The GCT Program: Recent developments and concrete open problems

Ketan D. Mulmuley

The University of Chicago

November 30, 2018

▲□▶ ▲□▶ ▲ □▶ ▲ □▶ □ のへぐ

[GCT5][M.]: Geometric Complexity Theory V: Efficient algorithms for Noether Normalization.

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三三 - のへぐ

[GCT5][M.]: Geometric Complexity Theory V: Efficient algorithms for Noether Normalization.

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ □臣 ○のへ⊙

Extended abstract: FOCS 2012.

[GCT5][M.]: Geometric Complexity Theory V: Efficient algorithms for Noether Normalization.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Extended abstract: FOCS 2012.

Journal version: JAMS 2017.

► *K*: An algebraically closed field of characteristic zero.

- ► *K*: An algebraically closed field of characteristic zero.
- ► VP: The class of families of polynomials that can be computed by algebraic circuits over K of polynomial degree and size.

▲□▶ ▲□▶ ▲ □▶ ▲ □▶ □ のへぐ

- ► *K*: An algebraically closed field of characteristic zero.
- ► VP: The class of families of polynomials that can be computed by algebraic circuits over K of polynomial degree and size.
- ► VP_{ws} : The class of families of polynomials that can be computed by symbolic determinants over K of polynomial size.

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

- ► *K*: An algebraically closed field of characteristic zero.
- ► VP: The class of families of polynomials that can be computed by algebraic circuits over K of polynomial degree and size.
- ► VP_{ws} : The class of families of polynomials that can be computed by symbolic determinants over K of polynomial size.
- ► VNP: The class of families of *p*-definable polynomials (e.g. the permanent).

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

- ► *K*: An algebraically closed field of characteristic zero.
- ► VP: The class of families of polynomials that can be computed by algebraic circuits over K of polynomial degree and size.
- ► VP_{ws} : The class of families of polynomials that can be computed by symbolic determinants over K of polynomial size.
- ► VNP: The class of families of *p*-definable polynomials (e.g. the permanent).
- ► VP: The class of families of polynomials that can be approximated infinitesimally closely by algebraic circuits over K of polynomial degree and size.

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

- ► *K*: An algebraically closed field of characteristic zero.
- ► VP: The class of families of polynomials that can be computed by algebraic circuits over K of polynomial degree and size.
- ► VP_{ws} : The class of families of polynomials that can be computed by symbolic determinants over K of polynomial size.
- ► VNP: The class of families of *p*-definable polynomials (e.g. the permanent).
- ► VP: The class of families of polynomials that can be approximated infinitesimally closely by algebraic circuits over K of polynomial degree and size.
- ► VP_{ws}: The class of families of polynomials that can be approximated infinitesimally closely by symbolic determinants over K of polynomial size.

The battleground of GCT: The VP vs. \overline{VP} problem

▲□▶▲圖▶▲≣▶▲≣▶ ≣ のQ@

| ◆ □ ▶ ◆ □ ▶ ◆ □ ▶ → □ ● ● ● ● ●

The hardness hypothesis of GCT (GCT1:MS2001): VNP $\not\subseteq \overline{VP}$.

The hardness hypothesis of GCT (GCT1:MS2001): VNP $\not\subseteq \overline{VP}$.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Any realistic approach to the $\rm VP$ vs. $\rm VNP$ problem can be expected to prove this stronger form of Valiant's conjecture.

The hardness hypothesis of GCT (GCT1:MS2001): VNP $\not\subseteq \overline{VP}$.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Any realistic approach to the $\rm VP$ vs. $\rm VNP$ problem can be expected to prove this stronger form of Valiant's conjecture.

Question [GCT1,B,BLMW]: Is $\overline{VP} = VP$?

The hardness hypothesis of GCT (GCT1:MS2001): VNP $\not\subseteq \overline{VP}$.

Any realistic approach to the VP vs. VNP problem can be expected to prove this stronger form of Valiant's conjecture. Question [GCT1,B,BLMW]: Is $\overline{VP} = VP$?

 Related to foundational issues in algebraic geometry and representation theory [GCT6].

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

The hardness hypothesis of GCT (GCT1:MS2001): VNP $\not\subseteq \overline{VP}$. Any realistic approach to the VP vs. VNP problem can be expected to prove this stronger form of Valiant's conjecture. Question [GCT1,B,BLMW]: Is $\overline{VP} = VP$?

 Related to foundational issues in algebraic geometry and representation theory [GCT6]. [Not covered in this lecture].

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

The hardness hypothesis of GCT (GCT1:MS2001): $VNP \not\subseteq \overline{VP}$. Any realistic approach to the VP vs. VNP problem can be expected to prove this stronger form of Valiant's conjecture. Question [GCT1,B,BLMW]: Is $\overline{VP} = VP$?

- Related to foundational issues in algebraic geometry and representation theory [GCT6]. [Not covered in this lecture].
- The cause of a deep difficulty at the interface of algebraic geometry, representation theory and complexity theory, called the GCT chasm, which arises in the context of the VP vs. VNP problem,

The hardness hypothesis of GCT (GCT1:MS2001): $VNP \not\subseteq \overline{VP}$. Any realistic approach to the VP vs. VNP problem can be expected to prove this stronger form of Valiant's conjecture. Question [GCT1,B,BLMW]: Is $\overline{VP} = VP$?

- Related to foundational issues in algebraic geometry and representation theory [GCT6]. [Not covered in this lecture].
- The cause of a deep difficulty at the interface of algebraic geometry, representation theory and complexity theory, called the GCT chasm, which arises in the context of the VP vs. VNP problem, regardless of whether the answer to this question is affirmative or negative

The hardness hypothesis of GCT (GCT1:MS2001): $VNP \not\subseteq \overline{VP}$. Any realistic approach to the VP vs. VNP problem can be expected to prove this stronger form of Valiant's conjecture. Question [GCT1,B,BLMW]: Is $\overline{VP} = VP$?

- Related to foundational issues in algebraic geometry and representation theory [GCT6]. [Not covered in this lecture].
- The cause of a deep difficulty at the interface of algebraic geometry, representation theory and complexity theory, called the GCT chasm, which arises in the context of the VP vs. VNP problem, regardless of whether the answer to this question is affirmative or negative [GCT5]

The hardness hypothesis of GCT (GCT1:MS2001): $VNP \not\subseteq \overline{VP}$. Any realistic approach to the VP vs. VNP problem can be expected to prove this stronger form of Valiant's conjecture. Question [GCT1,B,BLMW]: Is $\overline{VP} = VP$?

- Related to foundational issues in algebraic geometry and representation theory [GCT6]. [Not covered in this lecture].
- The cause of a deep difficulty at the interface of algebraic geometry, representation theory and complexity theory, called the GCT chasm, which arises in the context of the VP vs. VNP problem, regardless of whether the answer to this question is affirmative or negative [GCT5] [This lecture].

The hardness hypothesis of GCT (GCT1:MS2001): VNP $\not\subseteq \overline{VP}$. Any realistic approach to the VP vs. VNP problem can be expected to prove this stronger form of Valiant's conjecture. Question [GCT1,B,BLMW]: Is $\overline{VP} = VP$?

- Related to foundational issues in algebraic geometry and representation theory [GCT6]. [Not covered in this lecture].
- The cause of a deep difficulty at the interface of algebraic geometry, representation theory and complexity theory, called the GCT chasm, which arises in the context of the VP vs. VNP problem, regardless of whether the answer to this question is affirmative or negative [GCT5] [This lecture].
- ► This difficulty has to be overcome by any approach to the VP vs. VNP problem that seeks to separate VNP from VP.

The hardness hypothesis of GCT (GCT1:MS2001): VNP $\not\subseteq \overline{VP}$. Any realistic approach to the VP vs. VNP problem can be expected to prove this stronger form of Valiant's conjecture. Question [GCT1,B,BLMW]: Is $\overline{VP} = VP$?

- Related to foundational issues in algebraic geometry and representation theory [GCT6]. [Not covered in this lecture].
- The cause of a deep difficulty at the interface of algebraic geometry, representation theory and complexity theory, called the GCT chasm, which arises in the context of the VP vs. VNP problem, regardless of whether the answer to this question is affirmative or negative [GCT5] [This lecture].
- This difficulty has to be overcome by any approach to the VP vs. VNP problem that seeks to separate VNP from VP. We call any such approach a GCT approach in a broad sense.

▲□▶▲圖▶▲≣▶▲≣▶ ≣ の�?

Let Y be an m × m variable matrix, X an n × n submatrix of Y, n < m, and z any entry of Y outside X.</p>

- Let Y be an m × m variable matrix, X an n × n submatrix of Y, n < m, and z any entry of Y outside X.</p>
- ► V = K[Y]_m: The space of homogeneous forms of degree m in the entries of Y.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

- Let Y be an m × m variable matrix, X an n × n submatrix of Y, n < m, and z any entry of Y outside X.</p>
- ► V = K[Y]_m: The space of homogeneous forms of degree m in the entries of Y.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

• $\mathbb{P}(V)$: The projective space associated with V.

- Let Y be an m × m variable matrix, X an n × n submatrix of Y, n < m, and z any entry of Y outside X.</p>
- ► V = K[Y]_m: The space of homogeneous forms of degree m in the entries of Y.
- $\mathbb{P}(V)$: The projective space associated with V.
- Σ[det, m] ⊆ P(V): The set of all points in P(V) corresponding to non-zero homogeneous polynomials in the entries of Y,

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

- Let Y be an m × m variable matrix, X an n × n submatrix of Y, n < m, and z any entry of Y outside X.</p>
- ► V = K[Y]_m: The space of homogeneous forms of degree m in the entries of Y.
- $\mathbb{P}(V)$: The projective space associated with V.
- Σ[det, m] ⊆ P(V): The set of all points in P(V) corresponding to non-zero homogeneous polynomials in the entries of Y, which can be expressed as determinants of symbolic m × m matrices,

- Let Y be an m × m variable matrix, X an n × n submatrix of Y, n < m, and z any entry of Y outside X.</p>
- ► V = K[Y]_m: The space of homogeneous forms of degree m in the entries of Y.
- $\mathbb{P}(V)$: The projective space associated with V.
- ∑[det, m] ⊆ ℙ(V): The set of all points in ℙ(V) corresponding to non-zero homogeneous polynomials in the entries of Y, which can be expressed as determinants of symbolic m × m matrices, whose entries are homogeneous linear functions of the entries of Y

- Let Y be an m × m variable matrix, X an n × n submatrix of Y, n < m, and z any entry of Y outside X.</p>
- ► V = K[Y]_m: The space of homogeneous forms of degree m in the entries of Y.
- $\mathbb{P}(V)$: The projective space associated with V.
- ∑[det, m] ⊆ P(V): The set of all points in P(V) corresponding to non-zero homogeneous polynomials in the entries of Y, which can be expressed as determinants of symbolic m × m matrices, whose entries are homogeneous linear functions of the entries of Y (a constructible set).

- ▶ Let Y be an m × m variable matrix, X an n × n submatrix of Y, n < m, and z any entry of Y outside X.</p>
- ► V = K[Y]_m: The space of homogeneous forms of degree m in the entries of Y.
- $\mathbb{P}(V)$: The projective space associated with V.
- ∑[det, m] ⊆ P(V): The set of all points in P(V) corresponding to non-zero homogeneous polynomials in the entries of Y, which can be expressed as determinants of symbolic m × m matrices, whose entries are homogeneous linear functions of the entries of Y (a constructible set).

► $\Delta[\det, m] = \overline{\Sigma[\det, m]} \subseteq \mathbb{P}(V)$: The Zariski closure of $\Sigma[\det, m]$ in $\mathbb{P}(V)$

- ▶ Let Y be an m × m variable matrix, X an n × n submatrix of Y, n < m, and z any entry of Y outside X.</p>
- ► V = K[Y]_m: The space of homogeneous forms of degree m in the entries of Y.
- $\mathbb{P}(V)$: The projective space associated with V.
- ∑[det, m] ⊆ P(V): The set of all points in P(V) corresponding to non-zero homogeneous polynomials in the entries of Y, which can be expressed as determinants of symbolic m × m matrices, whose entries are homogeneous linear functions of the entries of Y (a constructible set).

► $\Delta[\det, m] = \overline{\Sigma[\det, m]} \subseteq \mathbb{P}(V)$: The Zariski closure of $\Sigma[\det, m]$ in $\mathbb{P}(V)$ (a variety).

- Let Y be an m × m variable matrix, X an n × n submatrix of Y, n < m, and z any entry of Y outside X.</p>
- ► V = K[Y]_m: The space of homogeneous forms of degree m in the entries of Y.
- $\mathbb{P}(V)$: The projective space associated with V.
- ∑[det, m] ⊆ P(V): The set of all points in P(V) corresponding to non-zero homogeneous polynomials in the entries of Y, which can be expressed as determinants of symbolic m × m matrices, whose entries are homogeneous linear functions of the entries of Y (a constructible set).
- ► $\Delta[\det, m] = \overline{\Sigma[\det, m]} \subseteq \mathbb{P}(V)$: The Zariski closure of $\Sigma[\det, m]$ in $\mathbb{P}(V)$ (a variety).
- △[det, m] also equals the GL_{m²}(K)-orbit-closure of det(Y) ∈ P(V) under the natural action of GL_{m²}(K) on P(V).

Reformulation of the $\overline{\mathrm{VP}_{ws}}$ vs. VNP problem (continued)

▲□▶▲圖▶▲≣▶▲≣▶ ≣ の�?

Reformulation of the $\overline{VP_{ws}}$ vs. VNP problem (continued)

The VNP ⊈ VP_{ws} conjecture [Valiant] is equivalent to saying that z^{m-n}perm(X) ∉ Σ[det, m].

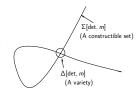
Reformulation of the $\overline{VP_{ws}}$ vs. VNP problem (continued)

- The VNP ⊈ VP_{ws} conjecture [Valiant] is equivalent to saying that z^{m-n}perm(X) ∉ Σ[det, m].
- The VNP ∉ VP_{ws} conjecture [GCT1] is equivalent to saying that z^{m-n}perm(X) ∉ Δ[det, m].

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Reformulation of the $\overline{VP_{ws}}$ vs. VNP problem (continued)

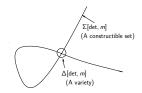
- The VNP ⊈ VP_{ws} conjecture [Valiant] is equivalent to saying that z^{m-n}perm(X) ∉ Σ[det, m].
- The VNP ∉ VP_{ws} conjecture [GCT1] is equivalent to saying that z^{m-n}perm(X) ∉ Δ[det, m].



▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

Reformulation of the $\overline{\mathrm{VP}_{\mathrm{ws}}}$ vs. VNP problem (continued)

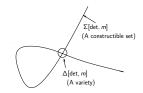
- The VNP ⊈ VP_{ws} conjecture [Valiant] is equivalent to saying that z^{m-n}perm(X) ∉ Σ[det, m].
- The VNP ⊈ VP_{ws} conjecture [GCT1] is equivalent to saying that z^{m-n}perm(X) ∉ Δ[det, m].



The geometry of Σ[det, m] is controlled by the singularities of Δ[det, m]. Hence their structure is important in the context of the VP_{ws} vs. VP_{ws} and VP_{ws} vs. VNP problems.

Reformulation of the $\overline{\mathrm{VP}_{\mathrm{ws}}}$ vs. VNP problem (continued)

- The VNP ⊈ VP_{ws} conjecture [Valiant] is equivalent to saying that z^{m-n}perm(X) ∉ Σ[det, m].
- The VNP ∉ VP_{ws} conjecture [GCT1] is equivalent to saying that z^{m-n}perm(X) ∉ Δ[det, m].



- The geometry of Σ[det, m] is controlled by the singularities of Δ[det, m]. Hence their structure is important in the context of the VP_{ws} vs. VP_{ws} and VP_{ws} vs. VNP problems.
- Unfortunately, the singularities of Δ[det, m] are not even normal [Kumar]. This is the beginning of difficulties [Next].

Hilbert: There exists a homogeneous linear map $\psi : V \to K^k$, for any $k > \dim(\Delta[\det, m])$, such that ψ does not vanish on any non-zero point in the affine cone $\hat{\Delta}[\det, m] \subseteq V$ of $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

Hilbert: There exists a homogeneous linear map $\psi : V \to K^k$, for any $k > \dim(\Delta[\det, m])$, such that ψ does not vanish on any non-zero point in the affine cone $\hat{\Delta}[\det, m] \subseteq V$ of $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

This means the rational map $\hat{\psi} : \mathbb{P}(V) \dashrightarrow \mathbb{P}(K^k)$ is regular (well-defined) on $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

Hilbert: There exists a homogeneous linear map $\psi : V \to K^k$, for any $k > \dim(\Delta[\det, m])$, such that ψ does not vanish on any non-zero point in the affine cone $\hat{\Delta}[\det, m] \subseteq V$ of $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

This means the rational map $\hat{\psi} : \mathbb{P}(V) \dashrightarrow \mathbb{P}(K^k)$ is regular (well-defined) on $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

We call such a homogeneous, linear map $\psi: V \to K^k$ a normalizing map for $\Delta[\det, m]$.

Hilbert: There exists a homogeneous linear map $\psi : V \to K^k$, for any $k > \dim(\Delta[\det, m])$, such that ψ does not vanish on any non-zero point in the affine cone $\hat{\Delta}[\det, m] \subseteq V$ of $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

This means the rational map $\hat{\psi} : \mathbb{P}(V) \dashrightarrow \mathbb{P}(K^k)$ is regular (well-defined) on $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

We call such a homogeneous, linear map $\psi: V \to K^k$ a normalizing map for $\Delta[\det, m]$.

The Problem NNL:

Hilbert: There exists a homogeneous linear map $\psi : V \to K^k$, for any $k > \dim(\Delta[\det, m])$, such that ψ does not vanish on any non-zero point in the affine cone $\hat{\Delta}[\det, m] \subseteq V$ of $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

This means the rational map $\hat{\psi} : \mathbb{P}(V) \dashrightarrow \mathbb{P}(K^k)$ is regular (well-defined) on $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

We call such a homogeneous, linear map $\psi: V \to K^k$ a normalizing map for $\Delta[\det, m]$.

The Problem NNL:

Given $\Delta[\det, m]$, with a succinct specification, construct a normalizing map $\psi: V \to K^k$, with k = poly(m), with a succinct specification.

Hilbert: There exists a homogeneous linear map $\psi : V \to K^k$, for any $k > \dim(\Delta[\det, m])$, such that ψ does not vanish on any non-zero point in the affine cone $\hat{\Delta}[\det, m] \subseteq V$ of $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

This means the rational map $\hat{\psi} : \mathbb{P}(V) \dashrightarrow \mathbb{P}(K^k)$ is regular (well-defined) on $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

We call such a homogeneous, linear map $\psi: V \to K^k$ a normalizing map for $\Delta[\det, m]$.

The Problem NNL:

Given $\Delta[\det, m]$, with a succinct specification, construct a normalizing map $\psi: V \to K^k$, with k = poly(m), with a succinct specification.

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

Succinct means of poly(m) size.

Hilbert: There exists a homogeneous linear map $\psi : V \to K^k$, for any $k > \dim(\Delta[\det, m])$, such that ψ does not vanish on any non-zero point in the affine cone $\hat{\Delta}[\det, m] \subseteq V$ of $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

This means the rational map $\hat{\psi} : \mathbb{P}(V) \dashrightarrow \mathbb{P}(K^k)$ is regular (well-defined) on $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

We call such a homogeneous, linear map $\psi: V \to K^k$ a normalizing map for $\Delta[\det, m]$.

The Problem NNL:

Given $\Delta[\det, m]$, with a succinct specification, construct a normalizing map $\psi: V \to K^k$, with k = poly(m), with a succinct specification.

Succinct means of poly(m) size. The usual specifications of $\Delta[\det, m] \subseteq \mathbb{P}(V)$ by its equations

Hilbert: There exists a homogeneous linear map $\psi : V \to K^k$, for any $k > \dim(\Delta[\det, m])$, such that ψ does not vanish on any non-zero point in the affine cone $\hat{\Delta}[\det, m] \subseteq V$ of $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

This means the rational map $\hat{\psi} : \mathbb{P}(V) \dashrightarrow \mathbb{P}(K^k)$ is regular (well-defined) on $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

We call such a homogeneous, linear map $\psi: V \to K^k$ a normalizing map for $\Delta[\det, m]$.

The Problem NNL:

Given $\Delta[\det, m]$, with a succinct specification, construct a normalizing map $\psi: V \to K^k$, with k = poly(m), with a succinct specification.

Succinct means of poly(m) size. The usual specifications of $\Delta[\det, m] \subseteq \mathbb{P}(V)$ by its equations or of ψ by its matrix

Hilbert: There exists a homogeneous linear map $\psi : V \to K^k$, for any $k > \dim(\Delta[\det, m])$, such that ψ does not vanish on any non-zero point in the affine cone $\hat{\Delta}[\det, m] \subseteq V$ of $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

This means the rational map $\hat{\psi} : \mathbb{P}(V) \dashrightarrow \mathbb{P}(K^k)$ is regular (well-defined) on $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

We call such a homogeneous, linear map $\psi: V \to K^k$ a normalizing map for $\Delta[\det, m]$.

The Problem NNL:

Given $\Delta[\det, m]$, with a succinct specification, construct a normalizing map $\psi: V \to K^k$, with k = poly(m), with a succinct specification.

Succinct means of poly(m) size. The usual specifications of $\Delta[\det, m] \subseteq \mathbb{P}(V)$ by its equations or of ψ by its matrix are not succinct,

Hilbert: There exists a homogeneous linear map $\psi : V \to K^k$, for any $k > \dim(\Delta[\det, m])$, such that ψ does not vanish on any non-zero point in the affine cone $\hat{\Delta}[\det, m] \subseteq V$ of $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

This means the rational map $\hat{\psi} : \mathbb{P}(V) \dashrightarrow \mathbb{P}(K^k)$ is regular (well-defined) on $\Delta[\det, m] \subseteq \mathbb{P}(V)$.

We call such a homogeneous, linear map $\psi: V \to K^k$ a normalizing map for $\Delta[\det, m]$.

The Problem NNL:

Given $\Delta[\det, m]$, with a succinct specification, construct a normalizing map $\psi: V \to K^k$, with k = poly(m), with a succinct specification.

Succinct means of poly(m) size. The usual specifications of $\Delta[\det, m] \subseteq \mathbb{P}(V)$ by its equations or of ψ by its matrix are not succinct, since $\dim(V) = 2^{poly(m)}$.

► The problem NNL for Δ[det, m] is equivalent to the problem of constructing a hitting set for VP_{ws}.

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三 のへぐ

- ► The problem NNL for Δ[det, m] is equivalent to the problem of constructing a hitting set for VP_{ws}.
- This, in conjunction with Gröbner basis theory, implies that NNL is in EXPSPACE [GCT5].

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

- ► The problem NNL for Δ[det, m] is equivalent to the problem of constructing a hitting set for VP_{ws}.
- This, in conjunction with Gröbner basis theory, implies that NNL is in EXPSPACE [GCT5].

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Recent development

- ► The problem NNL for Δ[det, m] is equivalent to the problem of constructing a hitting set for VP_{ws}.
- This, in conjunction with Gröbner basis theory, implies that NNL is in EXPSPACE [GCT5].

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三 のへぐ

Recent development [Forbes and Shpilka; Guo, Saxena, Sinhababu]:

- ► The problem NNL for Δ[det, m] is equivalent to the problem of constructing a hitting set for VP_{ws}.
- This, in conjunction with Gröbner basis theory, implies that NNL is in EXPSPACE [GCT5].

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

Recent development [Forbes and Shpilka; Guo, Saxena, Sinhababu]: NNL is in PSPACE.

- ► The problem NNL for Δ[det, m] is equivalent to the problem of constructing a hitting set for VP_{ws}.
- This, in conjunction with Gröbner basis theory, implies that NNL is in EXPSPACE [GCT5].
- Recent development [Forbes and Shpilka; Guo, Saxena, Sinhababu]: NNL is in PSPACE.
- \blacktriangleright This is how far we can go without knowing the relationship between $\overline{VP_{ws}}$ and $VP_{ws}.$

- ► The problem NNL for Δ[det, m] is equivalent to the problem of constructing a hitting set for VP_{ws}.
- This, in conjunction with Gröbner basis theory, implies that NNL is in EXPSPACE [GCT5].
- Recent development [Forbes and Shpilka; Guo, Saxena, Sinhababu]: NNL is in PSPACE.
- ▶ This is how far we can go without knowing the relationship between $\overline{VP_{ws}}$ and VP_{ws} .
- ► If VP_{ws} = VP_{ws}, then NNL is in PH, assuming generalized Riemann hypothesis.

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

- ► The problem NNL for Δ[det, m] is equivalent to the problem of constructing a hitting set for VP_{ws}.
- This, in conjunction with Gröbner basis theory, implies that NNL is in EXPSPACE [GCT5].
- Recent development [Forbes and Shpilka; Guo, Saxena, Sinhababu]: NNL is in PSPACE.
- ▶ This is how far we can go without knowing the relationship between $\overline{VP_{ws}}$ and $VP_{ws}.$
- ► If VP_{ws} = VP_{ws}, then NNL is in PH, assuming generalized Riemann hypothesis.

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

Where is NNL?

(ロ)、(型)、(E)、(E)、(E)、(O)()

Theorem (GCT5)

NNL is P (ignoring a quasi prefix) iff a variant of the hardness hypothesis of GCT holds.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Theorem (GCT5)

NNL is P (ignoring a quasi prefix) iff a variant of the hardness hypothesis of GCT holds.

► The variant:



Theorem (GCT5)

NNL is P (ignoring a quasi prefix) iff a variant of the hardness hypothesis of GCT holds.

The variant: Some exponential-time computable multilinear polynomial cannot be approximated infinitesimally closely by sub-exponential-size algebraic circuits.

Theorem (GCT5)

NNL is P (ignoring a quasi prefix) iff a variant of the hardness hypothesis of GCT holds.

► The variant: Some exponential-time computable multilinear polynomial cannot be approximated infinitesimally closely by sub-exponential-size algebraic circuits.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

► The proof:

Theorem (GCT5)

NNL is P (ignoring a quasi prefix) iff a variant of the hardness hypothesis of GCT holds.

The variant: Some exponential-time computable multilinear polynomial cannot be approximated infinitesimally closely by sub-exponential-size algebraic circuits.

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

► The proof: Classical algebraic geometry [Hilbert, ...] +

Theorem (GCT5)

NNL is P (ignoring a quasi prefix) iff a variant of the hardness hypothesis of GCT holds.

► The variant: Some exponential-time computable multilinear polynomial cannot be approximated infinitesimally closely by sub-exponential-size algebraic circuits.

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

► The proof: Classical algebraic geometry [Hilbert, ...] + algebraic complexity theory

Theorem (GCT5)

NNL is P (ignoring a quasi prefix) iff a variant of the hardness hypothesis of GCT holds.

- The variant: Some exponential-time computable multilinear polynomial cannot be approximated infinitesimally closely by sub-exponential-size algebraic circuits.
- The proof: Classical algebraic geometry [Hilbert, ...] + algebraic complexity theory [Kaltofen and Trager (the crux of the proof),

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

Theorem (GCT5)

NNL is P (ignoring a quasi prefix) iff a variant of the hardness hypothesis of GCT holds.

- ► The variant: Some exponential-time computable multilinear polynomial cannot be approximated infinitesimally closely by sub-exponential-size algebraic circuits.
- The proof: Classical algebraic geometry [Hilbert, ...] + algebraic complexity theory [Kaltofen and Trager (the crux of the proof), Heintz and Schnorr,

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

Theorem (GCT5)

NNL is P (ignoring a quasi prefix) iff a variant of the hardness hypothesis of GCT holds.

- The variant: Some exponential-time computable multilinear polynomial cannot be approximated infinitesimally closely by sub-exponential-size algebraic circuits.
- The proof: Classical algebraic geometry [Hilbert, ...] + algebraic complexity theory [Kaltofen and Trager (the crux of the proof), Heintz and Schnorr, Kabanets and Impagliazzo,

Theorem (GCT5)

NNL is P (ignoring a quasi prefix) iff a variant of the hardness hypothesis of GCT holds.

- The variant: Some exponential-time computable multilinear polynomial cannot be approximated infinitesimally closely by sub-exponential-size algebraic circuits.
- The proof: Classical algebraic geometry [Hilbert, ...] + algebraic complexity theory [Kaltofen and Trager (the crux of the proof), Heintz and Schnorr, Kabanets and Impagliazzo, Nisan and Wigderson].

Theorem (GCT5)

NNL is P (ignoring a quasi prefix) iff a variant of the hardness hypothesis of GCT holds.

- ► The variant: Some exponential-time computable multilinear polynomial cannot be approximated infinitesimally closely by sub-exponential-size algebraic circuits.
- The proof: Classical algebraic geometry [Hilbert, ...] + algebraic complexity theory [Kaltofen and Trager (the crux of the proof), Heintz and Schnorr, Kabanets and Impagliazzo, Nisan and Wigderson].
- ► Analogous result holds, in general, for any explicit variety in place of ∆[det, m].

Theorem (GCT5)

NNL is P (ignoring a quasi prefix) iff a variant of the hardness hypothesis of GCT holds.

- The variant: Some exponential-time computable multilinear polynomial cannot be approximated infinitesimally closely by sub-exponential-size algebraic circuits.
- The proof: Classical algebraic geometry [Hilbert, ...] + algebraic complexity theory [Kaltofen and Trager (the crux of the proof), Heintz and Schnorr, Kabanets and Impagliazzo, Nisan and Wigderson].
- ► Analogous result holds, in general, for any explicit variety in place of ∆[det, m].

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

By an explicit variety,

Theorem (GCT5)

- ► The variant: Some exponential-time computable multilinear polynomial cannot be approximated infinitesimally closely by sub-exponential-size algebraic circuits.
- The proof: Classical algebraic geometry [Hilbert, ...] + algebraic complexity theory [Kaltofen and Trager (the crux of the proof), Heintz and Schnorr, Kabanets and Impagliazzo, Nisan and Wigderson].
- ► Analogous result holds, in general, for any explicit variety in place of ∆[det, m].
- By an explicit variety, we mean any variety

Theorem (GCT5)

- ► The variant: Some exponential-time computable multilinear polynomial cannot be approximated infinitesimally closely by sub-exponential-size algebraic circuits.
- The proof: Classical algebraic geometry [Hilbert, ...] + algebraic complexity theory [Kaltofen and Trager (the crux of the proof), Heintz and Schnorr, Kabanets and Impagliazzo, Nisan and Wigderson].
- Analogous result holds, in general, for any explicit variety in place of Δ[det, m].
- By an explicit variety, we mean any variety whose coordinate ring has a set of generators

Theorem (GCT5)

- The variant: Some exponential-time computable multilinear polynomial cannot be approximated infinitesimally closely by sub-exponential-size algebraic circuits.
- The proof: Classical algebraic geometry [Hilbert, ...] + algebraic complexity theory [Kaltofen and Trager (the crux of the proof), Heintz and Schnorr, Kabanets and Impagliazzo, Nisan and Wigderson].
- Analogous result holds, in general, for any explicit variety in place of Δ[det, m].
- By an explicit variety, we mean any variety whose coordinate ring has a set of generators that can be encoded succinctly and uniformly

Theorem (GCT5)

- ► The variant: Some exponential-time computable multilinear polynomial cannot be approximated infinitesimally closely by sub-exponential-size algebraic circuits.
- The proof: Classical algebraic geometry [Hilbert, ...] + algebraic complexity theory [Kaltofen and Trager (the crux of the proof), Heintz and Schnorr, Kabanets and Impagliazzo, Nisan and Wigderson].
- Analogous result holds, in general, for any explicit variety in place of Δ[det, m].
- By an explicit variety, we mean any variety whose coordinate ring has a set of generators that can be encoded succinctly and uniformly by algebraic circuits

Theorem (GCT5)

- ► The variant: Some exponential-time computable multilinear polynomial cannot be approximated infinitesimally closely by sub-exponential-size algebraic circuits.
- The proof: Classical algebraic geometry [Hilbert, ...] + algebraic complexity theory [Kaltofen and Trager (the crux of the proof), Heintz and Schnorr, Kabanets and Impagliazzo, Nisan and Wigderson].
- Analogous result holds, in general, for any explicit variety in place of Δ[det, m].
- By an explicit variety, we mean any variety whose coordinate ring has a set of generators that can be encoded succinctly and uniformly by algebraic circuits of size polynomial in the dimension of the variety.

An Intermediate Problem:

An Intermediate Problem:

Show that NNL is in PH (assuming only GRH).

An Intermediate Problem:

Show that NNL is in PH (assuming only GRH).

• This is a challenge regardless of whether $\overline{VP_{ws}} = VP_{ws}$ or not.

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三 のへぐ

An Intermediate Problem:

Show that NNL is in PH (assuming only GRH).

• This is a challenge regardless of whether $\overline{VP_{ws}} = VP_{ws}$ or not.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

• If $\overline{VP_{ws}} = VP$, the challenge is to show this equality.

An Intermediate Problem:

Show that NNL is in PH (assuming only GRH).

• This is a challenge regardless of whether $\overline{VP_{ws}} = VP_{ws}$ or not.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

- If $\overline{VP_{ws}} = VP$, the challenge is to show this equality.
- If not, the task gets even harder.

An Intermediate Problem:

Show that NNL is in PH (assuming only GRH).

- This is a challenge regardless of whether $\overline{VP_{ws}} = VP_{ws}$ or not.
- If $\overline{VP_{ws}} = VP$, the challenge is to show this equality.
- If not, the task gets even harder.
- Hence bringing down NNL from PSPACE to PH would need overcoming the VP vs. VP problem [the battleground of GCT], one way or the other.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

An Intermediate Problem:

Show that NNL is in PH (assuming only GRH).

- This is a challenge regardless of whether $\overline{VP_{ws}} = VP_{ws}$ or not.
- If $\overline{VP_{ws}} = VP$, the challenge is to show this equality.
- If not, the task gets even harder.
- Hence bringing down NNL from PSPACE to PH would need overcoming the VP vs. VP problem [the battleground of GCT], one way or the other.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

▶ [GCT6]:

An Intermediate Problem:

Show that NNL is in PH (assuming only GRH).

- This is a challenge regardless of whether $\overline{VP_{ws}} = VP_{ws}$ or not.
- If $\overline{VP_{ws}} = VP$, the challenge is to show this equality.
- If not, the task gets even harder.
- Hence bringing down NNL from PSPACE to PH would need overcoming the VP vs. VP problem [the battleground of GCT], one way or the other.
- ▶ [GCT6]: The VP_{ws} vs. $\overline{VP_{ws}}$ problem is related to foundational issues in algebraic geometry and representation theory.

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

An Intermediate Problem:

Show that NNL is in PH (assuming only GRH).

- This is a challenge regardless of whether $\overline{VP_{ws}} = VP_{ws}$ or not.
- If $\overline{VP_{ws}} = VP$, the challenge is to show this equality.
- If not, the task gets even harder.
- Hence bringing down NNL from PSPACE to PH would need overcoming the VP vs. VP problem [the battleground of GCT], one way or the other.
- ▶ [GCT6]: The VP_{ws} vs. VP_{ws} problem is related to foundational issues in algebraic geometry and representation theory.
- Hence bringing NNL to PH may need a deep synthesis and extension of the existing techniques of algebraic geometry, representation theory, and complexity theory.

<ロト < 団 > < 巨 > < 巨 > 三 の < で</p>

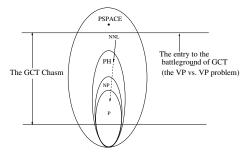
We call the existing PSPACE vs. P gap in the complexity of NNL the GCT chasm

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三三 - のへぐ

We call the existing PSPACE vs. P gap in the complexity of NNL the GCT chasm (revising the earlier definition in GCT5, thanks to [FS,GSS]).

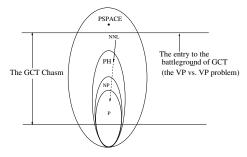
▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

We call the existing PSPACE vs. P gap in the complexity of NNL the GCT chasm (revising the earlier definition in GCT5, thanks to [FS,GSS]).



▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ ▲ 三 ● ● ●

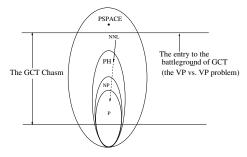
We call the existing PSPACE vs. P gap in the complexity of NNL the GCT chasm (revising the earlier definition in GCT5, thanks to [FS,GSS]).



This GCT chasm will have to be crossed by any approach to the VP vs. VNP which also separates VNP from VP in the process.

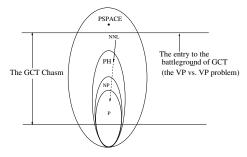
▲ロ ▶ ▲周 ▶ ▲ 国 ▶ ▲ 国 ▶ ● の Q @

We call the existing PSPACE vs. P gap in the complexity of NNL the GCT chasm (revising the earlier definition in GCT5, thanks to [FS,GSS]).



This GCT chasm will have to be crossed by any approach to the VP vs. VNP which also separates VNP from VP in the process. Recall: By definition, any such approach is a GCT approach in a broad sense.

We call the existing PSPACE vs. P gap in the complexity of NNL the GCT chasm (revising the earlier definition in GCT5, thanks to [FS,GSS]).



- This GCT chasm will have to be crossed by any approach to the VP vs. VNP which also separates VNP from VP in the process. Recall: By definition, any such approach is a GCT approach in a broad sense.
- ► GCT5,GCT6, and GCT7 provide a concrete GCT program to cross the GCT chasm.

▲□▶ ▲□▶ ▲ □▶ ▲ □▶ □ のへぐ

The first step of the GCT program to cross the GCT chasm (The Orbit Closure Intersection Problem) Let V be a finite-dimensional representation of a reductive group G (such as $SL_m(K)$).

▲ロ ▶ ▲周 ▶ ▲ 国 ▶ ▲ 国 ▶ ● の Q @

Let V be a finite-dimensional representation of a reductive group G (such as $SL_m(K)$).

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Problem (The orbit closure intersection problem) Given (V, G), and rational points $v, w \in V$, decide if the G-orbit-closures of v and w intersect.

Let V be a finite-dimensional representation of a reductive group G (such as $SL_m(K)$).

Problem (The orbit closure intersection problem) Given (V, G), and rational points $v, w \in V$, decide if the G-orbit-closures of v and w intersect.

This the first step of the GCT program [GCT5,GCT6,GCT7] to cross the GCT chasm.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Let V be a finite-dimensional representation of a reductive group G (such as $SL_m(K)$).

Problem (The orbit closure intersection problem) Given (V, G), and rational points $v, w \in V$, decide if the G-orbit-closures of v and w intersect.

This the first step of the GCT program [GCT5,GCT6,GCT7] to cross the GCT chasm.

A null-cone membership problem for V is a special case of this problem, which results when w is the origin.

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

Let V be a finite-dimensional representation of a reductive group G (such as $SL_m(K)$).

Problem (The orbit closure intersection problem) Given (V, G), and rational points $v, w \in V$, decide if the G-orbit-closures of v and w intersect.

This the first step of the GCT program [GCT5,GCT6,GCT7] to cross the GCT chasm.

A null-cone membership problem for V is a special case of this problem, which results when w is the origin.

Theorem (GCT5)

The orbit-closure intersection problem is in P, for any finite-dimensional representation V of a reductive group G, if

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Let V be a finite-dimensional representation of a reductive group G (such as $SL_m(K)$).

Problem (The orbit closure intersection problem) Given (V, G), and rational points $v, w \in V$, decide if the G-orbit-closures of v and w intersect.

This the first step of the GCT program [GCT5,GCT6,GCT7] to cross the GCT chasm.

A null-cone membership problem for V is a special case of this problem, which results when w is the origin.

Theorem (GCT5)

The orbit-closure intersection problem is in P, for any finite-dimensional representation V of a reductive group G, if (1) the categorical quotient $V//G = spec(K[V]^G)$ is explicit,

Let V be a finite-dimensional representation of a reductive group G (such as $SL_m(K)$).

Problem (The orbit closure intersection problem) Given (V, G), and rational points $v, w \in V$, decide if the G-orbit-closures of v and w intersect.

This the first step of the GCT program [GCT5,GCT6,GCT7] to cross the GCT chasm.

A null-cone membership problem for V is a special case of this problem, which results when w is the origin.

Theorem (GCT5)

The orbit-closure intersection problem is in P, for any finite-dimensional representation V of a reductive group G, if (1) the categorical quotient $V//G = \operatorname{spec}(K[V]^G)$ is explicit, and (2) the white-box PIT is in P.

The Orbit-Closure-Intersection Hypothesis

The Orbit-Closure-Intersection Hypothesis

Hypothesis (GCT5: M2012; M2017)

The orbit-closure intersection problem is in P, for any finite dimensional representation V of a reductive group G (possibly disconnected).

▲ロ ▶ ▲周 ▶ ▲ 国 ▶ ▲ 国 ▶ ● の Q @

The Orbit-Closure-Intersection Hypothesis

Hypothesis (GCT5: M2012; M2017)

The orbit-closure intersection problem is in P, for any finite dimensional representation V of a reductive group G (possibly disconnected).

Expected to be an inherent difficulty underneath white-box PIT.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Hypothesis (GCT5: M2012; M2017)

The orbit-closure intersection problem is in P, for any finite dimensional representation V of a reductive group G (possibly disconnected).

Expected to be an inherent difficulty underneath white-box PIT. The status of the hypothesis:

Hypothesis (GCT5: M2012; M2017)

The orbit-closure intersection problem is in P, for any finite dimensional representation V of a reductive group G (possibly disconnected).

Expected to be an inherent difficulty underneath white-box PIT. The status of the hypothesis:

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Holds if G is connected and dim(G) is constant

Hypothesis (GCT5: M2012; M2017)

The orbit-closure intersection problem is in P, for any finite dimensional representation V of a reductive group G (possibly disconnected).

Expected to be an inherent difficulty underneath white-box PIT. The status of the hypothesis:

▶ Holds if G is connected and dim(G) is constant [GCT5].

Hypothesis (GCT5: M2012; M2017)

The orbit-closure intersection problem is in P, for any finite dimensional representation V of a reductive group G (possibly disconnected).

Expected to be an inherent difficulty underneath white-box PIT. The status of the hypothesis:

▶ Holds if G is connected and dim(G) is constant [GCT5].

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

► Holds if V = M_m(K)ⁿ, with the adjoint action of G = SL_m(K)

Hypothesis (GCT5: M2012; M2017)

The orbit-closure intersection problem is in P, for any finite dimensional representation V of a reductive group G (possibly disconnected).

Expected to be an inherent difficulty underneath white-box PIT. The status of the hypothesis:

▶ Holds if G is connected and dim(G) is constant [GCT5].

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

► Holds if V = M_m(K)ⁿ, with the adjoint action of G = SL_m(K) [GCT5 + Forbes and Shpilka][2012].

Hypothesis (GCT5: M2012; M2017)

The orbit-closure intersection problem is in P, for any finite dimensional representation V of a reductive group G (possibly disconnected).

Expected to be an inherent difficulty underneath white-box PIT. The status of the hypothesis:

▶ Holds if G is connected and dim(G) is constant [GCT5].

- ► Holds if V = M_m(K)ⁿ, with the adjoint action of G = SL_m(K) [GCT5 + Forbes and Shpilka][2012].
- ► Holds if V = M_m(K)ⁿ, with the left-right action of G = SL_m(K) × SL_m(K)

Hypothesis (GCT5: M2012; M2017)

The orbit-closure intersection problem is in P, for any finite dimensional representation V of a reductive group G (possibly disconnected).

Expected to be an inherent difficulty underneath white-box PIT. The status of the hypothesis:

▶ Holds if *G* is connected and dim(*G*) is constant [GCT5].

- ► Holds if V = M_m(K)ⁿ, with the adjoint action of G = SL_m(K) [GCT5 + Forbes and Shpilka][2012].
- ► Holds if V = M_m(K)ⁿ, with the left-right action of G = SL_m(K) × SL_m(K) [GGOW; DM; IQS][2016].

Hypothesis (GCT5: M2012; M2017)

The orbit-closure intersection problem is in P, for any finite dimensional representation V of a reductive group G (possibly disconnected).

Expected to be an inherent difficulty underneath white-box PIT. The status of the hypothesis:

▶ Holds if *G* is connected and dim(*G*) is constant [GCT5].

- ► Holds if V = M_m(K)ⁿ, with the adjoint action of G = SL_m(K) [GCT5 + Forbes and Shpilka][2012].
- ► Holds if V = M_m(K)ⁿ, with the left-right action of G = SL_m(K) × SL_m(K) [GGOW; DM; IQS][2016]. A concrete application of GCT:

Hypothesis (GCT5: M2012; M2017)

The orbit-closure intersection problem is in P, for any finite dimensional representation V of a reductive group G (possibly disconnected).

- ▶ Holds if G is connected and dim(G) is constant [GCT5].
- ► Holds if V = M_m(K)ⁿ, with the adjoint action of G = SL_m(K) [GCT5 + Forbes and Shpilka][2012].
- ▶ Holds if V = M_m(K)ⁿ, with the left-right action of G = SL_m(K) × SL_m(K) [GGOW; DM; IQS][2016].
 A concrete application of GCT: This special case of the GCT hypothesis above implies a polynomial time algorithm for non-commutative rational identity testing.

Hypothesis (GCT5: M2012; M2017)

The orbit-closure intersection problem is in P, for any finite dimensional representation V of a reductive group G (possibly disconnected).

- ▶ Holds if G is connected and dim(G) is constant [GCT5].
- ► Holds if V = M_m(K)ⁿ, with the adjoint action of G = SL_m(K) [GCT5 + Forbes and Shpilka][2012].
- ▶ Holds if V = M_m(K)ⁿ, with the left-right action of G = SL_m(K) × SL_m(K) [GGOW; DM; IQS][2016].
 A concrete application of GCT: This special case of the GCT hypothesis above implies a polynomial time algorithm for non-commutative rational identity testing.
- Holds if $V = K^{\binom{n}{2}}$ with the natural action of S_n

Hypothesis (GCT5: M2012; M2017)

The orbit-closure intersection problem is in P, for any finite dimensional representation V of a reductive group G (possibly disconnected).

- ▶ Holds if G is connected and dim(G) is constant [GCT5].
- ► Holds if V = M_m(K)ⁿ, with the adjoint action of G = SL_m(K) [GCT5 + Forbes and Shpilka][2012].
- Holds if V = M_m(K)ⁿ, with the left-right action of G = SL_m(K) × SL_m(K) [GGOW; DM; IQS][2016].
 A concrete application of GCT: This special case of the GCT hypothesis above implies a polynomial time algorithm for non-commutative rational identity testing.
- ► Holds if $V = K^{\binom{n}{2}}$ with the natural action of S_n (Weighted Graph Isomorphism):

Hypothesis (GCT5: M2012; M2017)

The orbit-closure intersection problem is in P, for any finite dimensional representation V of a reductive group G (possibly disconnected).

- ▶ Holds if G is connected and dim(G) is constant [GCT5].
- ► Holds if V = M_m(K)ⁿ, with the adjoint action of G = SL_m(K) [GCT5 + Forbes and Shpilka][2012].
- ▶ Holds if V = M_m(K)ⁿ, with the left-right action of G = SL_m(K) × SL_m(K) [GGOW; DM; IQS][2016].
 A concrete application of GCT: This special case of the GCT hypothesis above implies a polynomial time algorithm for non-commutative rational identity testing.
- ► Holds if $V = K^{\binom{n}{2}}$ with the natural action of S_n (Weighted Graph Isomorphism): [Babai][2017].

▲□▶ ▲圖▶ ▲臣▶ ▲臣▶ ―臣 …の�?

The Orbit Equality Problem:



The Orbit Equality Problem:

Show that the problem of deciding, given any representation V of a finite group G and two rational points $v, w \in V$, whether v and w lie in the same G-orbit belongs to P.

The Orbit Equality Problem:

Show that the problem of deciding, given any representation V of a finite group G and two rational points $v, w \in V$, whether v and w lie in the same G-orbit belongs to P.

 This is a special case of the orbit-closure-intersection problem for finite groups.

The Orbit Equality Problem:

Show that the problem of deciding, given any representation V of a finite group G and two rational points $v, w \in V$, whether v and w lie in the same G-orbit belongs to P.

 This is a special case of the orbit-closure-intersection problem for finite groups.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

The main obstacles:

The Orbit Equality Problem:

Show that the problem of deciding, given any representation V of a finite group G and two rational points $v, w \in V$, whether v and w lie in the same G-orbit belongs to P.

 This is a special case of the orbit-closure-intersection problem for finite groups.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

► The main obstacles: (1)

The Orbit Equality Problem:

Show that the problem of deciding, given any representation V of a finite group G and two rational points $v, w \in V$, whether v and w lie in the same G-orbit belongs to P.

- This is a special case of the orbit-closure-intersection problem for finite groups.
- The main obstacles: (1) Classification of all finite groups (not just finite simple groups) is not yet known.

The Orbit Equality Problem:

Show that the problem of deciding, given any representation V of a finite group G and two rational points $v, w \in V$, whether v and w lie in the same G-orbit belongs to P.

- This is a special case of the orbit-closure-intersection problem for finite groups.
- The main obstacles: (1) Classification of all finite groups (not just finite simple groups) is not yet known. In fact, this is the most outstanding open problem of finite group theory.

The Orbit Equality Problem:

Show that the problem of deciding, given any representation V of a finite group G and two rational points $v, w \in V$, whether v and w lie in the same G-orbit belongs to P.

- This is a special case of the orbit-closure-intersection problem for finite groups.
- The main obstacles: (1) Classification of all finite groups (not just finite simple groups) is not yet known. In fact, this is the most outstanding open problem of finite group theory. (2)

The Orbit Equality Problem:

Show that the problem of deciding, given any representation V of a finite group G and two rational points $v, w \in V$, whether v and w lie in the same G-orbit belongs to P.

- This is a special case of the orbit-closure-intersection problem for finite groups.
- The main obstacles: (1) Classification of all finite groups (not just finite simple groups) is not yet known. In fact, this is the most outstanding open problem of finite group theory.
 (2) the complexity of constructing irreducible representations of finite simple groups of Lie type (using the *l*-adic cohomology as per Grothendick) is very high.

The Orbit Equality Problem:

Show that the problem of deciding, given any representation V of a finite group G and two rational points $v, w \in V$, whether v and w lie in the same G-orbit belongs to P.

- This is a special case of the orbit-closure-intersection problem for finite groups.
- The main obstacles: (1) Classification of all finite groups (not just finite simple groups) is not yet known. In fact, this is the most outstanding open problem of finite group theory.
 (2) the complexity of constructing irreducible representations of finite simple groups of Lie type (using the *l*-adic cohomology as per Grothendick) is very high.
- This is why the techniques such as operator scaling and optimization are unlikely to work for white-box PIT.

▲ロト ▲御 ▶ ▲ 臣 ▶ ▲ 臣 ▶ ● 臣 ● のへで

Hardest: Prove that VNP ⊈ VP (the hardness hypothesis of GCT),

► Hardest: Prove that VNP ⊈ VP (the hardness hypothesis of GCT), using obstructions [GCT2:MS2008].

► Hardest: Prove that VNP ⊈ VP (the hardness hypothesis of GCT), using obstructions [GCT2:MS2008]. (Occurence obstructions do not exist [Bürgisser, Ikenmeyer, Panova]).

► Hardest: Prove that VNP ⊈ VP (the hardness hypothesis of GCT), using obstructions [GCT2:MS2008]. (Occurrence obstructions do not exist [Bürgisser, Ikenmeyer, Panova]). GCT7: a systematic program to prove existence of multiplicity obstructions.

► Hardest: Prove that VNP ⊈ VP (the hardness hypothesis of GCT), using obstructions [GCT2:MS2008]. (Occurrence obstructions do not exist [Bürgisser, Ikenmeyer, Panova]). GCT7: a systematic program to prove existence of multiplicity obstructions.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

► Easier:

► Hardest: Prove that VNP ⊈ VP (the hardness hypothesis of GCT), using obstructions [GCT2:MS2008]. (Occurence obstructions do not exist [Bürgisser, Ikenmeyer, Panova]). GCT7: a systematic program to prove existence of multiplicity obstructions.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Easier: Show that the problem NNL for general explicit varieties is in P.

- ► Hardest: Prove that VNP ⊈ VP (the hardness hypothesis of GCT), using obstructions [GCT2:MS2008]. (Occurence obstructions do not exist [Bürgisser, Ikenmeyer, Panova]). GCT7: a systematic program to prove existence of multiplicity obstructions.
- Easier: Show that the problem NNL for general explicit varieties is in P. GCT5,6,7: a systematic program for this.

- ► Hardest: Prove that VNP ⊈ VP (the hardness hypothesis of GCT), using obstructions [GCT2:MS2008]. (Occurence obstructions do not exist [Bürgisser, Ikenmeyer, Panova]). GCT7: a systematic program to prove existence of multiplicity obstructions.
- Easier: Show that the problem NNL for general explicit varieties is in P. GCT5,6,7: a systematic program for this.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Much easier [GCT5]

- ► Hardest: Prove that VNP ⊈ VP (the hardness hypothesis of GCT), using obstructions [GCT2:MS2008]. (Occurence obstructions do not exist [Bürgisser, Ikenmeyer, Panova]). GCT7: a systematic program to prove existence of multiplicity obstructions.
- Easier: Show that the problem NNL for general explicit varieties is in P. GCT5,6,7: a systematic program for this.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Much easier [GCT5] [Not covered in this talk]

- ► Hardest: Prove that VNP ⊈ VP (the hardness hypothesis of GCT), using obstructions [GCT2:MS2008]. (Occurence obstructions do not exist [Bürgisser, Ikenmeyer, Panova]). GCT7: a systematic program to prove existence of multiplicity obstructions.
- Easier: Show that the problem NNL for general explicit varieties is in P. GCT5,6,7: a systematic program for this.
- Much easier [GCT5] [Not covered in this talk] [An inherent difficulty underneath black-box PIT]:

- ► Hardest: Prove that VNP ⊈ VP (the hardness hypothesis of GCT), using obstructions [GCT2:MS2008]. (Occurence obstructions do not exist [Bürgisser, Ikenmeyer, Panova]). GCT7: a systematic program to prove existence of multiplicity obstructions.
- Easier: Show that the problem NNL for general explicit varieties is in P. GCT5,6,7: a systematic program for this.
- Much easier [GCT5] [Not covered in this talk] [An inherent difficulty underneath black-box PIT]: Show that the problem NNL for the categorical quotient V//G is in P, for any finite dimensional representation V of any reductive group G.

- ► Hardest: Prove that VNP ⊈ VP (the hardness hypothesis of GCT), using obstructions [GCT2:MS2008]. (Occurence obstructions do not exist [Bürgisser, Ikenmeyer, Panova]). GCT7: a systematic program to prove existence of multiplicity obstructions.
- Easier: Show that the problem NNL for general explicit varieties is in P. GCT5,6,7: a systematic program for this.
- Much easier [GCT5] [Not covered in this talk] [An inherent difficulty underneath black-box PIT]: Show that the problem NNL for the categorical quotient V//G is in P, for any finite dimensional representation V of any reductive group G.

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

Easiest [GCT5]

- ► Hardest: Prove that VNP ⊈ VP (the hardness hypothesis of GCT), using obstructions [GCT2:MS2008]. (Occurence obstructions do not exist [Bürgisser, Ikenmeyer, Panova]). GCT7: a systematic program to prove existence of multiplicity obstructions.
- Easier: Show that the problem NNL for general explicit varieties is in P. GCT5,6,7: a systematic program for this.
- Much easier [GCT5] [Not covered in this talk] [An inherent difficulty underneath black-box PIT]: Show that the problem NNL for the categorical quotient V//G is in P, for any finite dimensional representation V of any reductive group G.

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

Easiest [GCT5] [Covered in this talk]

- ► Hardest: Prove that VNP ⊈ VP (the hardness hypothesis of GCT), using obstructions [GCT2:MS2008]. (Occurence obstructions do not exist [Bürgisser, Ikenmeyer, Panova]). GCT7: a systematic program to prove existence of multiplicity obstructions.
- Easier: Show that the problem NNL for general explicit varieties is in P. GCT5,6,7: a systematic program for this.
- Much easier [GCT5] [Not covered in this talk] [An inherent difficulty underneath black-box PIT]: Show that the problem NNL for the categorical quotient V//G is in P, for any finite dimensional representation V of any reductive group G.
- Easiest [GCT5] [Covered in this talk] [An inherent difficulty underneath white-box PIT]:

- ► Hardest: Prove that VNP ⊈ VP (the hardness hypothesis of GCT), using obstructions [GCT2:MS2008]. (Occurence obstructions do not exist [Bürgisser, Ikenmeyer, Panova]). GCT7: a systematic program to prove existence of multiplicity obstructions.
- Easier: Show that the problem NNL for general explicit varieties is in P. GCT5,6,7: a systematic program for this.
- Much easier [GCT5] [Not covered in this talk] [An inherent difficulty underneath black-box PIT]: Show that the problem NNL for the categorical quotient V//G is in P, for any finite dimensional representation V of any reductive group G.
- Easiest [GCT5] [Covered in this talk] [An inherent difficulty underneath white-box PIT]: Show that the orbit-closure intersection problem is in P, for any finite dimensional representation V of any reductive group G (possibly disconnected).

Thank you.

・ロト・(四)・(日)・(日)・(日)・(日)