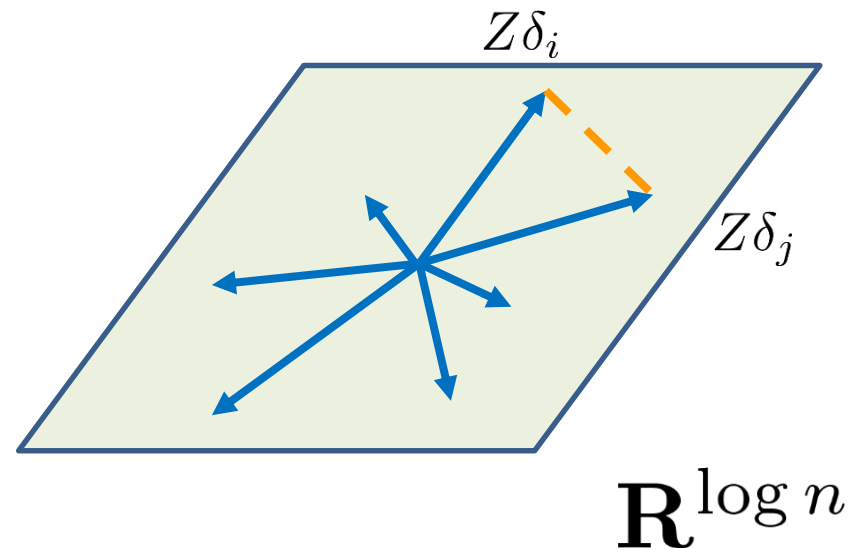
Set $Z = QB L^{-1}$

$$\begin{array}{ccc} \begin{array}{c} (\log n \times m) \\ \boxed{Q} \end{array} & \begin{array}{c} (m \times n) \\ \boxed{BL^{-1}} \end{array} & \begin{array}{c} (\log n \times n) \\ \boxed{Z} \end{array} \\ & & = \end{array}$$

Nearly Linear Time

$$\boxed{Z}^{(\log n \times n)}$$

$$\mathbf{Reff}(ij) \sim \|Z(\delta_i - \delta_j)\|^2$$



Nearly Linear Time

Find rows of $Z_{\log n \times n}$ by

$$\begin{matrix} (\log n \times n) \\ \boxed{Z} \end{matrix}$$

$$Z = QBL^{-1}$$

$$ZL = QB$$

$$z_i L = (QB)_i$$

$$\mathbf{Reff}(ij) \sim \|Z(\delta_i - \delta_j)\|^2$$

Nearly Linear Time

Find rows of $Z_{\log n \times n}$ by

$$\begin{matrix} (\log n \times n) \\ \boxed{Z} \end{matrix}$$

$$Z = QBL^{-1}$$

$$ZL = QB$$

$$z_i L = (QB)_i$$

$$\mathbf{Reff}(ij) \sim \|Z(\delta_i - \delta_j)\|^2$$

Solve $O(\log n)$ linear systems in L using fast Laplacian solver

learns all pairwise resistances by probing a few random electrical flows.

Nearly Linear Time

Find rows of $Z_{\log n \times n}$ by

$$\begin{matrix} (\log n \times n) \\ \boxed{Z} \end{matrix}$$

$$Z = QBL^{-1}$$

$$ZL = QB$$

$$z_i L = (QB)_i$$

$$\mathbf{R}_{\text{eff}}(ij) \sim \|Z(\delta_i - \delta_j)\|^2$$

Solve $O(\log n)$ linear systems in L using fast Laplacian solver

Can show approximate \mathbf{R}_{eff} suffice.

(only change M by a constant factor)



Actual Algorithm

Input: undirected graph $G = (V, E, w)$

Output: subgraph H with $L_G \preceq L_H \preceq (1 + \epsilon)L_G$

1. Let $Q_{\log n \times m}$ be a scaled random projection.

Compute approximate resistance matrix

$$Z = QBL^+$$

by solving $\log n$ Laplacian systems

2. Repeat the following $9n \log n / \epsilon^2$ times:

choose edge $e = ij$ w.p. $p_e \propto \|Z(\delta_i - \delta_j)\|^2$

add e to H with weight $s_e = 1/p_e$

Actual Algorithm

Input: undirected graph $G = (V, E, w)$

Output: subgraph H with $L_G \preceq L_H \preceq (1 + \epsilon)L_G$

1. Let $Q_{\log n \times m}$ be a scaled random projection.

Compute approximate resistance matrix

$$Z = QBL^+$$

by solving $\log n$ Laplacian systems

2. Repeat the following $9n \log n / \epsilon^2$ times:

choose edge $e = ij$ w.p. $p_e \propto \|Z(\delta_i - \delta_j)\|^2$

add e to H with weight $s_e = 1/p_e$

+improvements by [Koutis-Levin-Peng'12]

Chicken / Egg?

$$\text{Solve } L_G x = b$$

Chicken / Egg?

Solve $L_G x = b$



Compute sparsifier

Chicken / Egg?

Solve $L_G x = b$



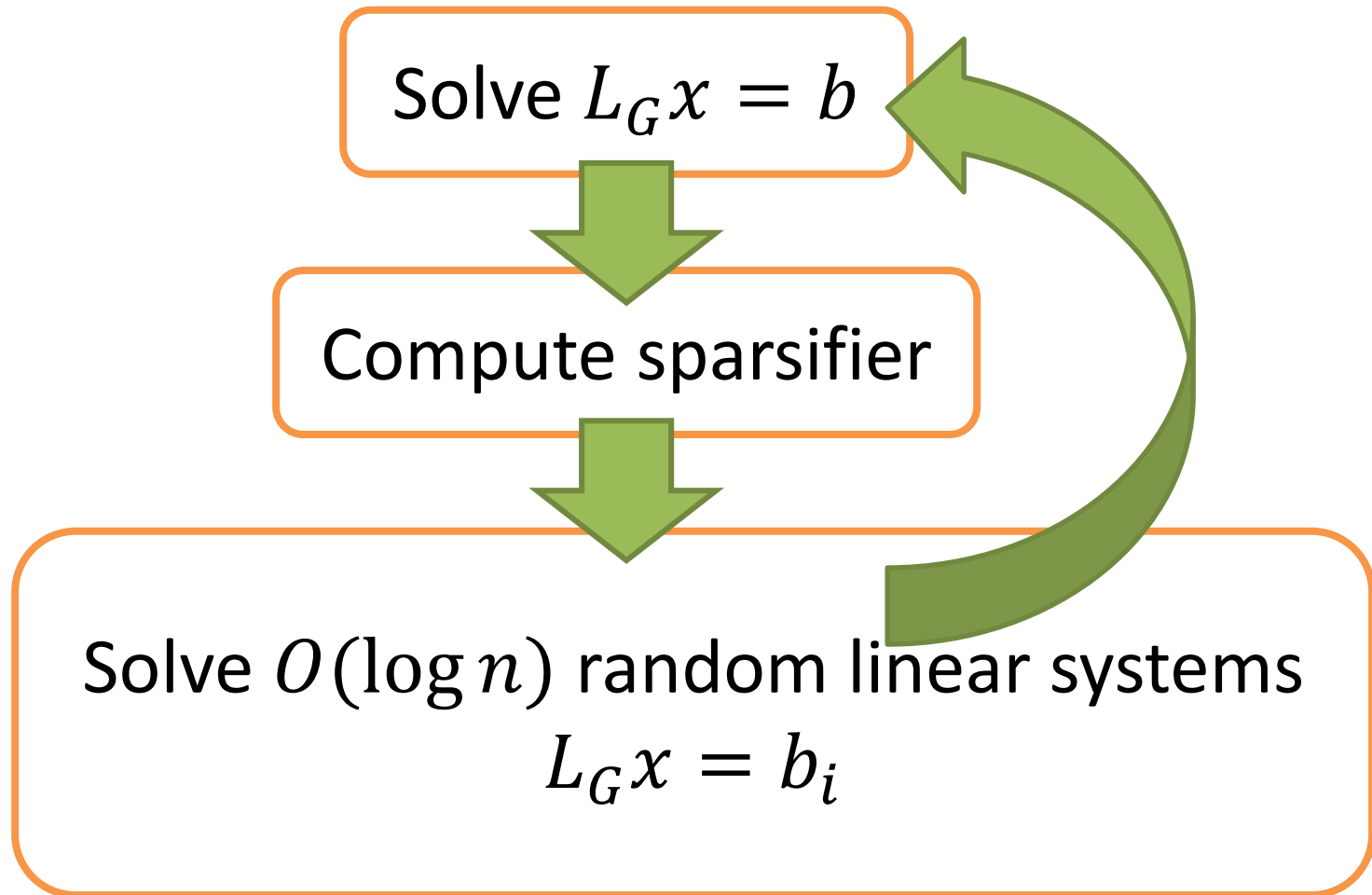
Compute sparsifier



Solve $O(\log n)$ random linear systems

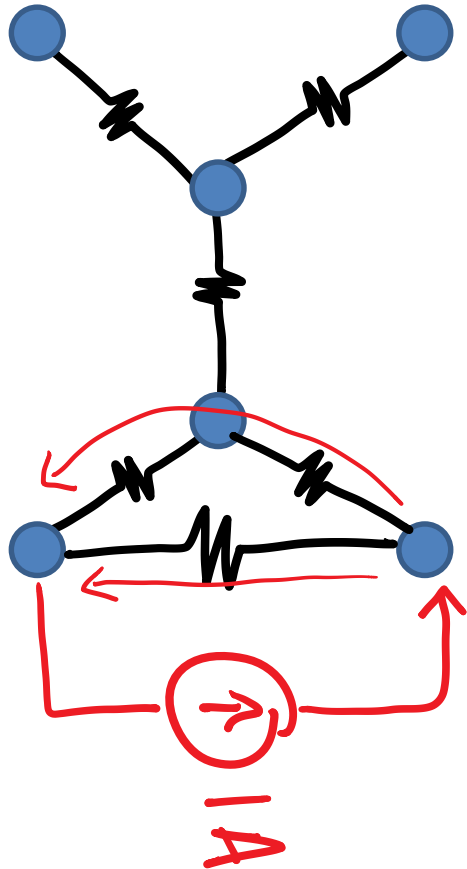
$$L_G x = b_i$$

[Koutis-Miller-Peng'10] resolve this

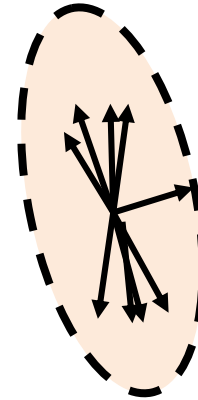


Two Useful Ways to view a Graph

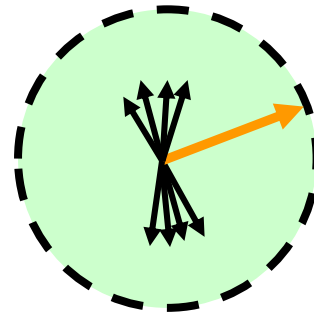
electrical network



bunch of vectors



$$L_G = \sum_e b_e b_e^T$$

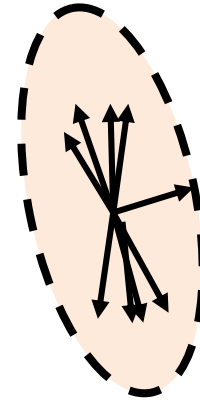
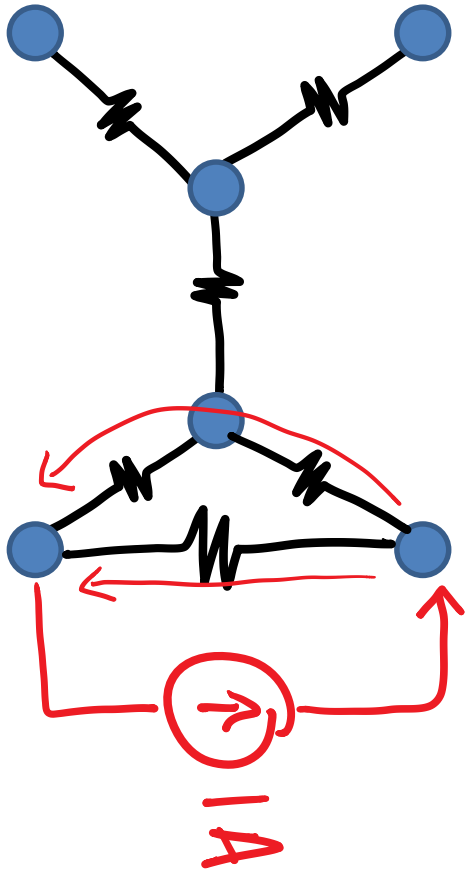


$$I = \sum_e v_e v_e^T$$

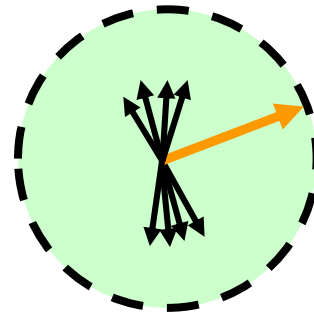
$$T_{\text{W}} \quad \text{Reff}(e) = \|L_G^{-1/2} b_e\|^2 = \|v_e\|^2 \quad \text{ph}$$

electrical network

bunch of vectors



$$L_G = \sum_e b_e b_e^T$$



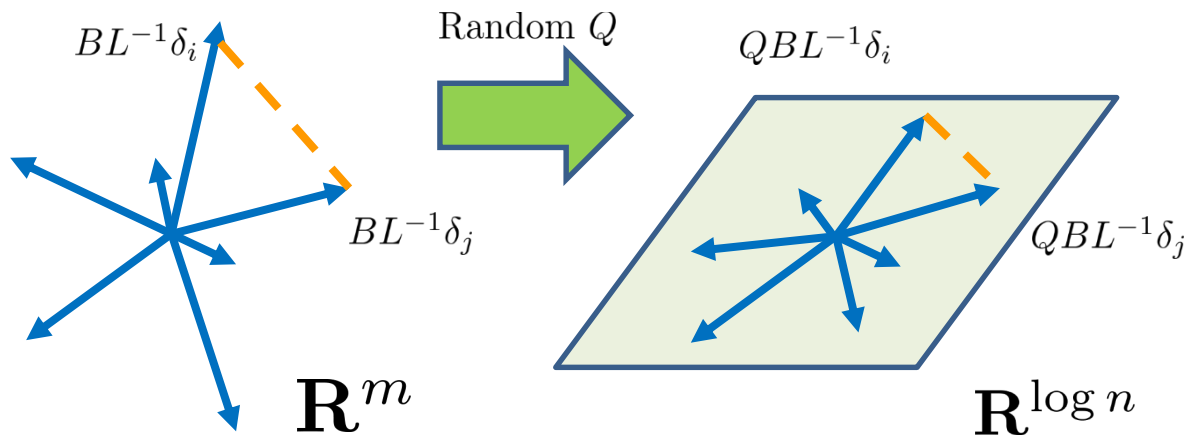
$$I = \sum_e v_e v_e^T$$

Two Useful Tools

Matrix Chernoff Bound

$$\mathbb{P} \left[\left\| \frac{1}{k} \sum_i X_i - I \right\| \geq \epsilon \right] \leq 2d \exp \left(-\frac{k\epsilon^2}{4M} \right)$$

Johnson-Lindenstrauss Lemma



Advantages over pure combinatorics

There is a global **rescaling** transformation:

$$L_G \approx L_H \quad \text{iff} \quad L_G^{-1/2} L_H L_G^{-1/2} \approx I$$

Powerful **random matrix** tools apply naturally:

1. Matrix Chernoff bound
2. Johnson-Lindenstrauss Lemma

Some Improvements

[Koutis-Levin-Peng'12] $O\left(\frac{m \log^2 n}{\epsilon^2}\right)$

[Kelner-Levin'11] 1-pass streaming algorithm

[Koutis'14] parallel algorithm

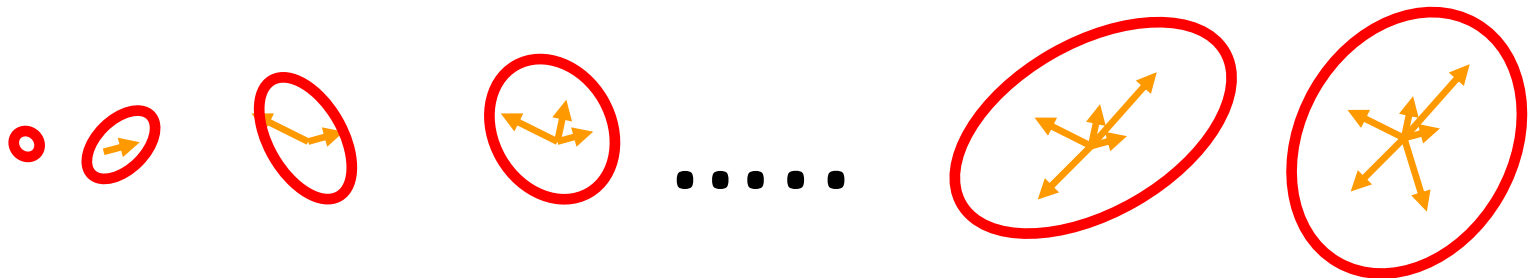
[Kapralov, Lee, Musco x2, Sidford'14]

1-pass dynamic streaming algorithm

Coming Up: A Slow Algorithm

Part II: Sparsifiers with $O(n/\epsilon^2)$ edges.

Based on more delicate understanding of how eigenvalues of a matrix evolve on adding edges.



Two Open Questions

Faster approximation of effective resistances.

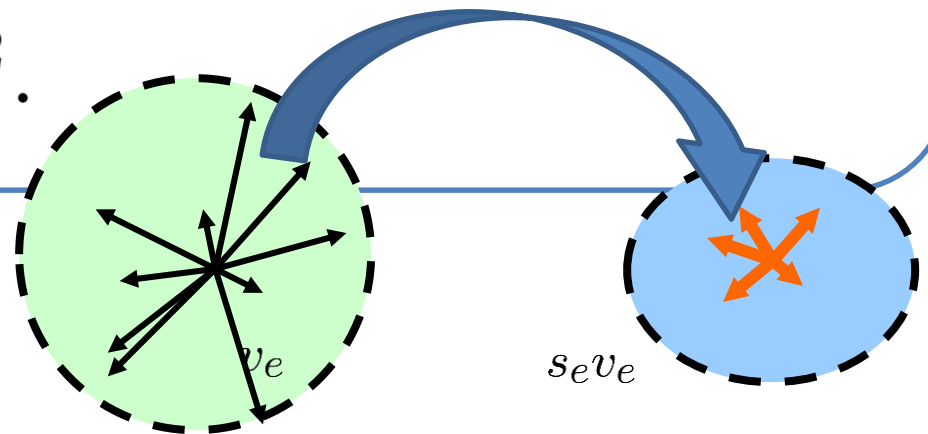
More physical processes on graphs.

Deterministic Solution [Batson-Spielman-S'09]

Spectral Sparsification Theorem:

Given $\sum_{i \leq m} v_i v_i^T = I_n$ there are $s_i \geq 0$ with:

- $(1 - \epsilon)I \preceq \sum_i s_i v_i v_i^T \preceq (1 + \epsilon)I$
- $\text{supp}(s) \leq 4n/\epsilon^2$.

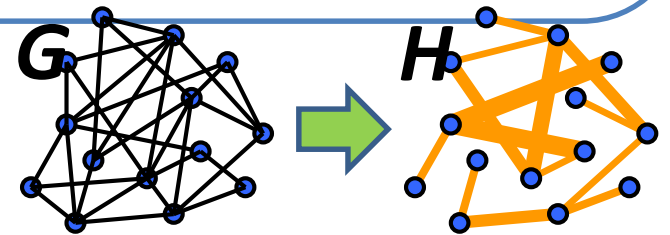


Deterministic Solution [BSS'09]

Spectral Sparsification Theorem:

Given $\sum_{e \leq m} b_e b_e^T = L_G$ there are $s_e \geq 0$ with:

- $(1 - \epsilon)L_G \preceq \sum_i s_i v_i v_i^T \preceq (1 + \epsilon)L_G$
- $\text{supp}(s) \leq 4(n - 1)/\epsilon^2$.



Deterministic Solution [BSS'09]

Spectral Sparsification Theorem:

Given $\sum_{e \in E} b_e b_e^T = L_G$ there are $s_e \geq 0$ with:

- $(1 - \epsilon)L_G \preceq \sum_i s_i v_i v_i^T \preceq (1 + \epsilon)L_G$
- $\text{p}(s) \leq 4(n - 1)/\epsilon^2$.

Open: Fast Algorithm?

