

Free Energy Wells and Overlap Gap Property in Sparse PCA

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Joint work with
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The Sparse PCA Model

Setup: *rank-1 plus noise*

Let $x \in \{0, 1\}^n$ be a **binary k-sparse** vector, $\lambda > 0$ the SNR, $k = o(n)$.

- For “additive noise” $W \in \mathbb{R}^{n \times n}$ *GOE matrix*
i.e. W_{ii} i.i.d. $\mathcal{N}(0, 2/n)$, $W_{ij} = W_{ji}$ i.i.d. $\mathcal{N}(0, 1/n)$,
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Minimum λ so that, given Y , x can be recovered (efficiently) with probability tending to 1 as $n \rightarrow +\infty$ (**w.h.p.**).

The Sparse PCA Model - Literature

Vast Literature. [Baik et al'05], [Johnstone, Lu '09], [Montanari et al '15], [Banks et al'18], [Ding et al'19], [Barbier et al'19], [Gamarnik et al '19]

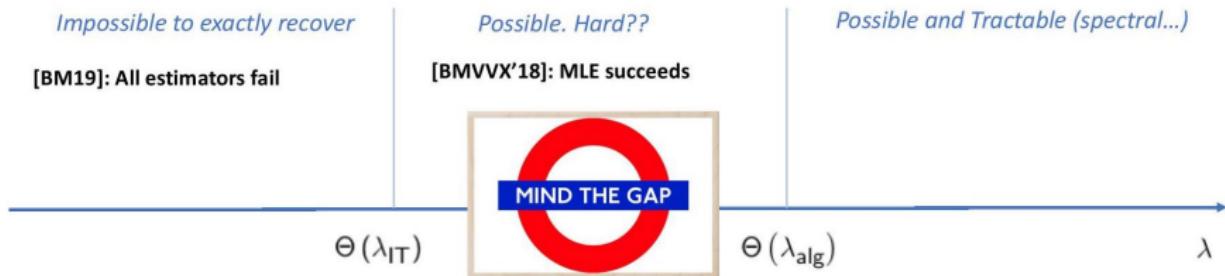


Figure: $\lambda_{IT} = 1/\sqrt{nk}$, $\lambda_{alg} = \min\{1/k, 1/\sqrt{n}\}$, MLE: $\max_{v \in \{0,1\}^n, \|v\|_0=k} v^\top Y v$

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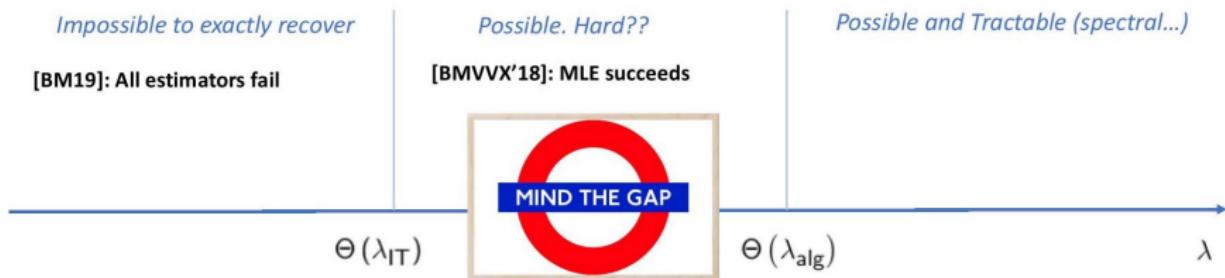


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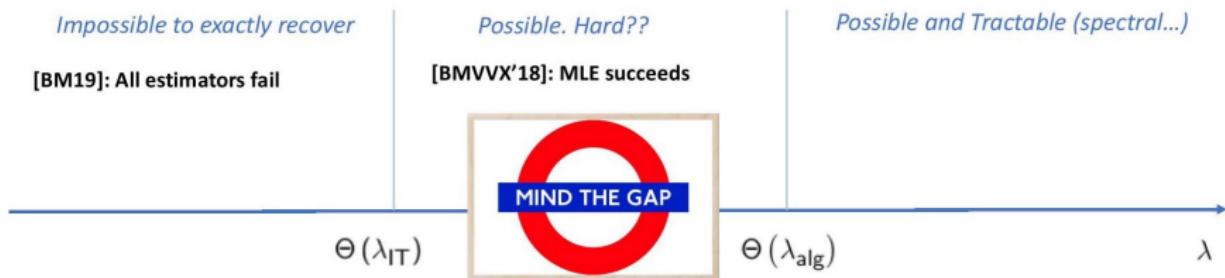


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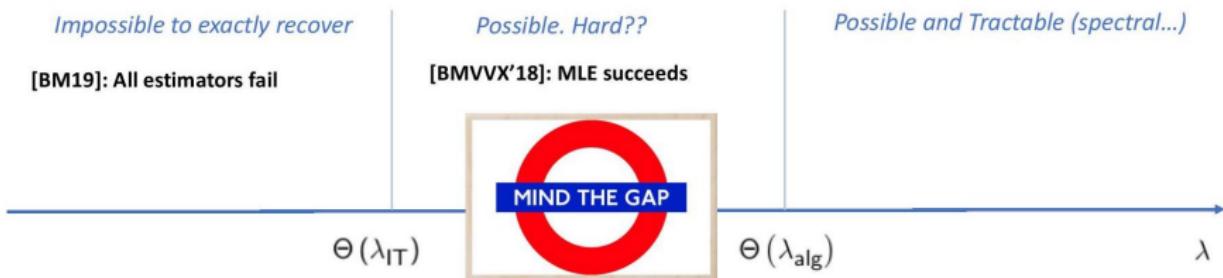


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- Generic in high dimensional inference: *computational-statistical gap*.
- *No complexity-theoretic explanation.*
- *Many methods:* low-degree (SOS), *statistical physics*, average-case reductions, statistical query lower bounds.

The Sparse PCA Model - Sub-exponential time methods

Recall $\mathbf{Y} = \lambda \mathbf{x} \mathbf{x}^\top + \mathbf{W}$.

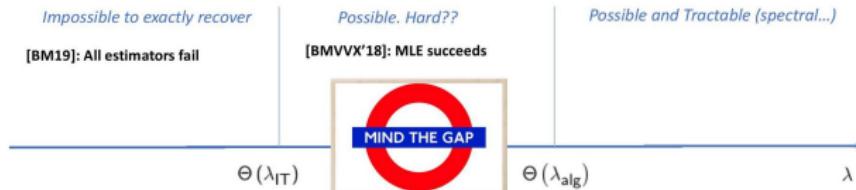


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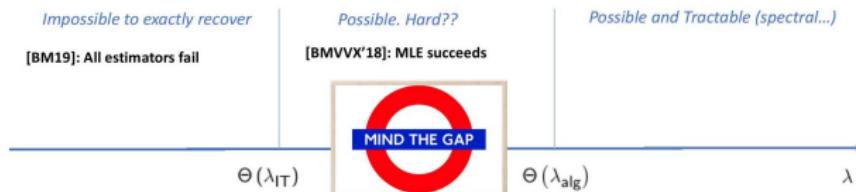


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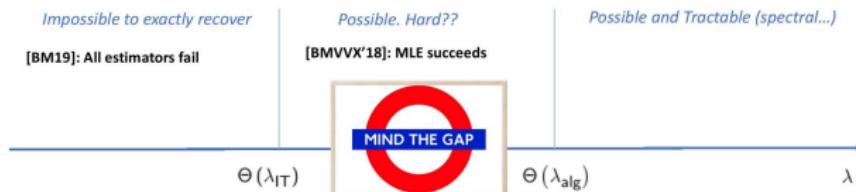


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If $\lambda_{IT} < \lambda < \lambda_{alg}$, optimal algorithm takes $\exp\left(\tilde{\Theta}\left((\sqrt{n}\lambda)^{-2}\right)\right)$ -time.

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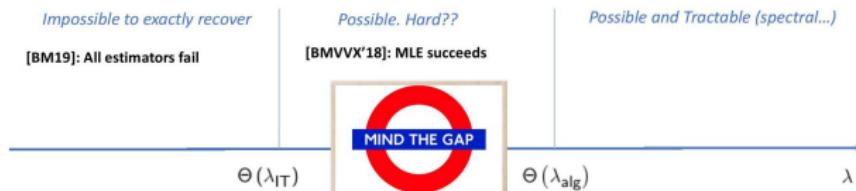


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(Q1) MCMC methods? (Q2) Optimal time via “landscape” analysis ?

This Work

For **(almost) all** λ in the hard regime
we prove **lower bounds** for MCMC methods for solving the MLE
matching the conjectured $\exp\left(\tilde{\Omega}\left((\sqrt{n}\lambda)^{-2}\right)\right)$ -time of [DKWB '19],
by establishing local barriers introduced in **spin glass theory**.

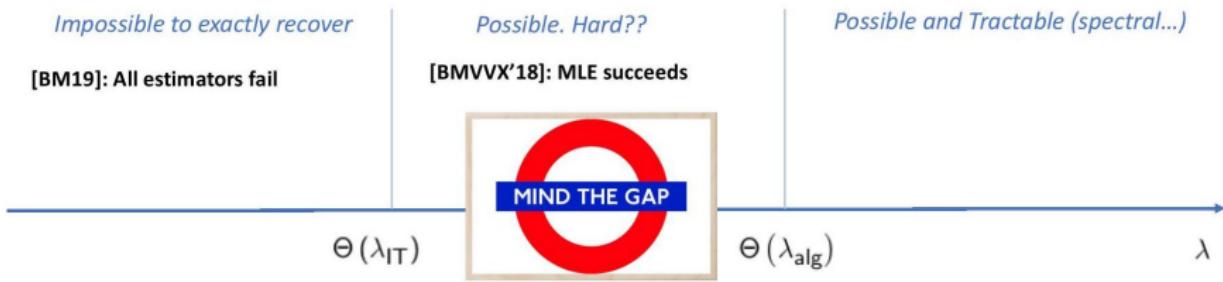


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Stationary distributions: Gibbs measures

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and MLE $\max_{v \in \{0,1\}^n, \|v\|_0=k} v^\top Y v$ works for all $\lambda > \lambda_{IT}$.

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- MLE_{k'} : $\max_{v \in \{0,1\}^n : \|v\|_0=k'} v^\top Y v.$
- $k' \neq k$: optimal algorithm $k' = (\sqrt{n}\lambda)^{-2} < k$ [DKWB'19],
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The Gibbs measures

$$\mu_{\beta, k'}(v) \propto e^{\beta v^\top Y v}, \quad v \in \mathcal{B}_{k'} := \{v \in \{0, 1\}^n, \|v\|_0 = k'\},$$

($\beta = \lambda n/2$ the posterior $\mathbb{P}[x|Y]$).

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β, k' “informative”

Sampling v from $\mu_{\beta, k'}$ suffices for recovery,
i.e. $\langle v, x \rangle$ is “large” w.h.p.

Free Energy Wells (FEW) from Statistical Physics

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We study the map $\ell \rightarrow \log \mu_{\beta,k'}(A_\ell)$ (essential for local dynamics).

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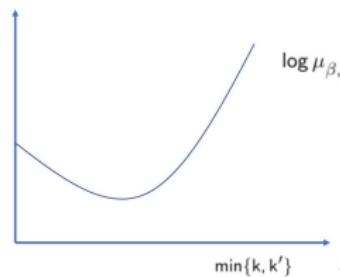


Figure: FEW

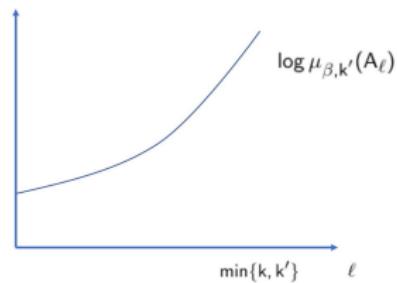


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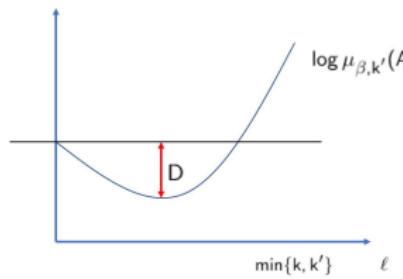


Figure: FEW of depth D

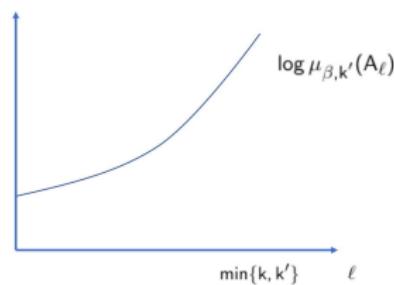


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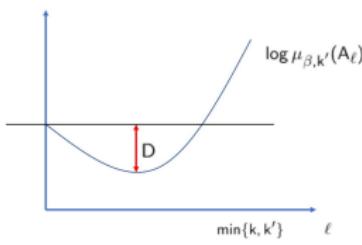


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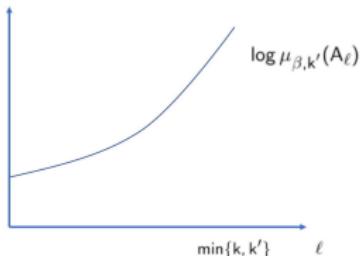


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Theorem

Under FEW of depth D for $\mu_{\beta,k'}$, any markov chain on $\mathcal{B}_{k'}$ which

- (1) changes at most 2 coordinates at a step and
- (2) has stationary distribution $\mu_{\beta,k'}$,

requires (worst-case initialization) e^D -time to recover x .

Similar results for FEW in *tensor PCA* [BAGJ'18], *principal submatrix recovery* [GSJ'19] and *planted clique* [GZ'19].

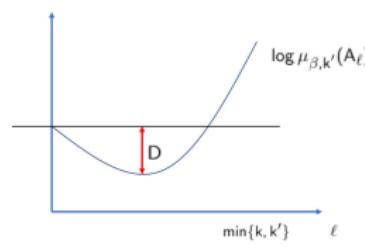


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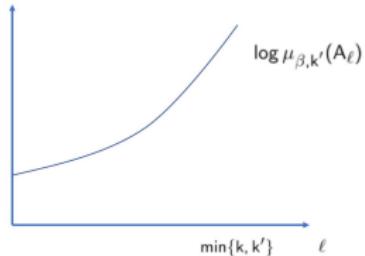


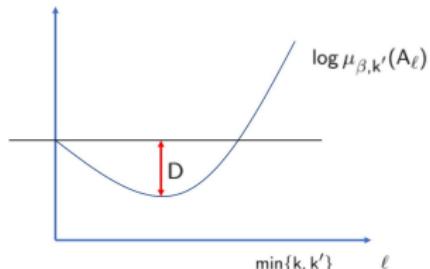
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Main Result on FEW

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For (almost)* all λ in the “hard” regime and all β, k' “informative”, $\mu_{\beta, k'}$ admits a FEW of depth $\Omega((\sqrt{n}\lambda)^{-2})$.

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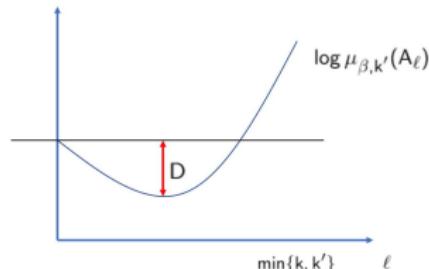
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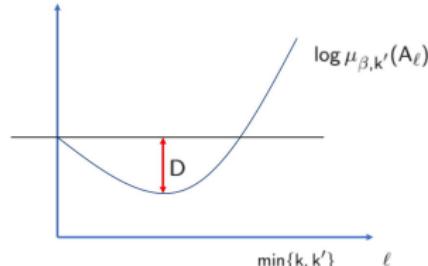
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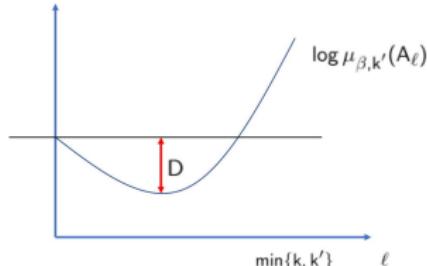
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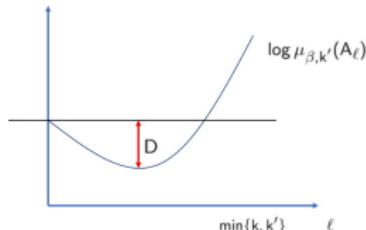
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- Almost all* becomes all under $k \leq n^{1/3}$ or $k' \leq k$.
- Establish OGP ($\beta = \infty$) for the same parameters.



Proof Sketch

$$\mu_{\beta, k'}(A_\ell) \propto \sum_{v \in A_\ell} e^{\beta v^\top Y v}, \quad A_\ell := \{v \in \mathcal{B}_{k'} : \langle v, x \rangle = \ell\}.$$



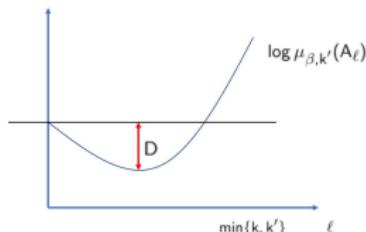
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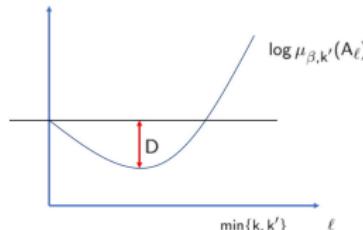
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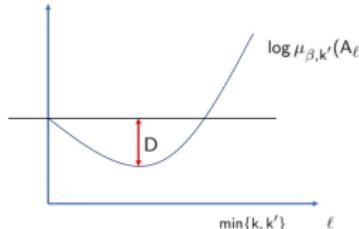
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- Criticality at $\beta = \beta_{\text{Bayes}} = \lambda n / 2$ gives depth $\Omega((\sqrt{n}\lambda)^{-2})$.



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- If $\beta \approx \infty$,

$$\log \mu_{\beta,k'}(A_\ell) \approx \beta \max_{v \in A_\ell} v^\top Y v.$$

Non-monotonicity iff OGP.

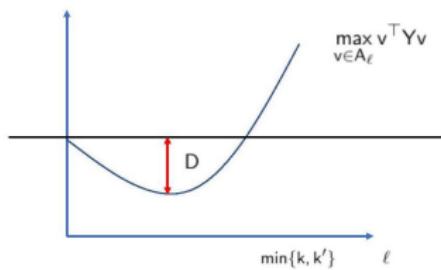


Figure: $\beta = \infty$, OGP of depth D

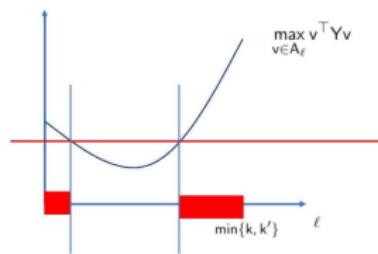


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