# Reconstruction of non-degenerate homogeneous depth-3 circuits

#### Chandan Saha

#### Joint work with Neeraj Kayal

## Reconstruction of circuits

- Let f(x) be a *n*-variate degree-*d* polynomial computed by a circuit of size *s* from a class *C*.
- Reconstruction problem. Given black-box access to *f*, output a small circuit computing *f*.



## Reconstruction of circuits

- Let f(x) be a *n*-variate degree-*d* polynomial computed by a circuit of size *s* from a class *C*.
- Reconstruction problem. Given black-box access to *f*, output a *small* circuit computing *f*.
- Size of the output circuit. Ideally, poly(s).
- Proper learning. Output a circuit from class *C*.

## Reconstruction of circuits

- Let f(x) be a *n*-variate degree-*d* polynomial computed by a circuit of size *s* from a class *C*.
- Reconstruction problem. Given black-box access to *f*, output a *small* circuit computing *f*.
- Efficiency. Ideally, poly(d, s). But, even  $N = \binom{n+d}{n}$  time reconstruction is non-trivial, for  $n \ll s \ll N$ , as exhaustive search over size-s circuits takes exp(s) time.

# **Reconstruction implies lower bounds**

- Fortnow & Klivans (2009): A randomized poly-time reconstruction algorithm for *C* implies there's a function in BPEXP that does not have poly-size circuits from *C*.
- Volkovich (2016): A deterministic poly-time recon. algorithm for C can be used to construct a function in EXP that doesn't have poly-size circuits from C.

# **Reconstruction implies lower bounds**

- Fortnow & Klivans (2009): A randomized poly-time reconstruction algorithm for *C* implies there's a function in BPEXP that does not have poly-size circuits from *C*.
- Volkovich (2016): A deterministic poly-time recon. algorithm for C can be used to construct a function in EXP that doesn't have poly-size circuits from C.
- Efficient reconstruction algorithms have focussed on classes *C* for which non-trivial lower bounds are known.

# **Reconstruction implies lower bounds**

- Fortnow & Klivans (2009): A randomized poly-time reconstruction algorithm for *C* implies there's a function in BPEXP that does not have poly-size circuits from *C*.
- Volkovich (2016): A deterministic poly-time recon. algorithm for *C* can be used to construct a function in EXP that doesn't have poly-size circuits from *C*.
- Efficient reconstruction algorithms have focussed on classes *C* for which non-trivial lower bounds are known.

Does lower bound imply efficient reconstruction ?

# Reconstruction is inherently hard

- Reconstruction is akin to <u>approximating the minimum</u> <u>circuit size</u>.
- Minimum Circuit Size Problem (MCSP). Given a truthtable T of size  $N = 2^n$  and an integer s, check if the function defined by T has a circuit of size at most s.

# Reconstruction is inherently hard

- Reconstruction is akin to approximating the minimum circuit size.
- Minimum Circuit Size Problem (MCSP). Given a truthtable T of size  $N = 2^n$  and an integer s, check if the function defined by T has a circuit of size at most s.
- Allender & Hirahara (2017): There's a  $\epsilon(N) = o(1)$  such that approximating the minimum circuit size to within  $N^{1-\epsilon}$  factor cannot be done in poly(N) time, assuming the existence of one-way function.

# Reconstruction is inherently hard

- Reconstruction is akin to approximating the minimum circuit size.
- Minimum Circuit Size Problem (MCSP). Given a truthtable T of size  $N = 2^n$  and an integer s, check if the function defined by T has a circuit of size at most s.
- Drawing analogy between Boolean and arithmetic circuits, reconstruction is expected to be a hard problem even if f is given verbosely as a list of  $N = \binom{n+d}{n}$  coefficients.

 Razborov & Rudich (1997); Forbes, Shpilka & Volk (2017); Grochow, Kumar, Saks & Saraf (2017):

Constructivity.



# Natural lower bound to PAC learning

- Carmosino, Impagliazzo, Kabanets & Kolokolova (2016): The natural lower bound framework for AC<sup>0</sup>[p] circuits can be used to give quasi-polynomial time PAC learning algorithm for the same class.
- Linial, Mansour & Nisan (1993): Similar result for  $AC^0$ .
- Jackson, Klivans & Servedio (2002): Similar result for  $AC^0$  with poly-logarithmic majority gates.

# Natural lower bound to PAC learning

- Carmosino, Impagliazzo, Kabanets & Kolokolova (2016): The natural lower bound framework for AC<sup>0</sup>[p] circuits can be used to give quasi-polynomial time PAC learning algorithm for the same class.
- Linial, Mansour & Nisan (1993): Similar result for  $AC^0$ .
- Jackson, Klivans & Servedio (2002): Similar result for  $AC^0$  with poly-logarithmic majority gates.
- These learning algorithms are not proper.

 Can we hope to get such natural lower bound to reconstruction translations for <u>arithmetic circuits</u>?

- Can we hope to get such natural lower bound to reconstruction translations for arithmetic circuits?
- Klivans & Shpilka (2006); Forbes & Shpilka (2013): Gave efficient reconstruction for <u>read-once oblivious ABP</u> (ROABP) and <u>non-commutative ABP</u>. (Natural lower bounds were known for these models.)

- Can we hope to get such natural lower bound to reconstruction translations for arithmetic circuits?
- There are a few challenges:
  - Exact learning. Two polynomials differ at many points. If the output is an arithmetic circuit then it has to compute f exactly.

- Can we hope to get such natural lower bound to reconstruction translations for arithmetic circuits?
- There are a few challenges:
  - Exact learning. Two polynomials differ at many points. If the output is an arithmetic circuit then it has to compute f exactly.
  - Depth reduction. Constant depth arithmetic circuits are too powerful.
  - Homogenization. Makes reconstruction challenging even for classes with exponential lower bounds.

• Each term  $T_i$  is a product of d linear forms in n variables.

## Homogeneous depth-3 circuits

 $f = T_1 + T_2 + \dots + T_s \longleftarrow A(n, d, s)$  homogeneous depth-3 circuit

• Each term  $T_i$  is a product of d linear forms in n variables.

- Each term  $T_i$  is a product of d linear forms in n variables.
- Nisan & Wigderson (1997): Showed a  $(n/d)^{\Omega(d)}$  lower bound on s for  $d \leq n$ .
- Kayal, S., Tavenas (2016): Showed a  $2^{\Omega(n)}$  lower bound on s for  $d \ge n$ .

- Each term  $T_i$  is a product of d linear forms in n variables.
- Nisan & Wigderson (1997): Showed a  $(n/d)^{\Omega(d)}$  lower bound on s for  $d \leq n$ .
- Kayal, S., Tavenas (2016): Showed a  $2^{\Omega(n)}$  lower bound on s for  $d \ge n$ .

Both the lower bound proofs are natural.

- Each term  $T_i$  is a product of d linear forms in n variables.
- Klivans & Shpilka (2003): Can we reconstruct homogeneous depth-3 circuits efficiently ?

$$f = T_1 + T_2 + \dots + T_s$$

• Theorem. Let  $n \ge (3d)^2$  and  $s \le (n/3d)^{d/3}$ . There is a randomized poly(n,s) time algorithm to reconstruct <u>non-degenerate</u> (n,d,s) homogeneous depth-3 circuits.

$$f = T_1 + T_2 + \dots + T_s$$

- Theorem. Let  $n \ge (3d)^2$  and  $s \le (n/3d)^{d/3}$ . There is a randomized poly(n,s) time algorithm to reconstruct <u>non-degenerate</u> (n,d,s) homogeneous depth-3 circuits.
- Proper learning. The output is a (n, d, s) homogeneous depth-3 circuit.

$$f = T_1 + T_2 + \dots + T_s$$

- Theorem. Let  $n \ge (3d)^2$  and  $s \le (n/3d)^{d/3}$ . There is a randomized poly(n,s) time algorithm to reconstruct <u>non-degenerate</u> (n,d,s) homogeneous depth-3 circuits.
- The algorithm works under two restrictions:
  ➤ Degree restriction: n ≥ (3d)<sup>2</sup>
  ➤ Non-degeneracy: Next slide...

$$f = T_1 + T_2 + \dots + T_s$$

- Theorem. Let  $n \ge (3d)^2$  and  $s \le (n/3d)^{d/3}$ . There is a randomized poly(n,s) time algorithm to reconstruct <u>non-degenerate</u> (n,d,s) homogeneous depth-3 circuits.
- The algorithm works under two restrictions:
  ➤ Degree restriction: n ≥ (3d)<sup>2</sup> Let's ignore it!
  ➤ Non-degeneracy: Next slide...

Non-degeneracy condition  $f = T_1 + T_2 + \dots + T_s$ 

- Let  $k = \frac{\log s}{\log(n/ed)}$ ,  $U \coloneqq \langle \partial^k f \rangle$  and  $U_i \coloneqq \langle \partial^k T_i \rangle$ . • Clearly,  $U \subseteq U_1 + U_2 + \dots + U_s$ .
- Non-degeneracy\*:  $U = U_1 \oplus U_2 \oplus \cdots \oplus U_s$

Non-degeneracy condition  $f = T_1 + T_2 + \dots + T_s$ 

- Let  $k = \frac{\log s}{\log(n/ed)}$ ,  $U \coloneqq \langle \partial^k f \rangle$  and  $U_i \coloneqq \langle \partial^k T_i \rangle$ . • Clearly,  $U \subseteq U_1 + U_2 + \dots + U_s$ .
- Non-degeneracy\*:  $U = U_1 \oplus U_2 \oplus \cdots \oplus U_s$

equality direct sum

Non-degeneracy condition  $f = T_1 + T_2 + \dots + T_s$  k = O(1) if s = poly(n)• Let  $k = \frac{\log s}{\log(n/ed)}, U \coloneqq \langle \partial^k f \rangle$  and  $U_i \coloneqq \langle \partial^k T_i \rangle$ . • Clearly,  $U \subseteq U_1 + U_2 + \dots + U_s$ .

• Non-degeneracy\*:  $U = U_1 \oplus U_2 \oplus \cdots \oplus U_s$ 

equality direct sum

Non-degeneracy condition  $f = T_1 + T_2 + \dots + T_s$ 

- Let  $k = \frac{\log s}{\log(n/ed)}$ ,  $U \coloneqq \langle \partial^k f \rangle$  and  $U_i \coloneqq \langle \partial^k T_i \rangle$ . • Clearly,  $U \subseteq U_1 + U_2 + \dots + U_s$ .
- Non-degeneracy\*:  $U = U_1 \oplus U_2 \oplus \cdots \oplus U_s$
- A random homogeneous depth-3 circuit is almost surely non-degenerate.

Can we get rid of non-degeneracy condition entirely?
 If yes, then...

- Can we get rid of non-degeneracy condition entirely? If yes, then...
  - > Lower bound for depth-3 circuits: (homogenization) If f(x) is computed by a (n, d, s) depth-3 circuit then  $z^d f(x/z)$  is computed by (n + 1, d, s) homogeneous depth-3 circuit. Thus, we get efficient reconstruction for depth-3 circuits, and [FK09] implies a lower bound for the same class!

- Can we get rid of non-degeneracy condition entirely? If yes, then...
  - Reconstruction for general circuits: (depth reduction) We get n<sup>O(\sqrt{d})</sup> time reconstruction for circuits of size poly(n) via the depth reduction to depth-3 result. [Gupta, Kamath, Kayal, Saptharishi (2013); Tavenas (2013); Koiran (2012); Agrawal & Vinay (2008)]

 Thus, getting an unconditional translation from natural lower bound proofs to efficient reconstruction seems extremely challenging even for homogeneous depth-3 circuits.

- Thus, getting an unconditional translation from natural lower bound proofs to efficient reconstruction seems extremely challenging even for homogeneous depth-3 circuits.
- However, it may be possible to use the natural lower bound framework of a model to do efficient reconstruction for the same model under some nondegeneracy condition that originates from the lower bound proof.

Non-degeneracy condition  $f = T_1 + T_2 + \dots + T_s$ 

- Let  $k = \frac{\log s}{\log(n/ed)}$ ,  $U \coloneqq \langle \partial^k f \rangle$  and  $U_i \coloneqq \langle \partial^k T_i \rangle$ .
- Non-degeneracy\*:  $U = U_1 \oplus U_2 \oplus \cdots \oplus U_s$
- Fact: A crucial aspect of the [NW95] lower bound proof is that each  $U_i$  is "simple" in the sense that it is a low-dimensional space.
Non-degeneracy condition  $f = T_1 + T_2 + \dots + T_s$ 

- Let  $k = \frac{\log s}{\log(n/ed)}$ ,  $U \coloneqq \langle \partial^k f \rangle$  and  $U_i \coloneqq \langle \partial^k T_i \rangle$ .
- Non-degeneracy\*:  $U = U_1 \oplus U_2 \oplus \cdots \oplus U_s$
- The non-degeneracy condition exploits this fact and reduces the reconstruction problem to decomposing the space U into a direct sum of "simple" spaces.

Non-degeneracy condition  $f = T_1 + T_2 + \dots + T_s$ 

• Let 
$$k = \frac{\log s}{\log(n/ed)}$$
,  $U \coloneqq \langle \partial^k f \rangle$  and  $U_i \coloneqq \langle \partial^k T_i \rangle$ .

- Non-degeneracy\*:  $U = U_1 \oplus U_2 \oplus \cdots \oplus U_s$
- The non-degeneracy condition exploits this fact and reduces the reconstruction problem to decomposing the space U into a direct sum of "simple" spaces.

A priori, it is not clear if this decomposition can be done efficiently.

#### **Conceptual contribution**

- A paradigm for handling <u>large fan-in sum gates</u>.
  - > Step 1: Reduce the problem of finding children of a sum gate to decomposition of a suitable space U into "simpler" spaces (using the lower bound framework).
  - > Step 2: Define an appropriate space S of linear operators on U. The structure of S (in our case, the irreducible invariant subspaces of U induced by S) helps retrieve the "simpler" spaces efficiently.

## **Conceptual contribution**

- A paradigm for handling <u>large fan-in sum gates</u>.
- We feel that this paradigm has the potential to give efficient reconstruction for other circuit models for which natural lower bounds are known.

## **Conceptual contribution**

- A paradigm for handling <u>large fan-in sum gates</u>.
- We feel that this paradigm has the potential to give efficient reconstruction for other circuit models for which natural lower bounds are known.
- Prior work on efficient reconstruction (barring those on ROABP / non-commutative ABP / read-once formula) could only handle <u>very low fan-in sum gates</u>.

#### **Related results**

## Restricted depth-3 circuits

- Beimel, Bergadano, Bshouty, Kushilevitz & Varricchio (2000): Randomized poly(n, d, s) time reconstruction for <u>depth-3 powering</u> circuits and <u>set-multilinear depth-3</u> <u>3</u> circuits.
- Klivans & Shpilka (2003): Randomized poly(n, 2<sup>d</sup>, s) time reconstruction for general depth-3 circuits.
- The output hypothesis is an ROABP.

### Restricted depth-3 circuits

- Shpilka (2007): Randomized  $qpoly(n, d, |\mathbb{F}|)$  time reconstruction for <u>depth-3 circuits with top fan-in two</u>.
- Karnin & Shpilka (2009): Deterministic reconstruction for <u>depth-3</u> circuits in poly(n).  $|\mathbb{F}|^{(\log d)^{O(s^3)}}$  time.
- Sinha (2016): Randomized reconstruction for <u>depth-3</u> <u>circuits with top fan-in two over  $\mathbb{R}$ </u> in poly(n, d) time.

## Restricted depth-3 circuits

- Shpilka (2007): Randomized  $qpoly(n, d, |\mathbb{F}|)$  time reconstruction for <u>depth-3 circuits with top fan-in two</u>.
- Karnin & Shpilka (2009): Deterministic reconstruction for <u>depth-3</u> circuits in poly(n).  $|\mathbb{F}|^{(\log d)^{O(s^3)}}$  time.
- Sinha (2016): Randomized reconstruction for <u>depth-3</u> <u>circuits with top fan-in two over  $\mathbb{R}$ </u> in poly(n, d) time.
- These learning algorithms are proper\*.

## **Restricted depth-4 circuits**

- Gupta, Kayal & Lokam (2012): Randomized poly(s) time reconstruction for size s <u>multilinear depth-4 circuits</u> <u>with top fan-in two</u>.
- This learning is also proper.

- Kayal (2012): Randomized poly(n, s<sup>log<sub>d</sub> s</sup>) time reconstruction for <u>depth-3 powering circuits</u>.
- García-Marco, Koiran & Pecatte (2018): Randomized poly(n,s) time reconstruction for <u>depth-3</u> powering <u>circuits</u> for  $s \leq \binom{n+1}{2}$  and  $d \geq 5$ .

- Kayal (2012): Randomized poly(n, s<sup>log<sub>d</sub> s</sup>) time reconstruction for <u>depth-3 powering circuits</u>.
- García-Marco, Koiran & Pecatte (2018): Randomized poly(n,s) time reconstruction for depth-3 powering circuits for  $s \leq \binom{n+1}{2}$  and  $d \geq 5$ .
- Gupta, Kayal & Qiao (2013): Randomized poly(n,s) time reconstruction for <u>fan-in two regular formulas</u>.
- Kayal, Nair & S. (2018): Randomized poly(n, d) time reconstruction for constant width homogeneous ABP.

- Kayal (2012): Randomized poly(n, s<sup>log<sub>d</sub> s</sup>) time reconstruction for <u>depth-3 powering circuits</u>.
- García-Marco, Koiran & Pecatte (2018): Randomized poly(n,s) time reconstruction for depth-3 powering circuits for  $s \leq \binom{n+1}{2}$  and  $d \geq 5$ .
- Gupta, Kayal & Qiao (2013): Randomized poly(n,s) time reconstruction for <u>fan-in two regular formulas</u>.
- Kayal, Nair & S. (2018): Randomized poly(n, d) time reconstruction for constant width homogeneous ABP.

Kayal, S., Saptharishi (2014): Super-poly lower bound known

- Kayal (2012): Randomized poly(n, s<sup>log<sub>d</sub> s</sup>) time reconstruction for <u>depth-3 powering circuits</u>.
- García-Marco, Koiran & Pecatte (2018): Randomized poly(n,s) time reconstruction for depth-3 powering circuits for  $s \leq \binom{n+1}{2}$  and  $d \geq 5$ .
- Gupta, Kayal & Qiao (2013): Randomized poly(n,s) time reconstruction for <u>fan-in two regular formulas</u>.
- Kayal, Nair & S. (2018): Randomized poly(n, d) time reconstruction for constant width homogeneous ABP.

Kumar (2017): Linear width lower bound known

Back to homogeneous depth-3 circuits

#### The algorithm

$$f = T_1 + T_2 + \dots + T_s$$

• Let 
$$k = \frac{\log s}{\log(n/ed)}$$
,  $U \coloneqq \langle \partial^k f \rangle$  and  $U_i \coloneqq \langle \partial^k T_i \rangle$ .

Step 1: Compute a basis of U.
Step 2: Decompose U = U<sub>1</sub> ⊕ U<sub>2</sub> ⊕ … ⊕U<sub>s</sub>.
Step 3: Compute T<sub>i</sub> from a basis of U<sub>i</sub>.

### The algorithm

$$f = T_1 + T_2 + \dots + T_s$$

• Let 
$$k = \frac{\log s}{\log(n/ed)}$$
,  $U \coloneqq \langle \partial^k f \rangle$  and  $U_i \coloneqq \langle \partial^k T_i \rangle$ .

Main step

- > Step 1: Compute a basis of U.
- > Step 2: Decompose  $U = U_1 \oplus U_2 \oplus \cdots \oplus U_s$ .
- > Step 3: Compute  $T_i$  from a basis of  $U_i$ .

# Step 1: Computing a basis of U

- Fact 1: From black-box access to f, we can compute black-box access to  $\frac{\partial f}{\partial x}$  in poly(n, d) time.
- Fact 2: From black-box access to  $f_1, f_2, ..., f_m$ , we can compute black-box access to elements of a basis of  $\langle f_1, f_2, ..., f_m \rangle$  in randomized poly(n, d, m) time.

# Step 1: Computing a basis of U

- Fact 1: From black-box access to f, we can compute black-box access to  $\frac{\partial f}{\partial x}$  in poly(n, d) time.
- Fact 2: From black-box access to  $f_1, f_2, ..., f_m$ , we can compute black-box access to elements of a basis of  $\langle f_1, f_2, ..., f_m \rangle$  in randomized poly(n, d, m) time.
  - > Compute black-box access to elements of  $\partial^k f$  in poly(n, s) time using Fact 1.
  - > Compute black-box access to elements of a basis  $\Gamma = (g_1, ..., g_m)$  of U using Fact 2.

# Step 1: Computing a basis of U

- Fact 1: From black-box access to f, we can compute black-box access to  $\frac{\partial f}{\partial x}$  in poly(n, d) time.
- Fact 2: From black-box access to  $f_1, f_2, ..., f_m$ , we can compute black-box access to elements of a basis of  $\langle f_1, f_2, ..., f_m \rangle$  in randomized poly(n, d, m) time.
  - Compute black-box access to elements of ∂<sup>k</sup>f in poly(n, s) time using Fact 1. [∂<sup>k</sup>f| = (<sup>n+k-1</sup>) = poly(n, s)
     Compute black-box access to elements of a basis Γ = (g<sub>1</sub>, ..., g<sub>m</sub>) of U using Fact 2.

- From Step 2, we have black-box access to elements of a basis (g<sub>i,1</sub>, ..., g<sub>i,m<sub>i</sub></sub>) of U<sub>i</sub>.
- Let Deg(k) be the set of all degree-k monomials in the x-variables.  $|Deg(k)| = \binom{n+k-1}{k} = poly(n,s).$

- From Step 2, we have black-box access to elements of a basis (g<sub>i,1</sub>, ..., g<sub>i,m<sub>i</sub></sub>) of U<sub>i</sub>.
- Let *Deg(k)* be the set of all degree-*k* monomials in the *x*-variables.

> For  $\alpha \in Deg(k)$ , solve for  $c_{\alpha,i,j} \in \mathbb{F}$  such that

 $\sum_{i \in [s]} c_{\alpha,i,1} \cdot g_{i,1} + \dots + c_{\alpha,i,m_i} \cdot g_{i,m_i} = \frac{\partial^{\kappa} f}{\partial \alpha}$ 

- From Step 2, we have black-box access to elements of a basis (g<sub>i,1</sub>, ..., g<sub>i,m<sub>i</sub></sub>) of U<sub>i</sub>.
- Let *Deg(k)* be the set of all degree-*k* monomials in the *x*-variables.
  - For  $\alpha \in Deg(k)$ , solve for  $c_{\alpha,i,j} \in \mathbb{F}$  such that



We have black-box access

- From Step 2, we have black-box access to elements of a basis (g<sub>i,1</sub>, ..., g<sub>i,mi</sub>) of U<sub>i</sub>.
- Let *Deg(k)* be the set of all degree-*k* monomials in the *x*-variables.
  - > For  $\alpha \in Deg(k)$ , solve for  $c_{\alpha,i,j} \in \mathbb{F}$  such that

$$\sum_{i \in [s]} c_{\alpha,i,1} \cdot g_{i,1} + \dots + c_{\alpha,i,m_i} \cdot g_{i,m_i} = \frac{\partial^k f}{\partial \alpha}$$
$$= \frac{\partial^k T_1}{\partial \alpha} + \dots + \frac{\partial^k T_s}{\partial \alpha}$$

> Such a solution satisfies

$$c_{\alpha,i,1} \cdot g_{i,1} + \dots + c_{\alpha,i,m_i} \cdot g_{i,m_i} = \frac{\partial^{\kappa} T_i}{\partial \alpha}$$

- From Step 2, we have black-box access to elements of a basis (g<sub>i,1</sub>, ..., g<sub>i,mi</sub>) of U<sub>i</sub>.
- Let *Deg(k)* be the set of all degree-*k* monomials in the *x*-variables.
  - > Well known identity for homogeneous polynomials

$$T_{i} = \frac{(d-2k)!}{(d-k)!} \cdot \sum_{\alpha \in Deg(k)} \binom{k}{\alpha} \cdot \alpha \cdot \frac{\partial^{k} T_{i}}{\partial \alpha}$$
  
Identifying  $\alpha$  with its

exponent vector

- From Step 2, we have black-box access to elements of a basis (g<sub>i,1</sub>, ..., g<sub>i,mi</sub>) of U<sub>i</sub>.
- Let *Deg(k)* be the set of all degree-*k* monomials in the *x*-variables.
  - > Well known identity for homogeneous polynomials

$$T_i = \frac{(d-2k)!}{(d-k)!} \cdot \sum_{\alpha \in Deg(k)} \binom{k}{\alpha} \cdot \alpha \cdot \frac{\partial^k T_i}{\partial \alpha}$$

Thanks to Gaurav Sinha for showing us this argument for executing Step 3 !

- Let U be a space and S a space of linear operators on U.
- Definition. A space  $V \subseteq U$  is an <u>invariant subspace</u> of U (induced by S) if  $SV \subseteq V$ .

- Let U be a space and S a space of linear operators on U.
- Definition. A space  $V \subseteq U$  is an <u>invariant subspace</u> of U (induced by S) if  $SV \subseteq V$ . Moreover, V is <u>irreducible</u> if there's no invariant subspace properly contained in V.

- Let U be a space and S a space of linear operators on U.
- Definition. A space  $V \subseteq U$  is an <u>invariant subspace</u> of U (induced by S) if  $SV \subseteq V$ . Moreover, V is <u>irreducible</u> if there's no invariant subspace properly contained in V.
- Definition. The <u>closure</u> of vector  $v \in U$  with respect to S is the smallest invariant subspace of U containing v.

- Let U be a space and S a space of linear operators on U.
- Definition. A space  $V \subseteq U$  is an <u>invariant subspace</u> of U (induced by S) if  $SV \subseteq V$ . Moreover, V is <u>irreducible</u> if there's no invariant subspace properly contained in V.
- Definition. The <u>closure</u> of vector  $v \in U$  with respect to S is the smallest invariant subspace of U containing v.
- Fact 3: Given  $v \in \mathbb{F}^m$  and a set of matrices  $\{M_1, \dots, M_t\}$ in  $\mathbb{F}^{m \times m}$ , the closure of v with respect to  $\langle M_1, \dots, M_t \rangle$ can be computed in deterministic poly(m) time.

## Step 2: Decomposing U

- The idea:
  - > Define a suitable space S of linear operators on Usuch that  $U_1, \ldots, U_s$  are irreducible invariant subspaces of U induced by S.
  - > Pick vectors in U carefully such that the closures of these vectors with respect to S give  $U_1, \ldots, U_s$ .

## Step 2: Decomposing U

- The idea:
  - > Define a suitable space S of linear operators on Usuch that  $U_1, \ldots, U_s$  are irreducible invariant subspaces of U induced by S.
  - > Pick vectors in U carefully such that the closures of these vectors with respect to S give  $U_1, \dots, U_s$ .

Simultaneous block diagonalization of a basis of S.

• The shifted differential operator space:

$$\succ \quad S\mathcal{D}_k \coloneqq \left\langle \beta \cdot \frac{\partial^k}{\partial \alpha} : \ \alpha, \beta \in Deg(k) \right\rangle.$$
$$\succ \quad S = S\mathcal{D}_{k,U} \coloneqq \langle \psi \in S\mathcal{D}_k : \psi(U) \subseteq U \rangle.$$

• The shifted differential operator space:

$$\succ \quad S\mathcal{D}_k \coloneqq \left\langle \beta \cdot \frac{\partial^k}{\partial \alpha} : \ \alpha, \beta \in Deg(k) \right\rangle.$$
$$\succ \quad S = S\mathcal{D}_{k,U} \coloneqq \langle \psi \in S\mathcal{D}_k : \psi(U) \subseteq U \rangle.$$

• Observation. A basis  $(\psi_1, ..., \psi_t)$  of S can be computed in poly(n, s) time from a basis  $\Gamma = (g_1, ..., g_m)$  of U.

• The shifted differential operator space:

$$\succ \quad \mathbf{S}\mathbf{D}_k \coloneqq \left\langle \beta \cdot \frac{\partial^k}{\partial \alpha} : \ \alpha, \beta \in Deg(k) \right\rangle.$$
$$\succ \quad \mathbf{S} = \mathbf{S}\mathbf{D}_{k,U} \coloneqq \langle \psi \in \mathbf{S}\mathbf{D}_k : \psi(U) \subseteq U \rangle.$$

- Observation. A basis  $(\psi_1, \dots, \psi_t)$  of S can be computed in poly(n, s) time from a basis  $\Gamma = (g_1, \dots, g_m)$  of U.
- **Proof.** Solve for  $c_{\alpha,\beta}$  and  $d_{i,j}$  in  $\mathbb{F}$  such that

 $\sum_{\alpha,\beta\in Deg(k)} c_{\alpha,\beta} \cdot \beta \cdot \frac{\partial^k g_i}{\partial \alpha} = \sum_{j\in[m]} d_{i,j} \cdot g_j$ for every  $i \in [m]$ .

• The shifted differential operator space:

$$\succ \quad \mathbf{S}\mathbf{D}_k \coloneqq \left\langle \beta \cdot \frac{\partial^k}{\partial \alpha} : \ \alpha, \beta \in Deg(k) \right\rangle.$$
$$\succ \quad \mathbf{S} = \mathbf{S}\mathbf{D}_{k,U} \coloneqq \langle \psi \in \mathbf{S}\mathbf{D}_k : \psi(U) \subseteq U \rangle.$$

- Observation. A basis  $(\psi_1, \dots, \psi_t)$  of S can be computed in poly(n, s) time from a basis  $\Gamma = (g_1, \dots, g_m)$  of U.
- **Proof.** Solve for  $c_{\alpha,\beta}$  and  $d_{i,j}$  in  $\mathbb{F}$  such that

$$\sum_{\alpha,\beta\in Deg(k)} c_{\alpha,\beta} \cdot \beta \cdot \frac{\partial^k g_i}{\partial \alpha} = \sum_{j\in[m]} d_{i,j} \cdot g_j$$
  
for every  $i \in [m]$ .

We have black-box access to these polynomials
• Claim 1.  $U_1, ..., U_s$  are invariant subspaces of U induced by S.

• Claim 1.  $U_1, ..., U_s$  are invariant subspaces of U induced by S.

... follows from the non-degeneracy condition

- Claim 1.  $U_1, ..., U_s$  are invariant subspaces of U induced by S.
- Claim 2. There is an operator  $\psi \in S$  having distinct eigenvalues.

- Claim 1.  $U_1, ..., U_s$  are invariant subspaces of U induced by S.
- Claim 2. There is an operator  $\psi \in S$  having distinct eigenvalues.
- Claim 3.  $U_1, ..., U_s$  are <u>irreducible</u> invariant subspaces of U induced by S.

- Claim 1.  $U_1, ..., U_s$  are invariant subspaces of U induced by S.
- Claim 2. There is an operator  $\psi \in S$  having distinct eigenvalues.
- Claim 3.  $U_1, ..., U_s$  are <u>irreducible</u> invariant subspaces of U induced by S.
- The proofs of *Claim* 2 and *Claim* 3 are a bit technical.

#### • The algorithm.

I. Compute a basis  $(\psi_1, ..., \psi_t)$  of **S** from  $\Gamma = (g_1, ..., g_m)$ . Let  $M_{\Gamma}(\psi_i)$  be the  $m \times m$  matrix associated with  $\psi_i$ .

Once a basis  $\Gamma$  of U is fixed, every operator  $\psi \in S$  can be identified with a unique matrix  $M_{\Gamma}(\psi)$ .

- I. Compute a basis  $(\psi_1, ..., \psi_t)$  of  $\mathcal{S}$  from  $\Gamma = (g_1, ..., g_m)$ . Let  $M_{\Gamma}(\psi_i)$  be the  $m \times m$  matrix associated with  $\psi_i$ .
- 2. Pick  $r_1, ..., r_t \in \mathbb{F}$  randomly. Let  $M_{\Gamma} = \sum_{i \in [t]} r_i \cdot M_{\Gamma}(\psi_i)$ .

- I. Compute a basis  $(\psi_1, ..., \psi_t)$  of **S** from  $\Gamma = (g_1, ..., g_m)$ . Let  $M_{\Gamma}(\psi_i)$  be the  $m \times m$  matrix associated with  $\psi_i$ .
- 2. Pick  $r_1, ..., r_t \in \mathbb{F}$  randomly. Let  $M_{\Gamma} = \sum_{i \in [t]} r_i \cdot M_{\Gamma}(\psi_i)$ .
- 3. Factor the characteristic polynomial h(y) of  $M_{\Gamma}$ . If h is not square-free, output 'Fail'. Else, let  $h = h_1 \cdot h_2 \cdots h_l$ .

- I. Compute a basis  $(\psi_1, ..., \psi_t)$  of **S** from  $\Gamma = (g_1, ..., g_m)$ . Let  $M_{\Gamma}(\psi_i)$  be the  $m \times m$  matrix associated with  $\psi_i$ .
- 2. Pick  $r_1, ..., r_t \in \mathbb{F}$  randomly. Let  $M_{\Gamma} = \sum_{i \in [t]} r_i \cdot M_{\Gamma}(\psi_i)$ .
- 3. Factor the characteristic polynomial h(y) of  $M_{\Gamma}$ . If h is not square-free, output 'Fail'. Else, let  $h = h_1 \cdot h_2 \cdots h_l$ .
- 4. Find the null spaces  $N_1, ..., N_l$  of  $h_1(M_{\Gamma}), ..., h_l(M_{\Gamma})$ .

- I. Compute a basis  $(\psi_1, ..., \psi_t)$  of  $\mathcal{S}$  from  $\Gamma = (g_1, ..., g_m)$ . Let  $M_{\Gamma}(\psi_i)$  be the  $m \times m$  matrix associated with  $\psi_i$ .
- 2. Pick  $r_1, ..., r_t \in \mathbb{F}$  randomly. Let  $M_{\Gamma} = \sum_{i \in [t]} r_i \cdot M_{\Gamma}(\psi_i)$ .
- 3. Factor the characteristic polynomial h(y) of  $M_{\Gamma}$ . If h is not square-free, output 'Fail'. Else, let  $h = h_1 \cdot h_2 \cdots h_l$ .
- 4. Find the null spaces  $N_1, \ldots, N_l$  of  $h_1(M_{\Gamma}), \cdots, h_l(M_{\Gamma})$ .
- 5. For every  $j \in [l]$ , pick a  $v \in N_j$  and compute the closure of v with respect to  $\langle M_{\Gamma}(\psi_1), \dots, M_{\Gamma}(\psi_t) \rangle$ .

- I. Compute a basis  $(\psi_1, ..., \psi_t)$  of  $\mathcal{S}$  from  $\Gamma = (g_1, ..., g_m)$ . Let  $M_{\Gamma}(\psi_i)$  be the  $m \times m$  matrix associated with  $\psi_i$ .
- 2. Pick  $r_1, ..., r_t \in \mathbb{F}$  randomly. Let  $M_{\Gamma} = \sum_{i \in [t]} r_i \cdot M_{\Gamma}(\psi_i)$ .
- 3. Factor the characteristic polynomial h(y) of  $M_{\Gamma}$ . If h is not square-free, output 'Fail'. Else, let  $h = h_1 \cdot h_2 \cdots h_l$ .
- 4. Find the null spaces  $N_1, ..., N_l$  of  $h_1(M_{\Gamma}), ..., h_l(M_{\Gamma})$ .
- 5. For every  $j \in [l]$ , pick a  $v \in N_j$  and compute the closure of v with respect to  $\langle M_{\Gamma}(\psi_1), \dots, M_{\Gamma}(\psi_t) \rangle$ .
- 6. Let  $\{W_1, ..., W_p\}$  be the set of these closure spaces. If  $p \neq s$ , return 'Fail'. Else, return bases of  $\{\Gamma \cdot W_1, ..., \Gamma \cdot W_s\}$ .

- Analyzing the algorithm.
  - I. Compute a basis  $(\psi_1, ..., \psi_t)$  of **S** from  $\Gamma = (g_1, ..., g_m)$ . Let  $M_{\Gamma}(\psi_i)$  be the  $m \times m$  matrix associated with  $\psi_i$ .
  - 2. Pick  $r_1, \ldots, r_t \in \mathbb{F}$  randomly. Let  $M_{\Gamma} = \sum_{i \in [t]} r_i \cdot M_{\Gamma}(\psi_i)$ .

A random operator in  $\boldsymbol{S}$ 

- Analyzing the algorithm.
  - I. Compute a basis  $(\psi_1, ..., \psi_t)$  of **S** from  $\Gamma = (g_1, ..., g_m)$ . Let  $M_{\Gamma}(\psi_i)$  be the  $m \times m$  matrix associated with  $\psi_i$ .
  - 2. Pick  $r_1, ..., r_t \in \mathbb{F}$  randomly. Let  $M_{\Gamma} = \sum_{i \in [t]} r_i \cdot M_{\Gamma}(\psi_i)$ .
  - 3. Factor the characteristic polynomial h(y) of  $M_{\Gamma}$ . If h is not square-free, output 'Fail'. Else, let  $h = h_1 \cdot h_2 \cdots h_l$ .

*h* is square-free w.h.p (by *Claim* 2).

Claim 2. There is an operator  $\psi \in S$  having distinct eigenvalues.

- Analyzing the algorithm.
  - I. Compute a basis  $(\psi_1, ..., \psi_t)$  of **S** from  $\Gamma = (g_1, ..., g_m)$ . Let  $M_{\Gamma}(\psi_i)$  be the  $m \times m$  matrix associated with  $\psi_i$ .
  - 2. Pick  $r_1, ..., r_t \in \mathbb{F}$  randomly. Let  $M_{\Gamma} = \sum_{i \in [t]} r_i \cdot M_{\Gamma}(\psi_i)$ .
  - 3. Factor the characteristic polynomial h(y) of  $M_{\Gamma}$ . If h is not square-free, output 'Fail'. Else, let  $h = h_1 \cdot h_2 \cdots h_l$ .

*h* is square-free w.h.p (by *Claim* 2).

Claim 2.  $\implies$  A random operator in  $\mathcal{S}$  has distinct eigenvalues.

- Analyzing the algorithm.
  - I. Compute a basis  $(\psi_1, ..., \psi_t)$  of **S** from  $\Gamma = (g_1, ..., g_m)$ . Let  $M_{\Gamma}(\psi_i)$  be the  $m \times m$  matrix associated with  $\psi_i$ .
  - 2. Pick  $r_1, ..., r_t \in \mathbb{F}$  randomly. Let  $M_{\Gamma} = \sum_{i \in [t]} r_i \cdot M_{\Gamma}(\psi_i)$ .
  - 3. Factor the characteristic polynomial h(y) of  $M_{\Gamma}$ . If h is not square-free, output 'Fail'. Else, let  $h = h_1 \cdot h_2 \cdots h_l$ .
  - 4. Find the null spaces  $N_1, ..., N_l$  of  $h_1(M_{\Gamma}), ..., h_l(M_{\Gamma})$ .

Once a basis  $\Gamma$  of U is fixed, every  $U_i$  can be identified with a space  $U_{i,\Gamma} \subseteq \mathbb{F}^m$ .

*Claim* 4. Every  $N_i$  is contained in some  $U_{i,\Gamma}$ . (Proof later)

- Analyzing the algorithm.
  - I. Compute a basis  $(\psi_1, ..., \psi_t)$  of **S** from  $\Gamma = (g_1, ..., g_m)$ . Let  $M_{\Gamma}(\psi_i)$  be the  $m \times m$  matrix associated with  $\psi_i$ .
  - 2. Pick  $r_1, ..., r_t \in \mathbb{F}$  randomly. Let  $M_{\Gamma} = \sum_{i \in [t]} r_i \cdot M_{\Gamma}(\psi_i)$ .
  - 3. Factor the characteristic polynomial h(y) of  $M_{\Gamma}$ . If h is not square-free, output 'Fail'. Else, let  $h = h_1 \cdot h_2 \cdots h_l$ .
  - 4. Find the null spaces  $N_1, ..., N_l$  of  $h_1(M_{\Gamma}), ..., h_l(M_{\Gamma})$ .
  - 5. For every  $j \in [l]$ , pick a  $v \in N_j$  and compute the closure of v with respect to  $\langle M_{\Gamma}(\psi_1), \dots, M_{\Gamma}(\psi_t) \rangle$ .
  - 6. Let  $\{W_1, ..., W_p\}$  be the set of these closure spaces. If  $p \neq s$ , return 'Fail'. Else, return bases of  $\{\Gamma \cdot W_1, ..., \Gamma \cdot W_s\}$ .

*Obs.*  $\{W_1, \dots, W_s\}$  are the spaces  $\{U_{1,\Gamma}, \dots, U_{s,\Gamma}\}$  (by *Claim* 3)

- Claim 4. Every  $N_i$  is contained in some  $U_{i,\Gamma}$ .
- *Proof*.  $N_j$  is the null space of  $h_j(M_{\Gamma})$ . The statement of the claim is independent of the choice of basis  $\Gamma$ . Assume that  $\Gamma$  is a basis formed by taking union of bases of  $U_1, \ldots, U_s$ .

- Claim 4. Every  $N_i$  is contained in some  $U_{i,\Gamma}$ .
- Proof.  $N_j$  is the null space of  $h_j(M_{\Gamma})$ . By Claim 1,

 $M_{\Gamma} = \begin{pmatrix} R_1 & & \\ & \ddots & \\ & & R_s \end{pmatrix}, \text{ is a block-diagonal matrix.}$ 

- Claim 4. Every  $N_i$  is contained in some  $U_{i,\Gamma}$ .
- Proof.  $N_j$  is the null space of  $h_j(M_{\Gamma})$ . By Claim 1,

 $M_{\Gamma} = \begin{pmatrix} R_1 \\ \ddots \\ R_s \end{pmatrix}, \text{ is a block-diagonal matrix.}$ Let  $p_i$  be the characteristic polynomial of  $R_i$ . Then,

$$h = p_1 \cdot p_2 \cdots p_s = h_1 \cdot h_2 \cdots h_l$$

- Claim 4. Every  $N_i$  is contained in some  $U_{i,\Gamma}$ .
- *Proof*.  $N_j$  is the null space of  $h_j(M_{\Gamma})$ . By *Claim* 1,

 $M_{\Gamma} = \begin{pmatrix} R_1 & & \\ & \ddots & \\ & & R_s \end{pmatrix}, \text{ is a block-diagonal matrix.}$ 

Let  $p_i$  be the characteristic polynomial of  $R_i$ .  $h_j$  divides some  $p_i$ .

- Claim 4. Every  $N_i$  is contained in some  $U_{i,\Gamma}$ .
- Proof.  $N_j$  is the null space of  $h_j(M_{\Gamma})$ . By Claim 1,

 $M_{\Gamma} = \begin{pmatrix} R_1 & & \\ & \ddots & \\ & R_s \end{pmatrix}, \text{ is a block-diagonal matrix.}$ Let  $p_i$  be the characteristic polynomial of  $R_i$ .  $h_j$  divides some  $p_i$ . For  $v \in N_i$ ,

$$p_i(M_{\Gamma}) = \begin{pmatrix} p_i(R_1) & & \\ & \ddots & \\ & & p_i(R_s) \end{pmatrix}$$

- Claim 4. Every  $N_i$  is contained in some  $U_{i,\Gamma}$ .
- *Proof*.  $N_j$  is the null space of  $h_j(M_{\Gamma})$ . By *Claim* 1,

 $M_{\Gamma} = \begin{pmatrix} R_1 \\ \ddots \\ R_s \end{pmatrix}, \text{ is a block-diagonal matrix.}$ Let  $p_i$  be the characteristic polynomial of  $R_i$ .  $h_j$  divides some  $p_i$ . For  $v \in N_j$ ,

$$p_i(M_{\Gamma}) \cdot v = \begin{pmatrix} p_i(R_1) & & \\ & \ddots & \\ & & p_i(R_s) \end{pmatrix} \cdot v = 0$$

- Claim 4. Every  $N_i$  is contained in some  $U_{i,\Gamma}$ .
- *Proof*.  $N_j$  is the null space of  $h_j(M_{\Gamma})$ . By *Claim* 1,

 $M_{\Gamma} = \begin{pmatrix} R_1 & & \\ & \ddots & \\ & R_s \end{pmatrix}, \text{ is a block-diagonal matrix.}$ Let  $p_i$  be the characteristic polynomial of  $R_i$ .  $h_j$  divides some  $p_i$ . For  $v \in N_i$ ,

$$p_i(M_{\Gamma}) \cdot v = \begin{pmatrix} p_i(R_1) & & \\ & \ddots & \\ & & p_i(R_s) \end{pmatrix} \cdot \begin{bmatrix} v_1 \\ \vdots \\ v_s \end{bmatrix} = 0$$

- Claim 4. Every  $N_i$  is contained in some  $U_{i,\Gamma}$ .
- *Proof*.  $N_j$  is the null space of  $h_j(M_{\Gamma})$ . By *Claim* 1,

 $M_{\Gamma} = \begin{pmatrix} \kappa_1 & & \\ & \ddots & \\ & R_s \end{pmatrix}, \text{ is a block-diagonal matrix.}$ Let  $p_i$  be the characteristic polynomial of  $R_i$ .  $h_j$  divides some  $p_i$ . For  $v \in N_i$ ,

$$p_{i}(M_{\Gamma}) \cdot v = \begin{pmatrix} p_{i}(R_{1}) & & \\ & \ddots & \\ & & p_{i}(R_{s}) \end{pmatrix} \cdot \begin{bmatrix} v_{1} \\ \vdots \\ v_{s} \end{bmatrix} = 0$$
$$p_{i}(R_{q}) \cdot v_{q} = 0 \text{ for every } q \in [s].$$

- Claim 4. Every  $N_i$  is contained in some  $U_{i,\Gamma}$ .
- *Proof*.  $N_j$  is the null space of  $h_j(M_{\Gamma})$ . By *Claim* 1,

 $M_{\Gamma} = \begin{pmatrix} R_1 & & \\ & \ddots & \\ & & R_2 \end{pmatrix}, \text{ is a block-diagonal matrix.}$ 

 $p_i(R_q) \cdot v_q = 0$  for every  $q \in [s]$ . Pick any  $q \neq i$ .

- Claim 4. Every  $N_i$  is contained in some  $U_{i,\Gamma}$ .
- *Proof*.  $N_j$  is the null space of  $h_j(M_{\Gamma})$ . By *Claim* 1,

 $M_{\Gamma} = \begin{pmatrix} \kappa_1 & & \\ & \ddots & \\ & & R_s \end{pmatrix}, \text{ is a block-diagonal matrix.}$  $p_i(R_q) \cdot v_q = 0 \text{ for every } q \in [s]. \text{ Pick any } q \neq i. \text{ As } h \text{ is square-free, there are polynomials } e_1, e_2 \text{ such that}$ 

$$e_1 \cdot p_i + e_2 \cdot p_q = 1$$

- Claim 4. Every  $N_i$  is contained in some  $U_{i,\Gamma}$ .
- *Proof*.  $N_j$  is the null space of  $h_j(M_{\Gamma})$ . By *Claim* 1,

 $M_{\Gamma} = \begin{pmatrix} \kappa_1 & & \\ & \ddots & \\ & & R_s \end{pmatrix}, \text{ is a block-diagonal matrix.}$  $p_i(R_q) \cdot v_q = 0 \text{ for every } q \in [s]. \text{ Pick any } q \neq i. \text{ As } h \text{ is square-free, there are polynomials } e_1, e_2 \text{ such that}$ 

 $e_1 \cdot p_i + e_2 \cdot p_q = 1$  $e_1(R_q) \cdot p_i(R_q) = I_m$ 

- Claim 4. Every  $N_i$  is contained in some  $U_{i,\Gamma}$ .
- *Proof*.  $N_j$  is the null space of  $h_j(M_{\Gamma})$ . By *Claim* 1,

 $M_{\Gamma} = \begin{pmatrix} \kappa_1 & & \\ & \ddots & \\ & & R_s \end{pmatrix}, \text{ is a block-diagonal matrix.}$  $p_i(R_q) \cdot v_q = 0 \text{ for every } q \in [s]. \text{ Pick any } q \neq i. \text{ As } h \text{ is square-free, there are polynomials } e_1, e_2 \text{ such that}$ 

$$e_1 \cdot p_i + e_2 \cdot p_q = 1$$
$$e_1(R_q) \cdot p_i(R_q) \cdot v_q = v_q = 0.$$

 $:: v \in U_{i,\Gamma} .$ 

• We give an efficient reconstruction algorithm for nondegenerate homogeneous depth-3 circuits where both the algorithm and the non-degeneracy condition <u>originate from the [NW95] natural lower bound proof</u>.

- We give an efficient reconstruction algorithm for nondegenerate homogeneous depth-3 circuits where both the algorithm and the non-degeneracy condition originate from the [NW95] natural lower bound proof.
- In doing so, we give a <u>paradigm for handling large fan-in</u> <u>sum gates</u> by reducing the problem to decomposition of a suitable space U, and then solving this decomposition problem by defining an appropriate space S of operators on U and examining its structure.

• The particular operator space we work with is the <u>shifted differential operator space</u>. It shows the effectiveness of shifted derivatives in reconstruction problems.

- The particular operator space we work with is the shifted differential operator space. It shows the effectiveness of shifted derivatives in solving reconstruction problems.
- The paradigm has the <u>potential to give efficient</u> reconstruction for other models for which natural lower bounds are known. Homogeneous depth-4 circuits, constant depth multilinear circuits, regular formulas are instances of such models.

- The particular operator space we work with is the shifted differential operator space. It shows the effectiveness of shifted derivatives in solving reconstruction problems.
- The paradigm has the <u>potential to give efficient</u> <u>reconstruction for other models</u> for which natural lower bounds are known. Homogeneous depth-4 circuits, constant depth multilinear circuits, regular formulas are instances of such models.